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Title

Modelling Seasonal Ratcheting and Progressive Failure in Clay Slopes: A Validation

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Abstract

Seasonal wetting and drying stress cycles can lead to long-term deterioration of high-plasticity clay slopes through the accumulation of outward and downward deformations leading to plastic strain accumulation, progressive failure and first-time failures due to seasonal ratcheting. Using recent advances in hydro-mechanical coupling for the numerical modelling of unsaturated soil behaviour and development of nonlocal strain-softening regulatory models to reduce mesh dependency of localisation problems, the mechanism of seasonal ratcheting has been replicated within a numerical model. Hydrogeological and mechanical behaviours of the numerical model have been compared and validated against physical measurements of seasonal ratcheting from centrifuge experimentation. Following validation, the mechanism of seasonal ratcheting was explored in a parametric study investigating the role of stiffness and long-term behaviour of repeated stress cycling extrapolated to failure. Material stiffness has a controlling influence on the rate of strength deterioration for these slopes; the stiffer the material, the smaller the seasonal movement and therefore the more gradual the accumulation of irrecoverable strains and material softening. The validation presented provides confidence that the numerical modelling approach developed can capture near-surface behaviour of high-plasticity overconsolidated clay slopes subject to cyclic wetting and drying. The approach provides a tool to further investigate the effects of weather driven stress cycles and the implication of climate change on high-plasticity clay infrastructure slopes.

Key Words

Slope stability; Seasonal ratcheting; Progressive failure; Numerical modelling;

Nonlocal strain-softening

List of Notation

σ'_B = Bishop's generalised effective stress (kPa)
 σ = total stress (kPa)
 u_a = pore air pressure (kPa)
 u_w = pore water pressure (kPa)
 χ = is a parameter considering the area over which matric suction acts
 s = matric suction (kPa)
 S_r = degree of saturation
 S_w = saturation
 S_r^w = residual saturation
 α = van Genuchten fitting parameter (kPa⁻¹)
 m = van Genuchten fitting parameter
 K_{sat} = saturated hydraulic conductivity
 K_r^w = relative hydraulic conductivity of water phase (m/s)
 K_r^a = relative hydraulic conductivity of air phase (m/s)
 ε_p^* = nonlocal plastic strain
 V_w = weighted volume
 ω' = is the weighting function
 ε_d = local plastic strain
 x_n = global coordinate
 x_n' = local coordinate
 l = internal length
 r = distance from the stress point to adjacent stress points
 K = bulk modulus (kPa)
 G = shear modulus (kPa)
 v = specific volume
 κ = gradient of the swelling line
 λ = gradient of normal consolidation line
 σ_{ref} = reference pressure (kPa)
 v_κ = specific volume at reference pressure following the swelling line
 v_λ = original specific volume at reference pressure
 ν' = Poisson's ratio
 e = void ratio
 $k_{sat,vertical}$ = vertical saturated hydraulic conductivity (m/s)
 $k_{sat,horizontal}$ = horizontal saturated hydraulic conductivity (m/s)
 OCR = overconsolidation ratio
 K_0 = coefficient of earth pressure at rest
 K_{nc} = coefficient of earth pressure at rest normally consolidated
 c' = cohesion (kPa)
 φ' = internal angle of friction (°)

1 **Introduction**

2 Long-term deterioration of high-plasticity clay slopes due to seasonal wetting and
3 drying induced pore water pressure fluctuations driving effective stress cycles, has
4 been attributed as the cause of shallow (i.e. less than 2.5m deep) first-time failures in
5 clay infrastructure slopes (Take & Bolton, 2011; Briggs, et al., 2017). Within this
6 study, pore water pressure fluctuations and resulting effective stress cycles due to
7 environmental boundary conditions are referred to as environmental stress cycles.
8 These environmental cycles of wetting and drying cause cyclic volume change that
9 can lead to the accumulation of irrecoverable plastic strains resulting in mobilisation
10 of post-peak strength and progressive failure (Take, 2003; Take & Bolton, 2004;
11 Take & Bolton, 2011). This mechanism of shallow first-time failure due to repeated
12 environmental stress cycles and progressive failure, known as seasonal ratcheting
13 (Take & Bolton, 2011), has been observed in high-plasticity clay rail infrastructure
14 slopes (Briggs, et al., 2017), and was shown conclusively through centrifuge
15 experimentation (Take & Bolton, 2011). The mechanism of seasonal ratcheting in
16 high-plasticity clay slopes is the focus of the study reported in this paper. While
17 seasonal movement due to environmental wetting and drying stress cycles has been
18 shown to occur in intermediate-plasticity clay slopes (Hudacsek, et al., 2009),
19 progressive failure was not observed within this centrifuge experimentation. The
20 reasons for this were highlighted as a difference in stress history (i.e. Take and
21 Bolton (2011) considered overconsolidated high-plasticity clay and Hudacsek, et al.,
22 (2009) intermediate-plasticity compacted clay fill) as well as the difference in
23 mechanical properties of the high and intermediate-plasticity materials investigated
24 (Hudacsek, et al., 2009).

25 Environmental stress cycles in high-plasticity clay slopes, due to wetting and drying,
26 and progressive failure have been investigated through numerical analyses providing
27 useful parametric studies to develop understanding of the mechanism (Kovacevic, et
28 al., 2001; Nyambayo, et al., 2004; O'Brien, et al., 2004; Tsiampousi, et al., 2017). It
29 has been shown that hydraulic conductivity (Nyambayo, et al., 2004) and vegetation
30 (O'Brien, et al., 2004; Tsiampousi, et al., 2017) significantly influence the rate of
31 failure of high-plasticity clay slopes driven by cycles of effective stresses that result
32 from cyclic environmental boundary conditions. Within these studies, the failure
33 surfaces obtained are deep-seated (i.e. greater than 2.5m deep) and behaviour
34 modelled as fully saturated. While the studies are valuable, they do not adequately
35 capture seasonal ratcheting and shallow first-time failures. In particular, the nature
36 and magnitude of shrink-swell cycles leading to outward and downward movements,
37 plastic strain accumulation leading to progressive failure, have not been captured in
38 numerical models presented by Kovacevic, et al., (2001), Nyambayo, et al., (2004),
39 O'Brien, et al., (2004) and Tsiampousi, et al., (2017). Therefore, additional work is
40 required to model the mechanism of seasonal ratcheting to allow further
41 development in understanding of the mechanism and to investigate the implications
42 of changing seasonal weather patterns in the future due to climate change.

43 Recently, sophisticated soil-vegetation-atmosphere boundary conditions that drive
44 representative hydrogeological behaviour of slopes within numerical models have
45 been developed to investigate time dependent slope behaviour (Rouainia, et al.,
46 2009; Conte, et al., 2016; Elia, et al., 2017). In the work by Conte, et al., (2016) and
47 cases considered by Elia, et al., (2017), coupled hydro-mechanical numerical
48 analyses validated against monitored data have shown good agreement for
49 displacements driven by changing pore water pressures resulting from

50 environmental boundary cycles for reactive landslides (i.e. movements along defined
51 existing shear surfaces, where material is already at or near residual strength,
52 therefore strain-softening is not considered within this previous work). Whilst the
53 modelling approaches show that environmental stress cycles due to weather
54 sequences can be replicated numerically, the Conte, et al., (2016) model and models
55 discussed by Elia, et al., (2017) did not consider the accumulation of plastic strains
56 and progressive failure due to these stress cycles (i.e. the work is not explicitly
57 considering seasonal ratcheting). Therefore, additional work is required for more
58 complex strain-softening problems such as seasonal ratcheting in high-plasticity clay
59 slopes.

60 As seasonal ratcheting drives progressive failure, strain-softening behaviour must be
61 included within the modelling. It is known that localisation problems within discretised
62 numerical analyses suffer mesh dependency (Galavi & Schweiger, 2010;
63 Summersgill, et al., 2017). Recent advances in nonlocal strain-softening regulatory
64 models have been shown to significantly reduce mesh dependency of such problems
65 (Summersgill, et al., 2017).

66 This paper presents a coupled hydro-mechanical unsaturated (i.e. a soil containing
67 both a liquid and a gas phase) numerical model capable of modelling seasonal
68 ratcheting movements due to known environmental stress cycles. This work does not
69 consider or develop current knowledge of soil-vegetation-atmosphere boundary
70 conditions but focusses on the consequences of cyclic stress changes due to pore
71 water pressure fluctuations within high-plasticity overconsolidated clay slopes
72 causing seasonal ratcheting leading to shallow first-time progressive failure. It
73 purposefully does not consider deep-seated mechanisms that have been the focus
74 of other studies (e.g. Potts, et al., 1997). The focus of this study is justified because

75 shallow first-time failure in high-plasticity clay slopes is particularly important in the
76 assessment of long-term behaviour of infrastructure earthwork assets (Briggs, et al.,
77 2017).

78 This work is differentiated from previous studies considering seasonal environmental
79 stress cycles and progressive failure by the level of validation conducted through
80 direct comparison of numerical analyses against physical modelling data presented
81 by Take and Bolton (2011). The numerical model developed includes unsaturated
82 behaviour and a nonlocal strain-softening regulatory model has been implemented to
83 reduce mesh dependency for the modelling of progressive failure.

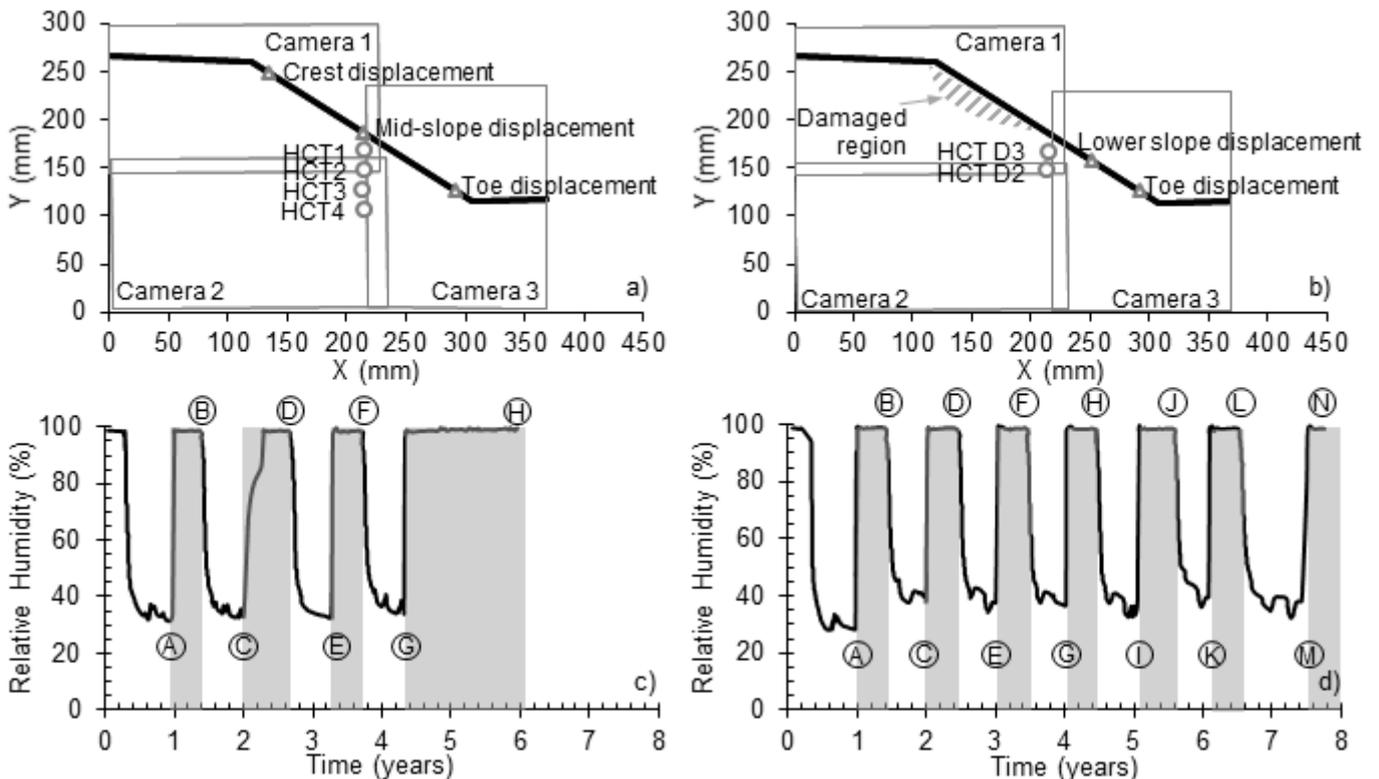
84 **Physical Modelling**

85 Physical models provide controlled conditions limiting unknowns and therefore they
86 can be used to assess validity of assumptions required for the development of a
87 numerical model that can replicate measured behaviour. In addition, materials used
88 in physical models have known properties, the stress history is controlled and
89 boundary conditions are well established. The physical modelling conducted by Take
90 (2003) and presented by Take and Bolton (2011) provides pore water pressure (i.e.
91 hydrogeological) and displacement (i.e. mechanical) data for Kaolin slopes subject to
92 repeated simplified environmental stress cycles due to wetting and drying.

93 This paper focuses on two tests considering Speswhite Kaolin with a slope
94 inclination of 36 degrees, models WAT7a and WAT8a (Take & Bolton, 2011). The
95 slopes were 140mm high at 1/60th scale with tests run under centripetal acceleration
96 of 60g, corresponding to a slope height of 8.4m at full scale. The only differences
97 between the two models are the pressure under which the initial Kaolin blocks were

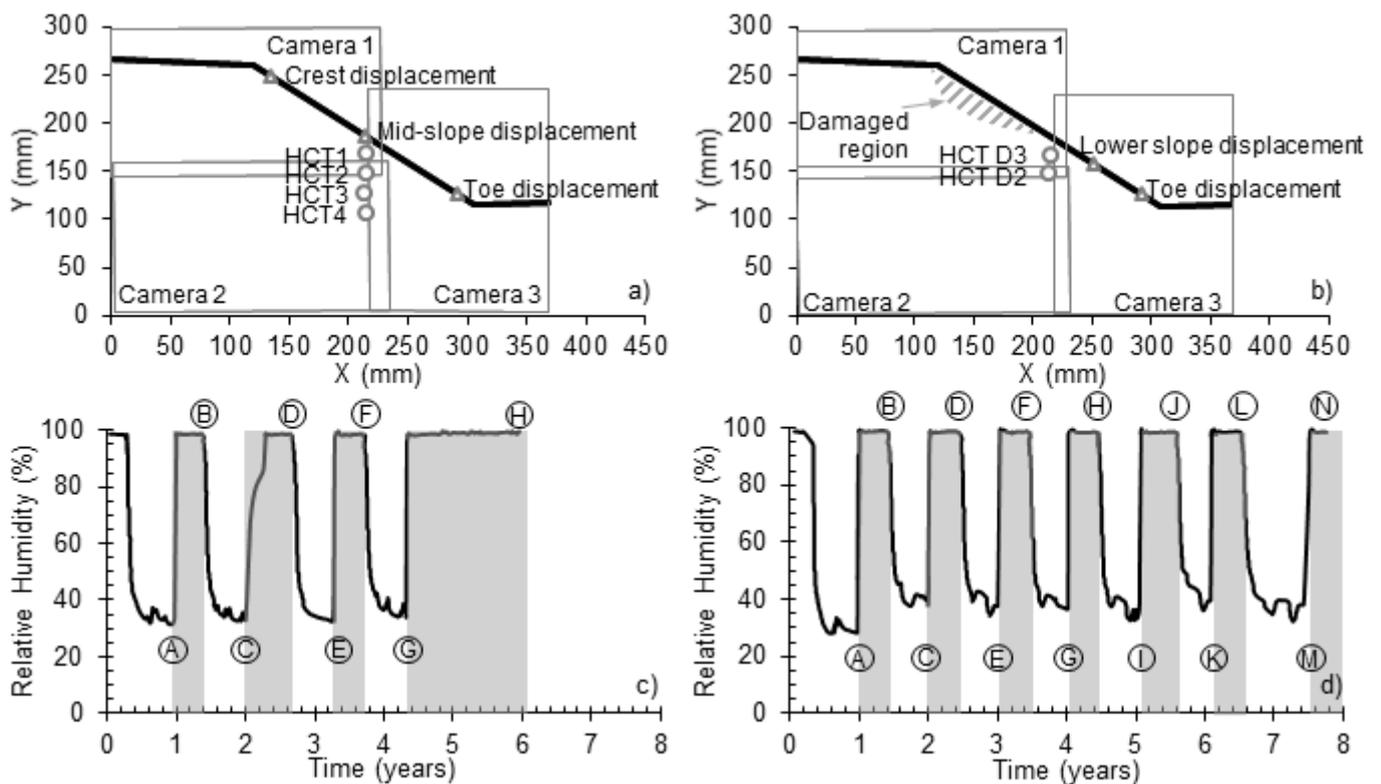
98 consolidated and the magnitude and timing of wetting and drying boundary
 99 conditions applied.

100 The slope models were formed through the following steps as described by Take
 101 (2003) and Take and Bolton (2011). Speswhite Kaolin was mixed to 120% moisture
 102 content and subjected to one-dimensional consolidation within a consolidometer to
 103 form an initial block. Loading was used to increase the vertical stresses within the
 104 consolidometer as follows for WAT7a: 2, 10, 15, 30, 60, 120, 250 and 500kPa, and
 105 for WAT8a the same stress path was followed but a maximum vertical stress of
 106 200kPa applied. After application of each load increment, primary consolidation was
 107 allowed prior to the next load increase. Unloading was done in 75 kPa increments
 108 and swelling was allowed to occur. Following consolidation and subsequent swelling,
 109 the slope models were formed (Take & Bolton, 2011).



110 Figure 1 shows the geometry and location of monitoring equipment for the two
 111 physical model experiments, camera locations for displacement measurements
 112 through particle image velocimetry (PIV) (White, et al., 2003) and high-capacity
 113 tensiometer (HCT) (Take & Bolton, 2003) locations for pore water pressure
 114 measurements.

115 Boundary conditions were controlled using a climate chamber developed by Take
 116 and Bolton (2002). Simulated rainfall, using suspended misting nozzles, and a
 117 relative humidity of 100% were used to replicate wet winter conditions and relative
 118 humidity of approximately 40% without simulated rainfall used to replicate dry
 119 summer conditions. The boundary conditions applied are shown in



120 Figure 1; the grey regions indicate the use of the mist nozzles. For WAT7a, four
 121 seasonal cycles were applied and then the model was subjected to prolonged
 122 wetting (G to H). WAT8a was subjected to seven seasonal cycles. In both instances

123 strain-softening was observed and small localised failures at the toe of the slopes
124 occurred.

125 Take and Bolton (2011) concluded that seasonal variation in soil water content drive
126 stress changes within slopes that can, in some cases, mobilise post-peak strength at
127 which point irrecoverable strain accumulation and softening occurs. Results from the
128 physical modelling are presented alongside numerical analyses results throughout
129 this paper.

130 **Numerical Modelling Framework**

131 Shallow first-time failure of a clay slope due to seasonal ratcheting is driven by pore
132 water pressure variation due to cycles of wetting and drying, which includes
133 unsaturated soil behaviour. Near surface desaturation as a result of environmental
134 boundary conditions has been observed in high-plasticity clay slopes (Smethurst, et
135 al., 2006; Smethurst, et al., 2012), and is a significant factor in slope behaviour. Soil
136 water content variation changes pore water pressures, affecting relative hydraulic
137 conductivity and internal stress conditions; which in turn influence the strength,
138 stiffness and volume of a soil. These behaviours are inter-related and must be
139 accounted for in any numerical modelling approach.

140 Unsaturated soil behaviour can be modelled by coupling hydrogeological (i.e. the
141 movement of water through a soil mass) and mechanical behaviour. Within this
142 paper, mechanical behaviour is described using Bishop's generalised effective stress
143 and coupled with hydrogeological behaviour through the addition of hydrogeological
144 descriptors, matric suction and degree of saturation allowing stresses to be
145 determined and flow of air and water phases through the soil to be established.

146 Bishop's generalised effective stress is a single stress state variable that combines
147 multiple stresses (σ, u_w, u_a) from a multi-phase medium (soil, water and air) into one
148 variable that can be used to describe physical behaviour. This is given in Equation
149 (1).

$$150 \quad \sigma'_B = (\sigma - u_a) + \chi(u_a - u_w)$$

151 Equation (1)

152 Where, σ'_B = Bishop's generalised effective stress; σ = total stress; u_a = pore air
153 pressure; u_w = pore water pressure; $(\sigma - u_a)$ = net stress; $s = (u_a - u_w)$ = matric
154 suction; χ = is a parameter considering the area over which matric suction acts (1
155 being fully saturated and 0 being dry).

156 Within this work, it is assumed that χ is equivalent to the degree of saturation. This
157 has been shown to be an approximation and the parameter is different for all soils
158 depending on their microstructure (Jardine, et al., 2004). However, the single
159 effective stress variable allows easy transition between saturated and unsaturated
160 behaviour and can account for shear strength variation effectively, which is the
161 critical variable for slope stability analysis. Whilst this framework can capture shear
162 strength variation well, it should be noted that it is currently not possible for all
163 unsaturated mechanical behaviours, in particular wetting collapse, to be accounted
164 for using a single stress state variable (Jardine, et al., 2004; Nuth & Laloui, 2008).

165 The hydrogeological component of the framework links soil water content and matric
166 suction through a soil water retention curve. Within this work, a van Genuchten
167 (1980) style soil water retention curve has been used, see Equation (2). The
168 resulting suction and degree of saturation are then used along with the saturated

169 hydraulic conductivity to establish the relative hydraulic conductivity of the water and
 170 air phases. Equations for relative hydraulic conductivity are shown in Equation (3) for
 171 the water phase and Equation (4) for the air phase (van Genuchten, 1980). The flow
 172 of the two phases within the soil are calculated using Darcy's law, taking into account
 173 the viscosity of the different phases. Within the framework, it is assumed that the
 174 water and air phases are idealised and homogeneous (i.e. air is not dissolved into
 175 the water phase resulting in pure water and air components).

$$176 \quad s = \alpha [S_r^{-1/m} - 1]^{1-m}$$

177 Equation (2)

178 Where, s = matric suction; $S_r = \frac{S_w - S_r^w}{1 - S_r^w}$ = degree of saturation; S_w = saturation; S_r^w =
 179 residual saturation; α = van Genuchten fitting parameter (kPa^{-1}); and m = van
 180 Genuchten fitting parameter.

$$181 \quad K_r^w = K_{sat} \cdot S_r^{0.5} [1 - (1 - S_r^{1/m})^m]^2$$

182 Equation (3)

$$183 \quad K_r^a = K_{sat} \cdot (1 - S_r)^{0.5} [1 - S_r^{1/m}]^{2m}$$

184 Equation (4)

185 Where, K_r^w = relative hydraulic conductivity of water phase (m/s); K_r^a = relative
 186 hydraulic conductivity of air phase (m/s); and K_{sat} = saturated hydraulic conductivity
 187 (m/s).

188 Using degree of saturation within Bishop's generalised effective stress and within the
 189 soil water retention curve, hydrogeological and mechanical behaviours have been

190 coupled within this framework. This framework has been adopted within many
191 commercially available numerical modelling software packages and the advantages
192 of this framework have been discussed by Nuth and Laloui (2008).

193 A Mohr-Coulomb strain-softening constitutive model with material softening and non-
194 associated shear flow rule has been used in this study. This constitutive model has
195 been adopted to allow post-peak strain softening to be modelled effectively (Potts, et
196 al., 1990; Potts, et al., 1997), a critical behaviour of seasonal ratcheting leading to
197 first-time failure due to repeated environmental stress cycles (Rouainia, et al., 2009;
198 Take & Bolton, 2011). Considering the stresses obtained using Equation (1), and
199 yield surface defined by the Mohr-Coulomb constitutive model, elastic and plastic
200 strains are determined. To reduce mesh dependency due to localisation, a nonlocal
201 strain-softening model has been implemented. The modelling undertaken within this
202 work has been carried out in the explicit finite difference modelling code, FLAC –
203 Two-Phase Flow option (FLAC-TP) (Itasca, 2011).

204 ***Implementation of Nonlocal Strain-Softening Model***

205 A partial nonlocal strain-softening model has been implemented, with local plastic
206 strains averaged relative to each stress point within the mesh using a weighting
207 function to obtain the nonlocal plastic strain value (Galavi & Schweiger, 2010;
208 Summersgill, et al., 2017). Nonlocal plastic strains are calculated at each time-step
209 and dictate material softening. The implementation procedure adopted is similar to
210 that described by Galavi and Schweiger, (2010); however, a Mohr-Coulomb strain-
211 softening constitutive model with material softening, to allow progressive failure to be
212 modelled, has been employed. The nonlocal plastic strain (ϵ_p^*) at stress point (x_n) is
213 calculated using Equation (5).

214
$$\varepsilon_p^*(x_n) = \frac{1}{V_w} \iiint \omega'(x_n') \varepsilon_d(x_n + x_n') dx_1' dx_2' dx_3'$$

215 Equation (5)

216 Where, $V_w = \iiint \omega(x_n') dx_1' dx_2' dx_3' =$ weighted volume; $\omega'(x_n')$ = is the weighting
217 function; $\varepsilon_d(x_n + x_n')$ = local plastic strain at different calculation points; x_n = global
218 coordinate; x_n' = local coordinate.

219 The weighting function adopted in the current work takes the form of the distribution
220 proposed by Galavi and Schweiger (2010) and is given in Equation (6); the centre of
221 the weighting function is located at the stress point at which the nonlocal plastic
222 strain is being calculated. Summersgill (2015) showed that for numerical models of
223 cut slopes, the weighting function proposed by Galavi and Schweiger (2010)
224 produces results that are the least mesh-dependent compared to alternative
225 weighting functions such as the gaussian distribution used by Bažant, et al., (1984)
226 or the over-nonlocal method used by Vermeer and Brinkgreve (1994).

227
$$\omega'(r) = \frac{r}{l} e^{-\left(\frac{r}{l}\right)^2}$$

228 Equation (6)

229 Where, l = internal length and r = distance from the stress point to adjacent stress
230 points.

231 As mesh dependency of local and nonlocal strain-softening models and the effect of
232 different weighting functions have been rigorously examined by Summersgill, et al.,
233 (2017), the work reported in this paper utilises the nonlocal strain-softening
234 regulatory approach but does not aim to further advance current methodology.

235 ***Mechanical Properties***

236 As discussed previously, seasonal ratcheting can lead to mobilisation of post-peak
237 strength and progressive failure. Therefore, establishing the correct strain-softening
238 model, strength, strains, and stiffness relationship is fundamental for the correct
239 modelling of the behaviour being investigated. The relationships for material
240 parameters used within the slope analyses have been taken from literature and
241 derived through the calibration of single element numerical analysis of
242 overconsolidated drained triaxial tests against experimental data for Kaolin. Take
243 and Bolton (2011) used Speswhite Kaolin within their centrifuge experimentation
244 under the rationale that the material has been well classified by others within the
245 literature.

246 ***Stiffness Properties***

247 The stiffness relationships adopted for Kaolin have been taken from reported
248 numerical modelling of a Kaolin embankment centrifuge experiment (Almeida, et al.,
249 1986) in which the bulk and shear moduli are a function of the specific volume, mean
250 effective stress and are updated at each time-step (Schofield & Wroth, 1968). Small-
251 strain stiffness, which is known to influence the rate of plastic strain accumulation
252 and non-linearity of stiffness, has been omitted from this study as deformations
253 observed in the physical modelling are far in excess of small-strain criteria (i.e. >1%
254 strain). Therefore, the use of a stress-dependent stiffness model based on large-
255 strain stiffness, which has been used in previous numerical modelling of a Kaolin
256 embankment in centrifuge experimentation (Almeida, et al., 1986), is more
257 appropriately aligned to the strain conditions being modelled. The additional
258 computational requirements to include small-strain stiffness is not merited for the
259 negligible impact this will have on model results.

260 $K = \frac{v \cdot \sigma'}{\kappa}$; min 2000kPa

261 Equation (7)

262 $G = \frac{3(1 - 2v')}{2(1 + v')} \cdot K$

263 Equation (8)

264 Where, K = bulk modulus (kPa); G = shear modulus (kPa); v = specific
265 volume ($v = 1 + e$); e = void ratio; κ = gradient of the swelling line; v' = Poisson's
266 ratio and σ' = mean effective stress (kPa) (Bishop's generalised effective stress).

267 Specific volume is obtained from knowledge of the consolidation and swelling
268 properties, the stress history, and the current stress state of the soil (Schofield &
269 Wroth, 1968). The specific volume, and thus stiffness, of the soil will change due to
270 cycles of wetting and drying, driving pore water pressure cycles that act as
271 environmental loading and unloading changing the effective stress state of the soil.
272 This can be considered in the $v: \ln(\sigma')$ space in line with Equation (9) and Equation
273 (10).

274 $v = v_\lambda - \lambda \cdot \ln \frac{\sigma'}{\sigma_{ref}}$, normal consolidation line

275 Equation (9)

276 $v = v_\kappa - \kappa \cdot \ln \frac{\sigma'}{\sigma_{ref}}$, swelling lines

277 Equation (10)

278 Where; λ = gradient of the virgin compression line; σ_{ref} = reference pressure (kPa);
279 v_λ = original specific volume at reference pressure; v_κ = specific volume at reference
280 pressure following the swelling line.

281 For Kaolin, the gradient of the normal consolidation line can be taken as $\lambda = 0.25$
282 and the swelling line as $\kappa = 0.05$ (Clegg, 1981; Take, 2003). Kaolin consolidated to
283 500kPa is cited as having a void ratio of approximately $e = 1.0$ (Al-Tabbaa & Wood,
284 1987). The corresponding specific volume at 500kPa is therefore $v = 2.0$ and the
285 specific volume for a reference pressure of 1kPa is $v_\lambda = 3.55$.

286 *Strength Properties*

287 To calibrate the strength and plastic strain criteria for the strain-softening behaviour
288 of Kaolin, an axisymmetric single element numerical model employing a local strain-
289 softening model was used to replicate drained overconsolidated triaxial tests (note
290 that the nonlocal strain-softening regulatory model cannot be used for a single
291 element model as no averaging of local strains can occur). For the slope analyses,
292 the local plastic strain criteria obtained from the numerical analyses of the triaxial
293 tests (i.e. $\varepsilon_{d,peak} = 0.05$ and $\varepsilon_{d,critical_state} = 0.15$) have been adopted within the
294 nonlocal strain-softening model (i.e. $\varepsilon_{p,peak}^* = 0.05$ and $\varepsilon_{p,critical_state}^* = 0.15$) along
295 with an internal length parameter equivalent to element thickness. This follows the
296 method presented by Summerhill, et al., (2017) where local plastic strain criteria from
297 previous studies have been taken as the nonlocal plastic strain criteria for analysis of
298 London Clay cut slopes.

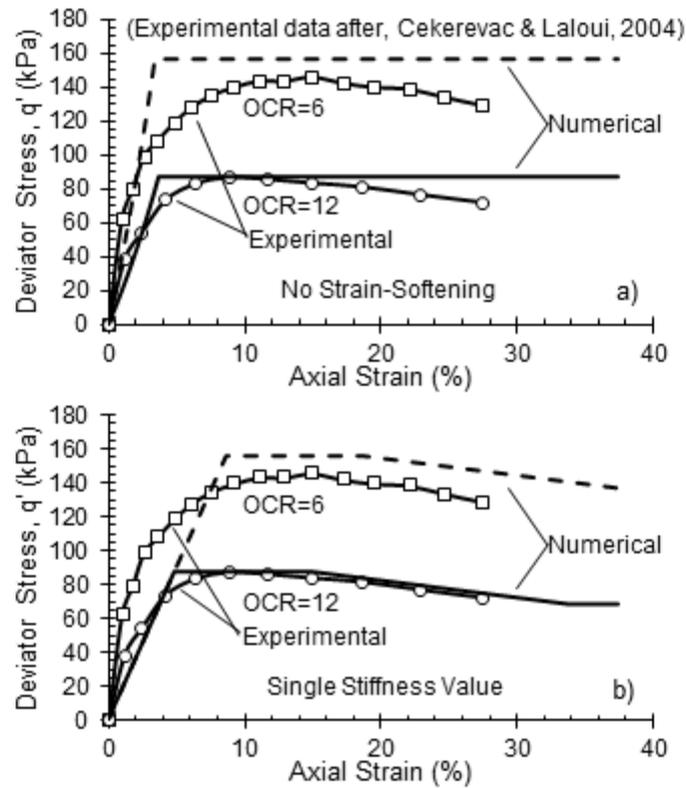
299 The dilation angle used in the numerical analyses has been assumed to be $\psi = 0$, as
300 dilation only affects the thickness of the shear surface, which is not critical in the
301 current study, not the magnitude of shear strains along the shear surface.

302 *Mechanical Behaviour*

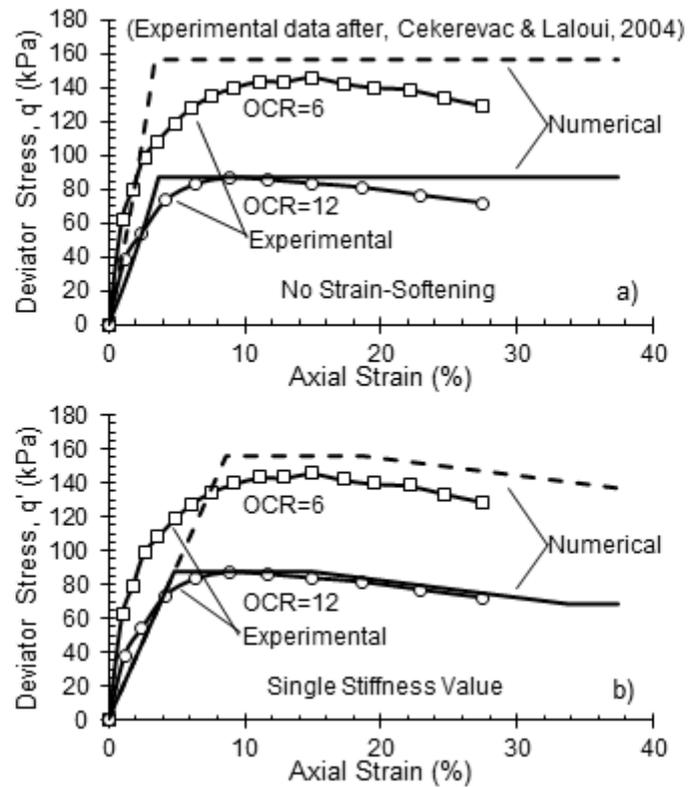
303 An axisymmetric, single element numerical model of overconsolidated drained
304 triaxial tests has been conducted to replicate tests undertaken by Cekerevac and
305 Laloui (2004). The model was fully saturated, and volume change due to drainage
306 was permitted (i.e. drained conditions were maintained). The samples were initially
307 consolidated to 600kPa and then unloaded to 100kPa (OCR=6) and 50kPa
308 (OCR=12). The initial stresses were applied to the numerical model and the
309 horizontal confining pressure fixed. A constant velocity was applied to the top of the
310 element to emulate loading in a strain-controlled test. The specific volume
311 relationship for the triaxial test numerical model is dependent on the swelling line
312 following the consolidation to 600kPa, giving $v_{k,ref} = 2.27$ at a reference pressure of
313 1kPa. The stress path of the samples and corresponding specific volume can be
314 seen in Figure 2a. During the analysis, the deviator stress, axial strain and stress
315 path of the model were monitored; these have been compared against experimental
316 data for Kaolin presented by Cekerevac and Laloui (2004) in Figure 2.

317 Figure 2b shows that the peak strength mobilised for different overconsolidation
318 ratios in the numerical model are of comparable magnitudes and mobilised at axial
319 strains representative of the experimental triaxial tests. This good fit confirms the
320 relevance of the strength parameters, the strain criteria, and the stiffness relationship
321 adopted for the mechanical behaviour of Kaolin. Importantly, the numerical model
322 captures the softening behaviour from peak to critical state at large strains, omitting
323 this mechanism from the numerical analyses has significant implications as post-
324 peak strength cannot be mobilised, a mechanism that is fundamental to this study.

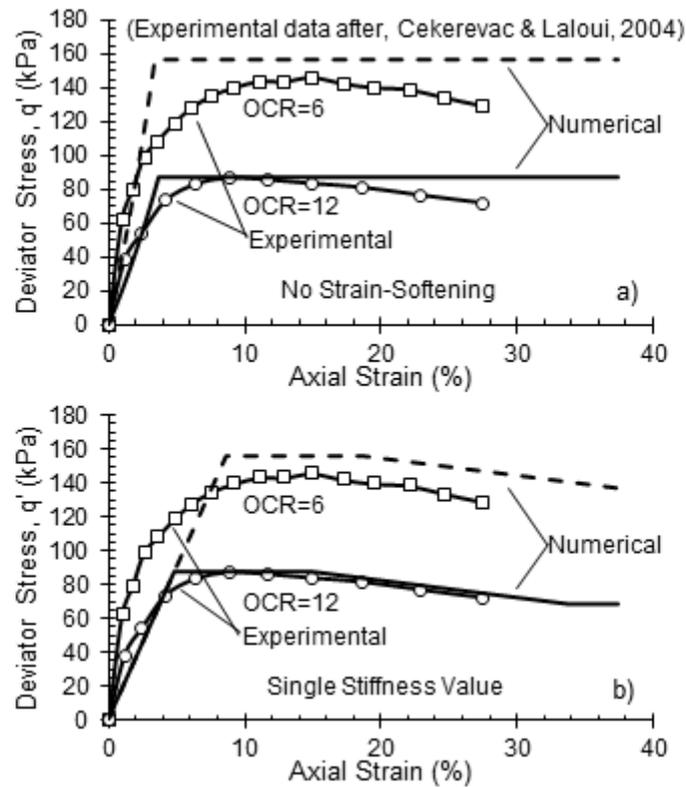
325 To assess the significance of the strain-softening model and stiffness relationship
326 presented, simple sensitivity analyses where these mechanisms were omitted for the
327 same triaxial test models were conducted, these are shown within



328 Figure 3. Without strain-softening behaviour, post-peak strength is not modelled, and
329 strength at large strains is grossly overestimated, see



330 Figure 3a. Without stiffness related to specific volume (i.e. single value of bulk and
 331 shear moduli), there is a significant difference in the strains at which peak strength
 332 are mobilised and the difference in the stress history (i.e. the overconsolidation ratio)
 333 of the samples is not accounted for, see



334 Figure 3b. The derived strain-softening parameters, plastic strain criteria and other
 335 mechanical properties used in the numerical analyses of the slope models are
 336 summarised in Table 1.

337 **Hydrogeological Properties**

338 To complete the coupled hydro-mechanical framework, soil water retention
 339 properties for Kaolin are presented in Figure 4 and summarised in Table 2. Soil
 340 water retention properties have been derived by fitting a van Genuchten (1980) style
 341 soil water retention curve to experimental data from Tarantino (2009), Hu, *et al.*,
 342 (2013) and Tripathy, *et al.*, (2014). The soil water retention curve used in this work
 343 does not account for hysteresis effects due to wetting and drying, which have been
 344 shown to be important in modelling infiltration (Bashir, *et al.*, 2016), or the fact that
 345 soil water retention properties vary with void ratio (Hu, *et al.*, 2013). In addition, the
 346 effect of deterioration of soil water retention properties due to repeated stress cycles

347 has not been accounted for. These simplifications have been made as the
348 magnitude of pore water pressure variation is relatively small and only a small
349 number of wetting and drying cycles are experienced. Therefore, the effect of
350 hysteresis and soil water retention property deterioration on the model results will be
351 small. As stated previously, this work looks to validate mechanical behaviour due to
352 established environmental stress cycles, so as long as hydrogeological behaviour,
353 and corresponding stress cycles, can be suitably replicated this simplification of soil
354 water retention properties is considered acceptable.

355 When modelling complex stratigraphy, it has been shown that including depth
356 dependent saturated hydraulic conductivity is important (Potts, et al., 1997). Within
357 this exercise, prior to the seasonal wetting and drying cycles, the Kaolin block has
358 been consolidated to a near constant void ratio and therefore has a uniform
359 saturated hydraulic conductivity at initialisation of the model. Some variability will
360 occur in saturated hydraulic conductivity due to swelling during wetting and
361 shrinkage due to drying and this is accounted for by the saturated hydraulic
362 conductivity being void ratio, and therefore stress, dependent. The relationships
363 used to calculate saturated hydraulic conductivity are empirical and taken from
364 laboratory studies of Kaolin by Al-Tabbaa and Wood (1987). The saturated hydraulic
365 conductivity relationship is given in Equation (11) and Equation (12), in which the
366 vertical and horizontal saturated hydraulic conductivity are related to void ratio ($e =$
367 $v - 1$) and are updated at each time-step within the numerical model; void ratio is
368 calculated considering specific volume as presented previously for the stiffness
369 relationship. This relationship has been included to allow the saturated hydraulic
370 conductivity to change depending on the stress state of the soil. Figure 4b shows the
371 effect of different void ratios on the relative hydraulic conductivity function, calculated

372 in line with the closed form solution presented by van Genuchten (1980), for water
373 within the soil. As the void ratio increases (i.e. stresses reduce), the saturated
374 hydraulic conductivity and therefore relative hydraulic conductivity increases.

$$375 \quad k_{sat,vertical} = 0.53e^{3.16} \times 10^{-9} \text{ m/s}$$

376 Equation (11)

$$377 \quad k_{sat,horizontal} = 1.49e^{2.03} \times 10^{-9} \text{ m/s}$$

378 Equation (12)

379 **Validation of the Numerical Modelling Approach**

380 Using the material parameters and relationships presented, a comparison of
381 hydrogeological and mechanical response of the two 1/60th 60g physical models
382 described previously (Take, 2003; Take & Bolton, 2011), with full scale 1g numerical
383 analyses has been conducted. All times and displacements from the physical
384 modelling have been scaled to full scale 1g; scaling factors from centrifuge ng to full
385 scale 1g are time, n^2 and length, n .

386 The hydrogeological response of the numerical analyses and boundary conditions
387 applied have been compared with pore water pressure measurements from high-
388 capacity tensiometers in the physical modelling (Take & Bolton, 2003). The
389 mechanical responses of the numerical analyses are compared with displacements
390 obtained from the physical modelling using the PIV measurement technique (White,
391 et al., 2003).

392 **Initial Conditions**

393 To replicate the steps taken to initiate the physical model by Take (2003), in the
394 numerical model Kaolin blocks were initially saturated and subjected to one-
395 dimensional consolidation to 500kPa (WAT7a) and 200kPa (WAT8a) and unloaded
396 to 0kPa. Complete pore water pressure equilibration was reached between each
397 loading increment within the numerical analyses. In the physical modelling, the slope
398 was shaped in the block of consolidated material at 1g, then spun to equilibrium at
399 60g in the centrifuge. To replicate this in the numerical analysis, following the one-
400 dimensional consolidation, the horizontal stresses were initiated to replicate the
401 stress history of the material in the physical models and then the slope formed
402 through the removal of elements.

403 Horizontal stresses, initiated within the Kaolin block following one-dimensional
404 consolidation, have been determined by considering the overconsolidation ratio and
405 the coefficient of earth pressure at rest (K_0) of the physical models. The
406 overconsolidation ratio was determined using Equation (13). The coefficient of earth
407 pressure at rest for reconstituted clays has been shown to fit the empirical
408 relationship given in Equation (14) (Mayne & Kulhawy, 1982).

$$409 \quad OCR = \frac{\sigma'_{v,maximum}}{\sigma'_{v,current}}$$

410 Equation (13)

$$411 \quad K_0 = K_{nc} \cdot (OCR)^{\varphi'}$$

412 Equation (14)

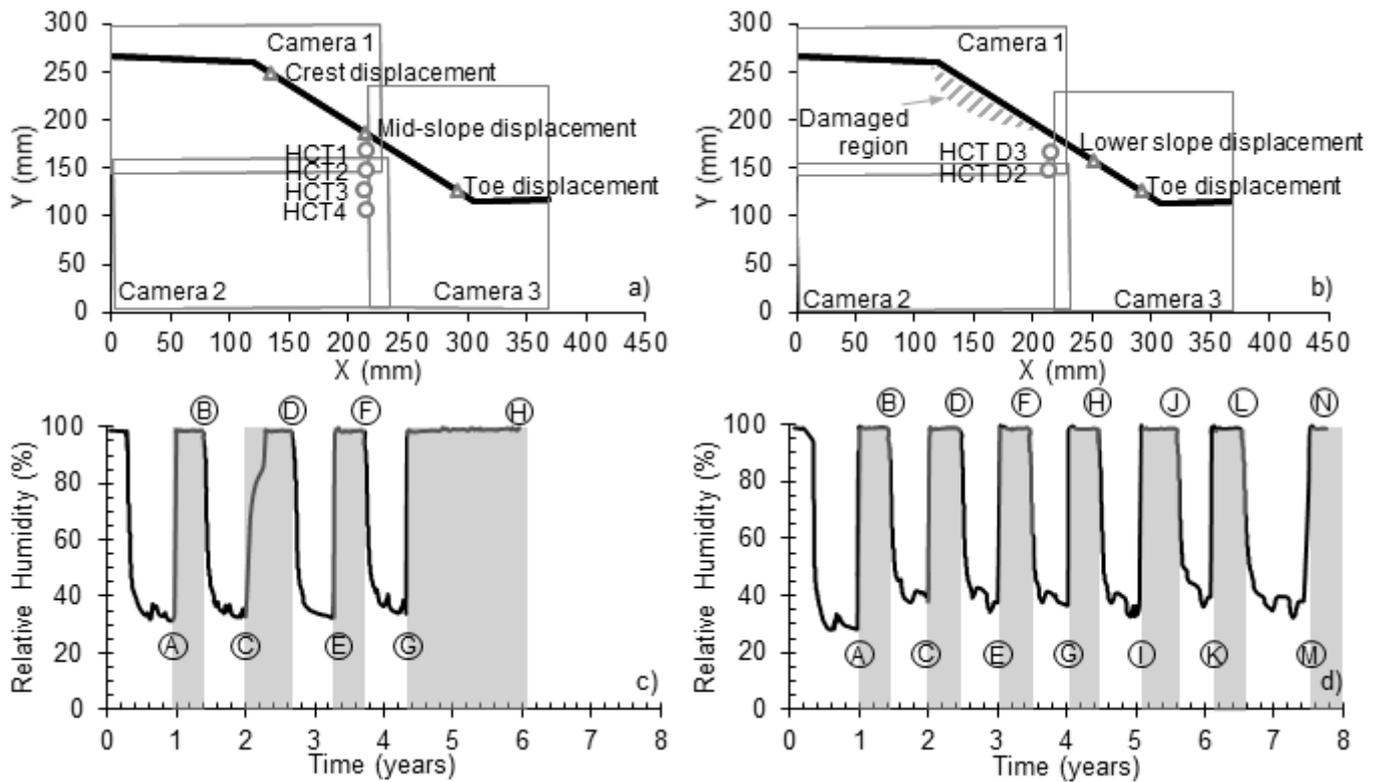
413 Where; $K_{nc} = 1 - \sin \varphi'$ and φ' is in radians in Equation (14).

414 The overconsolidation ratio, coefficient of earth pressure at rest, vertical and
415 horizontal stress with depth for both WAT7a and WAT8a are shown in Figure 5 for
416 conditions prior to shaping of the slope profile.

417 The physical models considered by Take (2003) and Take and Bolton (2011) were
418 260mm high and the nominal radius of the centrifuge used at the University of
419 Cambridge is 4.125m (Wood, 2004). As the model height is less than 0.1 times the
420 radius of the centrifuge arm, the variation in the centripetal acceleration across the
421 depth of the sample can be assumed to be negligible (Wood, 2004) and has
422 therefore been omitted from the numerical model.

423 As with the triaxial test, the specific volume of the soil must be considered within the
424 numerical model to ensure mechanical and hydrogeological behaviour is being
425 captured correctly. The specific volume relationships for the two slope models are
426 shown in Figure 6, where $v_{\kappa,500} = 2.31$ and $v_{\kappa,200} = 2.49$. As stresses within the
427 slope due to seasonal boundary conditions do not exceed the original consolidation
428 pressures of either slope model, further movement along the virgin compression line
429 will not occur.

430 It should be noted that during formation of the physical model WAT8a, the region
431 near the crest of the slope was damaged and a portion of the slope became
432 dislodged during the initial seasonal cycle before reattaching during a drying phase.
433 The portion affected is shown in



434 Figure 1. To ensure that this event does not influence the comparison of mechanical
 435 behaviour between the physical and numerical models, displacement records are
 436 considered only at the lower part and toe of the slope for model WAT8a.

437 **Boundary Conditions**

438 To replicate transient pore pressure conditions, and therefore environmental stress
 439 cycles, generated during the physical modelling, the numerical models have been
 440 subjected to inflow and outflow discharge boundary conditions along the model
 441 upper surface (i.e. toe, slope and crest).

442 During the physical modelling, it was not possible to determine the exact quantity of
 443 water flowing into and out of the slope. Therefore, the numerical model discharge
 444 boundary conditions have been applied to drive the pore pressure cycles observed
 445 at HCT1 for WAT7a and HCT D3 for WAT8a, and hence produce the environmental
 446 stress cycles in the near-surface of the slope of the same magnitude and frequency

447 to those observed in the physical model. For completeness, the discharges applied
448 to the slope surface are presented in Figure 8. The tensiometers used to measure
449 pore water pressures are approximately 1.0m below the slope surface at full scale
450 and are the closest measurements of hydrogeological behaviour to the slope surface
451 where the boundary conditions are applied; the implications of this are discussed
452 later. It should be noted that during drying, pore water pressure suctions along the
453 slope surface to achieve the correct suctions in HCT1 and HCT D3, were much
454 higher than at the location of HCT1 and HCT D3 resulting in the near-surface of the
455 slope becoming desaturated within the numerical analyses. A typical mesh of 0.5 x
456 0.5m elements used for the numerical modelling is shown in Figure 7.

457 The work presented here does not further current modelling capabilities to assess
458 soil-vegetation-atmosphere interactions but aims to validate mechanical behaviour of
459 seasonal ratcheting and accumulated deterioration due to the imposed wetting and
460 drying stress cycles.

461 ***Hydrogeological Response***

462 Figures 9 and 10 show the magnitude and timings of maximum and minimum
463 seasonal pore water pressure cycles are comparable between the experimental and
464 numerical models. The near-surface pore water pressures driving stress changes in
465 the main area of interest (i.e. the near-surface) are a close match. It should be noted
466 that for WAT7a, at waypoint C, the centrifuge was temporarily paused to allow
467 cameras to be reset and as such the dip in pore water pressures at this point are an
468 artefact of this process and have not be replicated within the numerical model,
469 therefore, the focus is waypoint D onwards. The drying phase within the numerical
470 modelling captures the same hydrogeological behaviour as that of the physical

471 model. However, the numerical model does not perform as well during the wetting
472 phase. This can be explained by the fact that the numerical models assume the
473 material is uniform whereas in reality, preferential flow routes exist as well as gaps
474 between the slope and the centrifuge chamber following drying, causing shrinkage of
475 the clay. This led to an increased hydraulic conductivity following the change in
476 boundary conditions from drying to wetting that cannot be accounted for within the
477 numerical analysis.

478 Figures 9 and 10 show that the stress path taken by elements of soil during wetting
479 differs between the numerical and physical modelling, however, the stress state (i.e.
480 pore water pressures) within the different analyses are equivalent at each waypoint
481 (i.e. point of change between wetting or drying); both the physical and numerical
482 models reach the same conditions at the same time for the maximum and minimum
483 values in each cycle. Therefore, the magnitude of the effective stress cycles
484 experienced by both models in the near-surface will be the same. At greater depth,
485 the numerical model predicts smaller pore water pressure fluctuation than measured.
486 This can be explained by the hydrogeological properties used within the numerical
487 analysis. These give lower hydraulic conductivity at depth than in the physical model
488 due to the relationships employed not accounting for preferential flow routes.

489 As stipulated previously, this work is interested in validating near-surface behaviour
490 of clay slopes subjected to wetting and drying stress cycles, therefore, it is the near-
491 surface hydrogeological behaviour that is of significance and pore water pressure
492 cycles at depth are of less relevance within this study.

493 ***Mechanical Behaviour***

494 The hydrogeological behaviour of the physical system and corresponding effective
495 stress cycles within the near-surface of the slopes due to seasonal wetting and
496 drying have been replicated within the numerical analyses. This allows mechanical
497 behaviour of the numerical models driven by these established stress cycles to be
498 compared with the measured deformations from the physical modelling. This is
499 critical in demonstrating and validating that the numerical modelling approach
500 developed can effectively replicate seasonal driven cycles of shrink-swell
501 displacements, seasonal ratcheting, and progressive failure and is a key contribution
502 of this study.

503 Figure 11 shows measured and modelled displacements for WAT7a and
504 demonstrates that the distinctive shrink-swell movement and accumulation of
505 outward and downward displacements, characteristic of seasonal ratcheting, are
506 captured using the approach described in this paper. Key aspects of seasonal
507 ratcheting behaviour have been captured; primarily vertical movement with little
508 horizontal displacement at the crest of the slope and conversely, significant
509 horizontal movement with little vertical displacement at the toe. However, there are
510 larger vertical displacements obtained in the numerical model than the physical
511 model at all locations.

512 The magnitudes of net displacements at the toe and mid-slope are close to those
513 observed experimentally following a complete cycle of wetting and drying (i.e. D-F in
514 Figure 11). In addition, Figure 12 shows that the magnitude of shear strains and
515 areas affected by strain accumulation at the toe of the slope at different times within
516 the analyses are comparable between the physical and numerical model. It should
517 be noted that there are a far greater number of points where strains are calculated
518 within the numerical model compared to the number of measurement points in the

519 physical models, which is why much higher shear strains are seen very close to the
520 toe of the slope. The accumulation of shear strains, a portion of which are elastic and
521 a portion plastic, illustrate the onset of progressive failure and mobilisation of post-
522 peak strength within the slope due to the pore water and hence effective stress
523 cycles experienced and movements that have occurred.

524 The larger vertical displacements observed in the numerical models can be
525 explained by considering how the stress cycles within the near surface have been
526 driven. Boundary conditions have been calibrated to replicate pore water pressure
527 and therefore stress cycles at HCT1, approximately 1.0m depth within the slope
528 model at full scale. From the discussion of hydrogeological response of the
529 numerical model, it was established that the saturated hydraulic conductivity
530 relationship used within the numerical analyses is lower than the physical model.
531 Therefore, considering drying, to achieve the same pore water pressure, and thus
532 stress condition, at 1.0m depth in the numerical model will require a discharge
533 boundary condition that is greater than will be experienced in the physical model.
534 This increased magnitude discharge boundary condition applied along the slope
535 surface will result in greater vertical deformation of points along the slope surface,
536 and it is these surface points that have been used for the comparison of the
537 numerical and physical model. In addition to the differences between the numerical
538 model and physical model boundary conditions, an isotropic stiffness model has
539 been used in the numerical analyses, but it is known that stiffness of consolidated
540 clays is in fact anisotropic. This difference will have contributed to some of the
541 differences observed.

542 Figure 13 shows the void ratios within the numerical analyses after a drying and
543 wetting phase. The stiffness and saturated hydraulic conductivity relationships are a

544 function of void ratio and are therefore stress dependent. It can be seen that there is
545 a significant change in the near-surface void ratio following wetting and swelling of
546 the soil, from a void ratio of around 1.10 at the end of drying increasing to
547 approximately 1.25 at the end of wetting. This variation adds further justification to
548 why material properties (i.e. stiffness and saturated hydraulic conductivity) must be
549 related to stress state.

550 Figure 14 shows a comparison of displacements for model WAT8a. Again, there are
551 greater vertical displacements within the numerical model but the annual cycle of
552 wetting and drying produces movements representative of seasonal ratcheting
553 observed in the physical modelling. Figures 11 and 14 demonstrate that the
554 numerical modelling approach developed can replicate the mechanical behaviour of
555 seasonal ratcheting for slopes with different initial stress conditions.

556 Neither slope model experienced complete failure during the physical modelling.
557 However, small sections at the toe of the slopes became detached from the models
558 at the end of the seasonal cycles imposed. This brittle behaviour following softening
559 observed in the physical model cannot be captured within the numerical model as
560 the soil is assumed to act as a continuum. However, large plastic strains were
561 observed in the toe of the slopes at the end of both numerical analyses.

562 The shear strains within WAT7a at waypoint G and the end of analysis, waypoint H,
563 have been considered in Figure 15. The shear strain contour plots show that there
564 are much higher shear strains and therefore softening within WAT7a following the
565 prolonged wetting at the end of the analysis. Figure 15 demonstrates the significance
566 of a prolonged wet period on the overall condition of a slope. The plot also illustrates
567 the nature of the progressive failure mechanism and the onset of softening from the

568 toe of the slope propagating back and up into the slope, which is a common
569 observation (Skempton, 1964; Potts, et al., 1997; Leroueil, 2001). The numerical
570 modelling approach developed can capture the mechanism of seasonal ratcheting;
571 characteristic movements due to environmental stress cycles, plastic strain
572 accumulation and progressive failure.

573 **Effects of Stiffness Parameters on Seasonal Ratcheting**

574 Given the validation of the numerical modelling approach presented, the approach
575 has been used to investigate the implication of different stiffness parameters on the
576 mechanical behaviour of seasonal ratcheting. This has been done by considering the
577 material used within the numerical model validation (Material A) and a stiffer material
578 (Material B). Slopes formed of the two materials with the same hydrogeological
579 properties have been subjected to the same continuous seasonal pore water
580 pressure cycles, and therefore effective stress cycles, to failure. The geometry and
581 initial consolidation pressure of model WAT7a have been used with extended cyclic
582 boundary conditions used to drive multiple -40kPa at the end of summer to 0kPa at
583 the end of winter, pore water pressure cycles at the location of HCT1. The stiffness
584 parameters for materials A and B are summarised in Table 3.

585 The results for the two stiffness soils are shown in Figure 16. For Material B, the
586 seasonal movement caused by the stress cycles is considerably less than that of
587 Material A. The magnitude of plastic deformation in a single wetting and drying cycle
588 is smaller and the time taken for the slope to fail due to mobilisation of post-peak
589 strength is much longer: 32 cycles in comparison to 14 cycles. Failure is defined by
590 sudden acceleration of the failing mass (i.e. significantly increased displacements
591 within a single stress cycle). This demonstrates the importance in using the

592 appropriate stiffness relationship when modelling seasonal-driven behaviour and
593 assessing deterioration due to seasonal ratcheting and progressive failure.

594 Interestingly, the shear bands obtained from the two models experiencing continued
595 seasonal stress cycles are both shallow and only incorporate the toe of the slope
596 (Figure 16f). While the slopes modelled are not directly comparable to high-plasticity
597 clay infrastructure slopes (i.e. having different stress histories, the inclusion of
598 vegetation, material variability etc.) the failure modes predicted by the numerical
599 analyses when considering environmental stress cycles are indicative of failures
600 observed in ageing high-plasticity clay infrastructure slopes (Briggs, et al., 2017).
601 The failures generated in the physical and numerical models and observed in
602 infrastructure slopes due to continued cyclic effective stresses are different to
603 deeper-seated progressive failure modes that result from prolonged wetting and
604 previously modelled by Potts, et al., (1997) and Summersgill, et al., (2017).

605 **Discussion**

606 The aim of the work described in this paper was to develop a numerical model
607 capable of capturing seasonal ratcheting behaviour of high-plasticity
608 overconsolidated clay slopes subjected to pore water and hence effective stress
609 cycles driven by wetting and drying. It has been conclusively demonstrated that
610 discharge boundary conditions within a two-phase flow software package that
611 employs Bishop's generalised effective stress can replicate seasonal ratcheting
612 behaviour and progressive failure if a van Genuchten (1980) style soil water retention
613 curve and relative hydraulic conductivity function to couple hydrogeological and
614 mechanical behaviour, and a strain-softening constitutive model are employed.

615 This study considers an idealised uniform high-plasticity overconsolidated soil with
616 simple summer-winter boundary conditions without vegetation. The failure
617 mechanism obtained using the numerical model replicates behaviour observed
618 experimentally. The failures predicted by the numerical analyses are indicative of
619 shallow first-time failures of ageing high-plasticity clay infrastructure slopes (Briggs,
620 et al., 2017). To the best of the authors' knowledge, this is the first time that seasonal
621 ratcheting movements and progressive failure due to wetting and drying stress
622 cycles have been replicated within a numerical framework and validated against
623 measured physical behaviour. The work extends previous published work on deep-
624 seated failure mechanisms (Potts, et al., 1997; Kovacevic, et al., 2001; Nyambayo,
625 et al., 2004) and weather-driven deformations of reactivated natural slope by Conte,
626 et al., (2016).

627 The presented slope models clearly demonstrate deterioration of high-plasticity clay
628 slopes through shear strain accumulation and progressive failure due to repeated
629 stress cycles driven by wetting and drying. The mechanism explored provides an
630 explanation for why a high-plasticity clay slope experiencing multiple similar
631 seasonal 'wet' conditions can fail due to a 'wet' event with the same magnitude as an
632 event that it had previously experienced and remained stable. With each seasonal
633 stress cycle, the condition of high-plasticity clay slopes can deteriorate, and the
634 magnitude of the final triggering event required to cause failure decreases. High-
635 plasticity clay slope deterioration occurs when near hydrostatic conditions are
636 reached and it is the frequency and duration spent at these conditions that dictates
637 the rate of deterioration. Understanding this deterioration process is vital to the
638 assessment of long-term behaviour of high-plasticity clay infrastructure earthworks,
639 in addition to investigating the implications of climate change.

640 The significance of stiffness properties on seasonal ratcheting has also been
641 demonstrated. To understand the rate of deterioration of a high-plasticity clay slope
642 adequately and to allow meaningful assessment of performance against number of
643 seasonal stress cycles, the stiffness relationship adopted must be representative of
644 the soil forming the slope.

645 More rigorous approaches are available for modelling unsaturated soil problems
646 (compared to Bishop's generalised effective stress method adopted in this work),
647 although they require use of a greater number of soil parameters, which may not be
648 practical. However, the validation presented has shown that the approach adopted is
649 capable of replicating and quantifying the observed mechanism of behaviour.

650 The analyses undertaken within this study utilise a nonlocal strain-softening
651 regulatory model to reduce mesh dependency, the approach used has been
652 presented and investigated extensively by others (i.e. Summersgill, et al., 2017). As
653 such, this work does not aim to improve current modelling capability considering
654 progressive failure.

655 The work replicates physical modelling of summer drying and winter wetting and to
656 model this numerically, simple uniform wetting and drying discharge boundary
657 conditions have been applied to the numerical analyses. This work validates an
658 approach for modelling the mechanism of seasonal ratcheting but does not progress
659 current approaches for modelling land-climate boundary conditions. The use of a
660 single soil water retention curve to relate suctions and saturations is a simplification.
661 It is known that hysteresis and variation in soil water retention properties due to
662 stress state are important characteristics of behaviour but these have not been
663 included within this study due to a lack of material property data for these aspects.

664 **Conclusion**

665 A numerical modelling framework including unsaturated behaviour and a nonlocal
666 strain-softening regulatory model has been developed to investigate seasonal
667 ratcheting in high-plasticity clay slopes. The numerical modelling approach
668 developed has been subjected to defined wetting and drying stress cycles and the
669 mechanical slope behaviour produced is indicative of seasonal ratcheting
670 displacements (i.e. outward and downward movements) observed in physical
671 modelling. It has been shown that seasonal ratcheting deformations due to repeated
672 wetting and drying stress cycles in high-plasticity clay slopes can lead to plastic
673 strain accumulation and progressive failure resulting in shallow first-time failures.

674 The validation of the numerical modelling approach against physical modelling
675 results, and parametric study undertaken have shown that strength deterioration of
676 high-plasticity clay slopes due to seasonal wetting and drying stress cycles occurs
677 when near hydrostatic conditions are reached within the near surface of a slope. It is
678 the frequency and duration at which these conditions are reached that dictates the
679 rate of strength deterioration. In addition, a parametric study has shown that material
680 stiffness has a significant influence on the magnitude of seasonal movements
681 occurring due to wetting and drying stress cycles, and hence the rate of deterioration
682 of a high-plasticity clay slope due to progressive failure and mobilisation of post-peak
683 strength.

684 While enhancements to the modelling framework can still be made (i.e. improved
685 land-climate boundary conditions and inclusion of stiffness anisotropy), this study
686 demonstrates it is possible to capture the role of cyclic wetting and drying behaviour
687 driving progressive failure resulting in shallow first-time failure in high-plasticity clay

688 slopes. This is an important step in better understanding the mechanism of seasonal
689 ratcheting and delivers the potential to study the implications of climate change on
690 the rate of slope deterioration due to this mechanism.

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818

Tables

819

Table 1 Kaolin mechanical properties

Peak Local Strain	0.05
Critical State Local Strain	0.15
Peak Nonlocal Strain	0.05
Critical State Nonlocal Strain	0.15
Internal Length Parameter (m)	0.5
Peak Cohesion (kPa)	6.25
Critical State Cohesion (kPa)	0.00
Peak Friction ($^{\circ}$)	24.0
Critical State Friction ($^{\circ}$)	24.0
Angle of Dilatation ($^{\circ}$)	0.0
Unit weight (kN/m ²)	17.9
λ	0.25
κ	0.05
Poisson's Ratio, ν'	0.35

820

821

Table 2 Fitted van Genuchten Parameters for Kaolin

van Genuchten fitting parameter (kPa)	α	7000
van Genuchten fitting parameter	n	1.85
van Genuchten fitting parameter	m	0.459

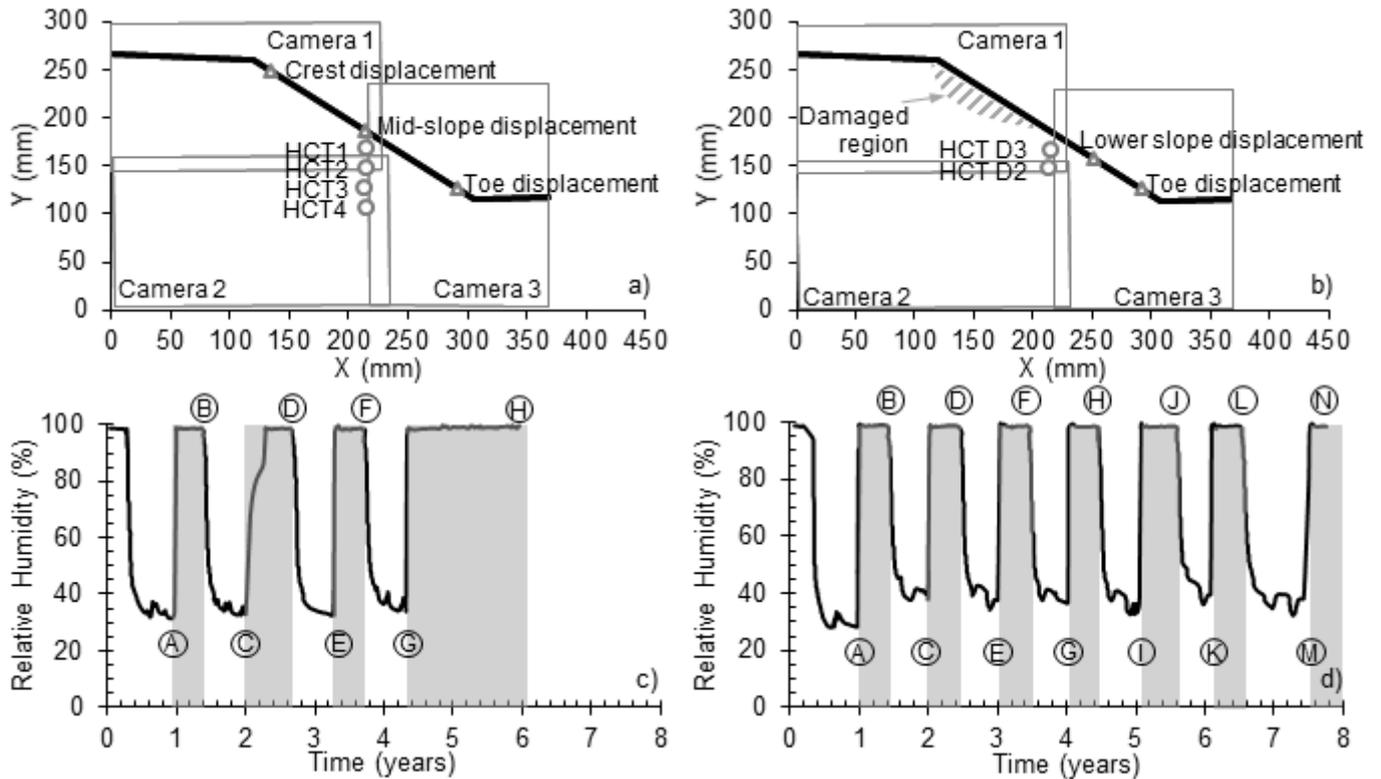
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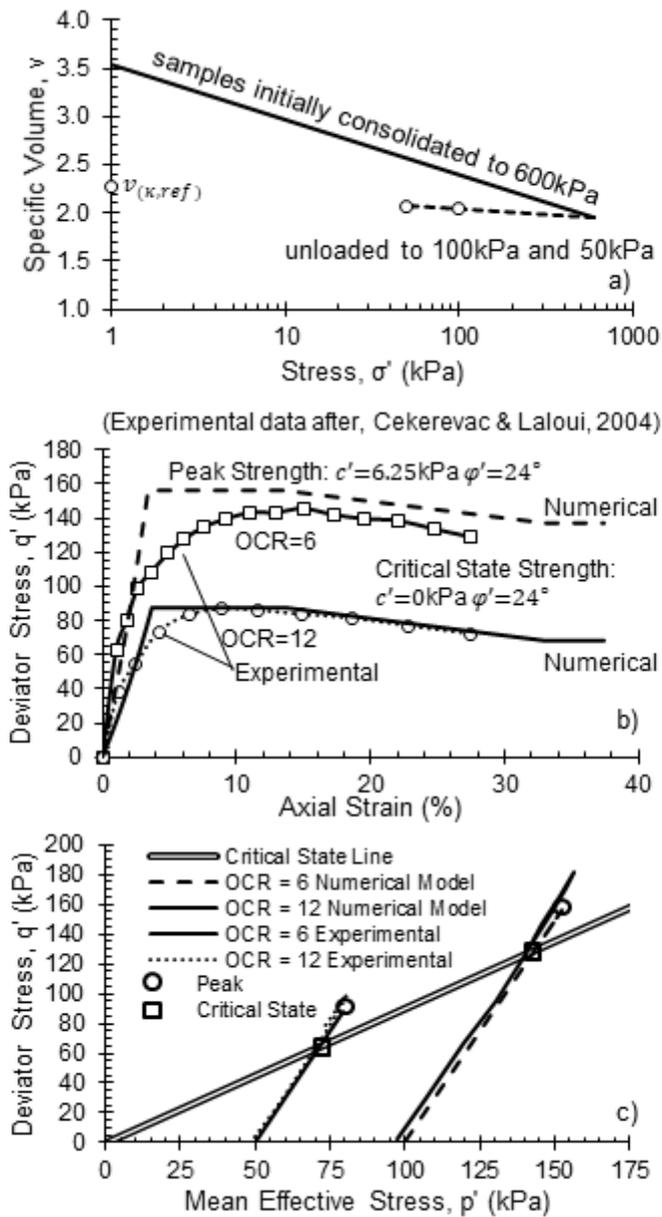
Table 3 Stiffness parameters for different materials

	Γ	λ	κ	K_{min} (kPa)
Material A	3.55	0.25	0.05	2000
Material B	2.65	0.124	0.02	3500

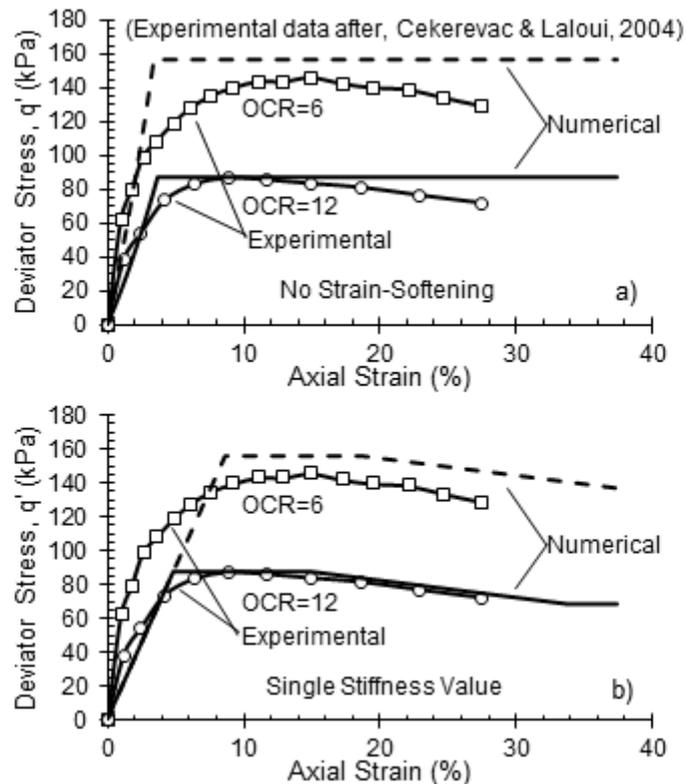
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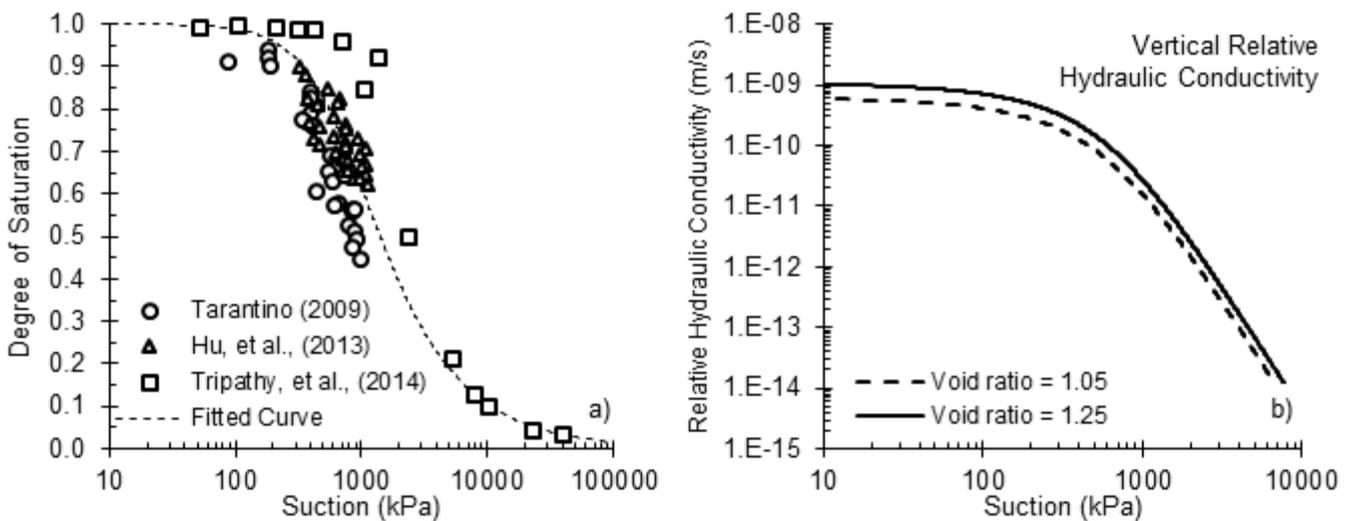
826 Figure 1 Physical model geometries (at 1/60th scale), camera locations for PIV
 827 measurements, tensiometer locations for pore pressure measurements and
 828 boundary conditions (after, Take, 2003); a) physical model WAT7a; b) physical
 829 model WAT8a; c) WAT7a boundary conditions; d) WAT8a boundary conditions



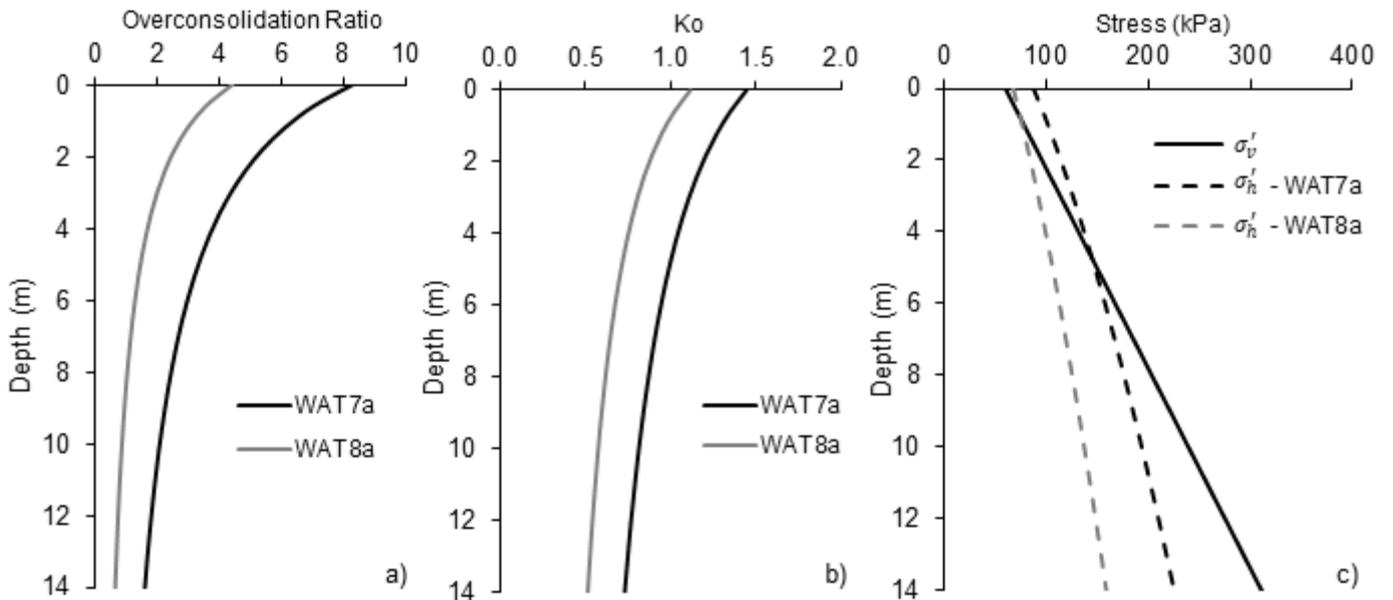
830 Figure 2 Comparison of measured and modelled triaxial test response of Kaolin
 831 (experimental data after, Cekerevac & Laloui, 2004); a) specific volume plot; b)
 832 stress-strain plot; c) stress path plot



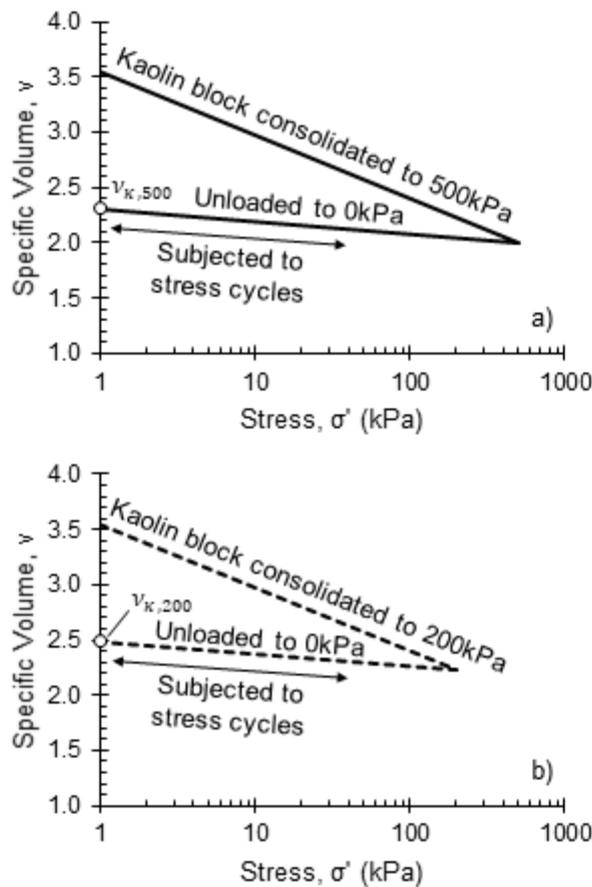
833 Figure 3 Sensitivity analyses of mechanical behaviour of Kaolin – stress-strain plots
 834 (experimental data after, Cekerevac & Laloui, 2004); a) no strain-softening
 835 behaviour; b) simple stiffness relationship



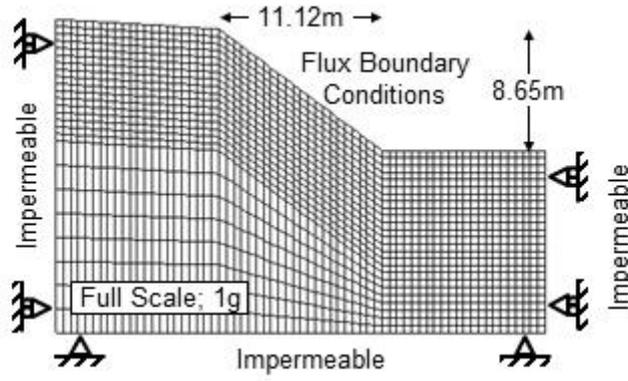
836 Figure 4 Kaolin soil water retention properties; a) soil water retention curve fitted
 837 against experimental data (experimental data after, Tarantino, 2009; Hu, *et al.*, 2013;
 838 Tripathy, *et al.*, 2014); b) vertical relative hydraulic conductivity function for different
 839 void ratios (e)



840 Figure 5 Initial stress conditions against depth prior to forming of slopes for WAT7a
 841 and WAT8a; a) overconsolidation ratio; b) K_0 ; c) stress state

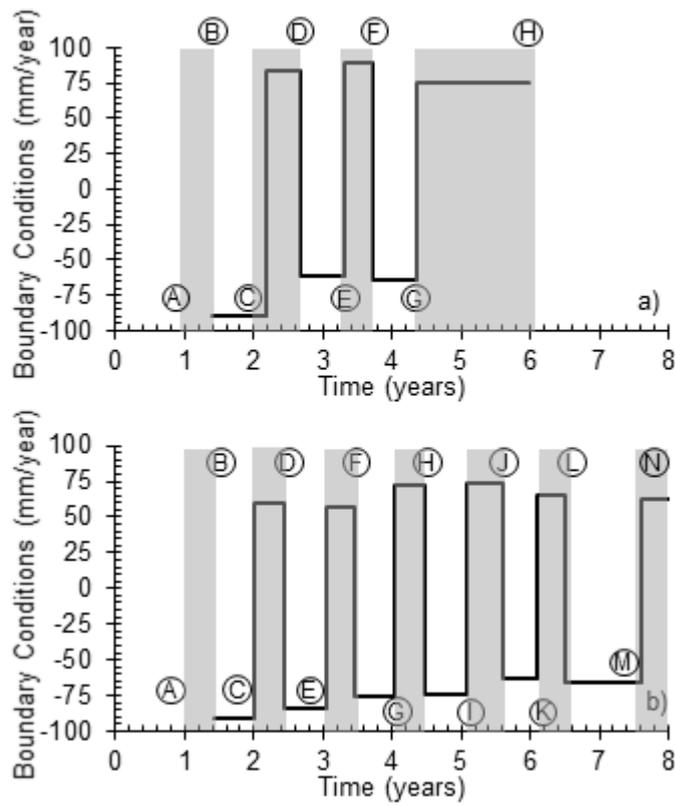


842 Figure 6 Specific volume relationships; a) WAT7a; b) WAT8a



843

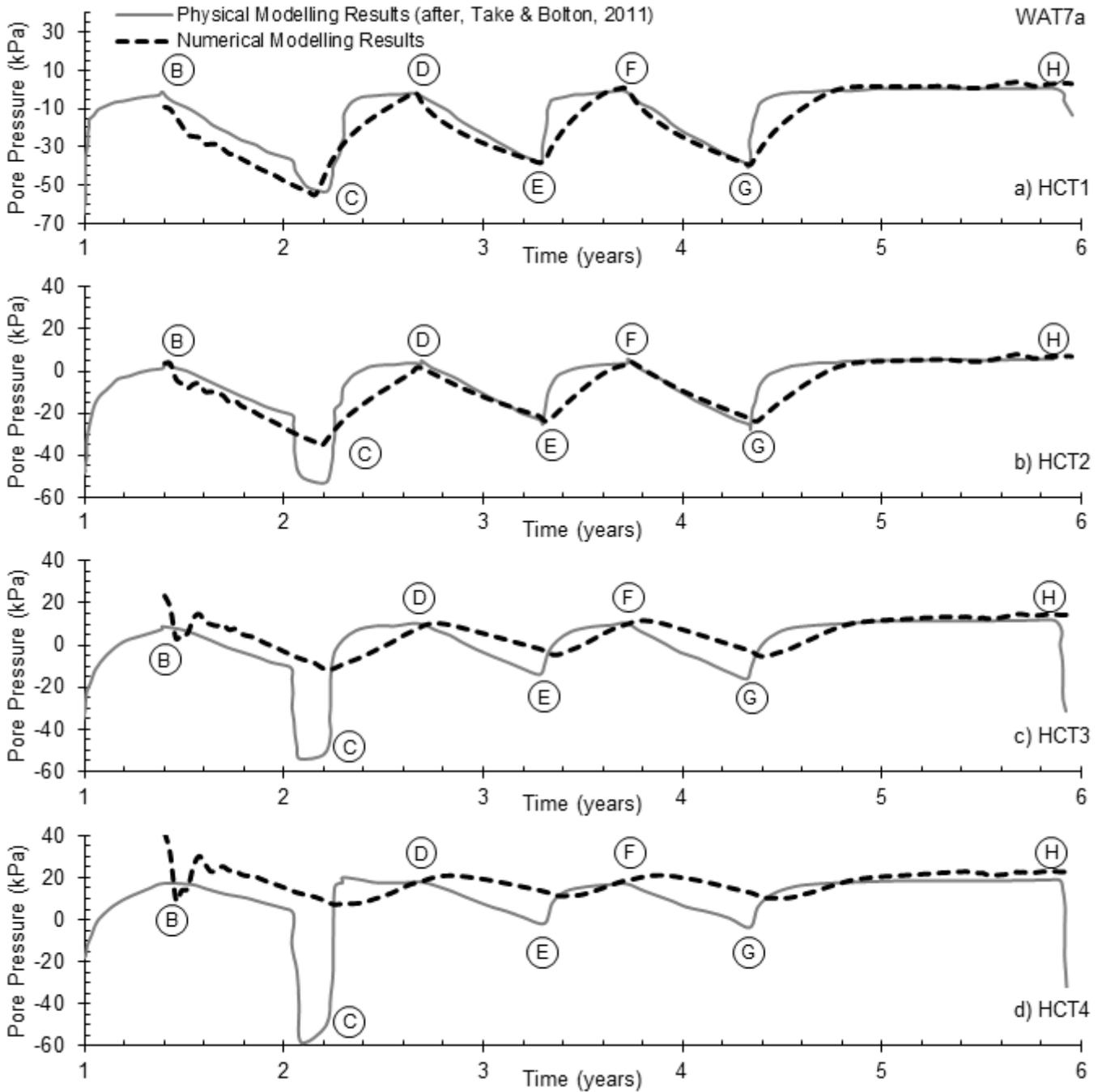
Figure 7 Typical mesh used



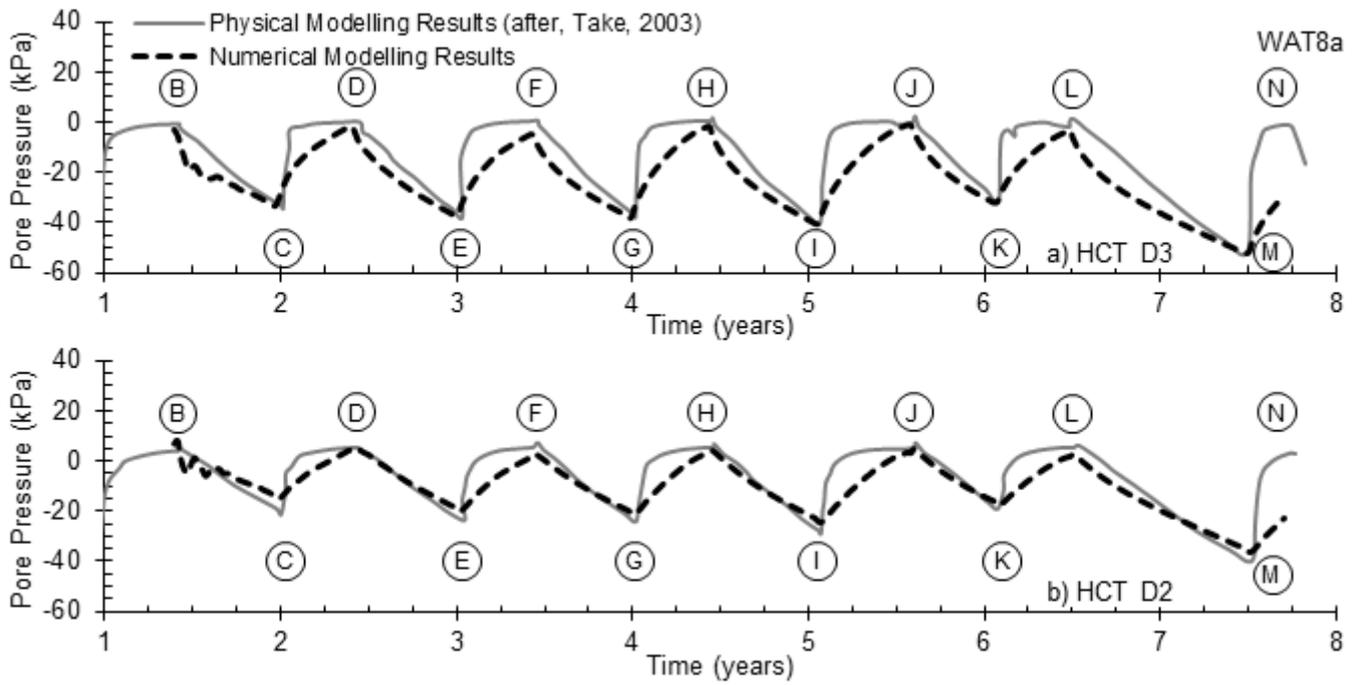
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Figure 8 Numerical model discharge boundary conditions; a) WAT7a boundary conditions; b) WAT8a boundary conditions

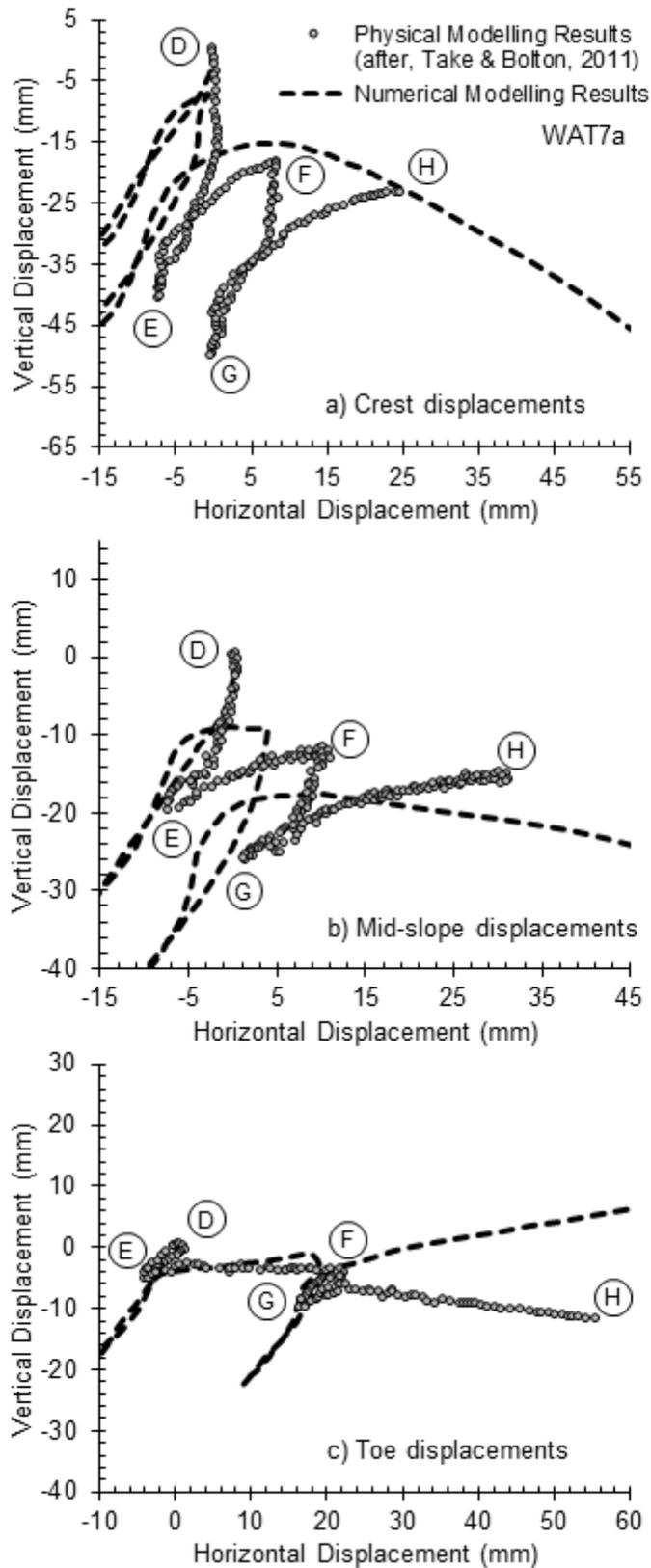
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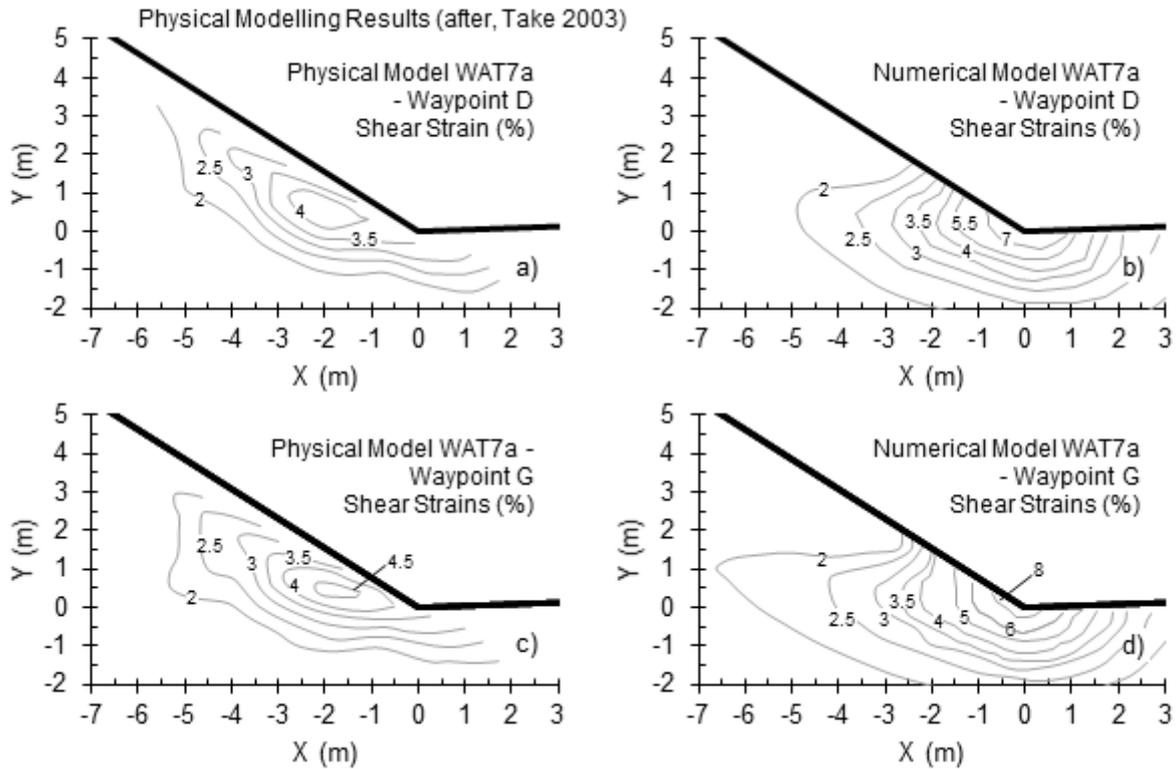
846 Figure 9 Comparison of physical and numerical modelling pore water pressures –
 847 WAT7a (experimental data after, Take & Bolton, 2011); a) HCT 1; b) HCT 2; c) HCT
 848 3; d) HCT 4



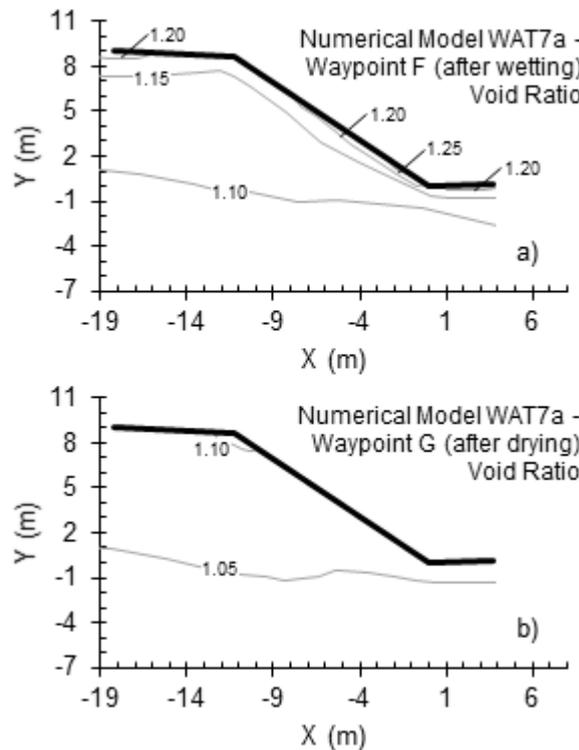
849 Figure 10 Comparison of physical and numerical modelling pore water pressures –
 850 WAT8a (experimental data after, Take, 2003); a) HCT D3; b) HCT D2



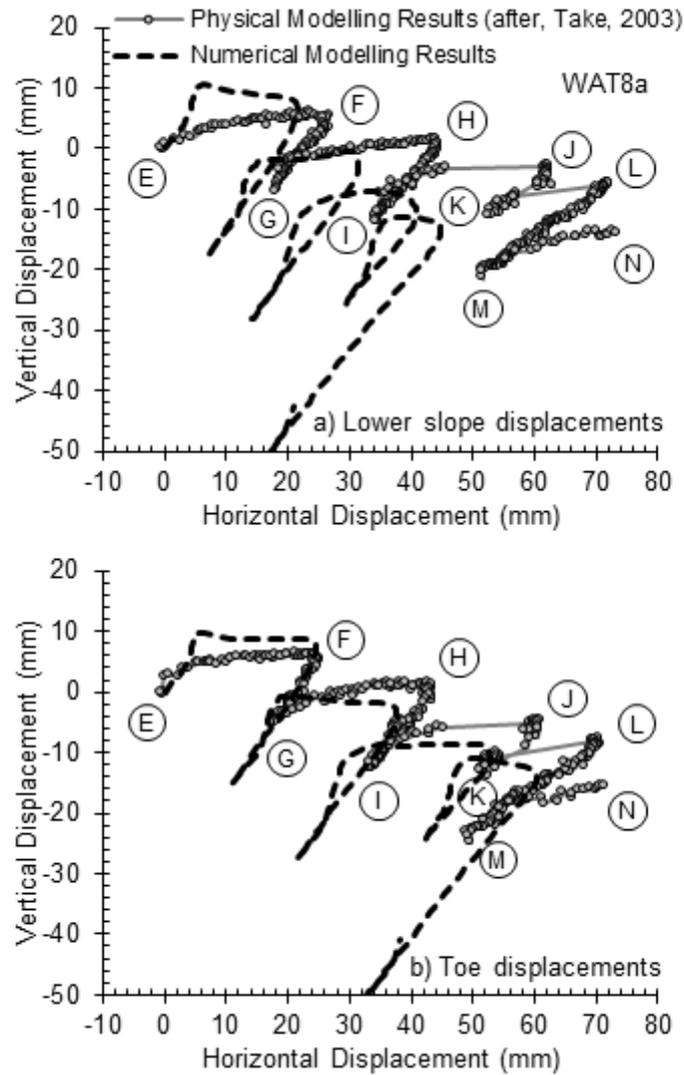
851 Figure 11 Comparison of physical and numerical modelling mechanical behaviour –
 852 WAT7a (experimental data after, Take & Bolton, 2011); a) crest displacements; b)
 853 mid-slope displacements; c) toe displacements



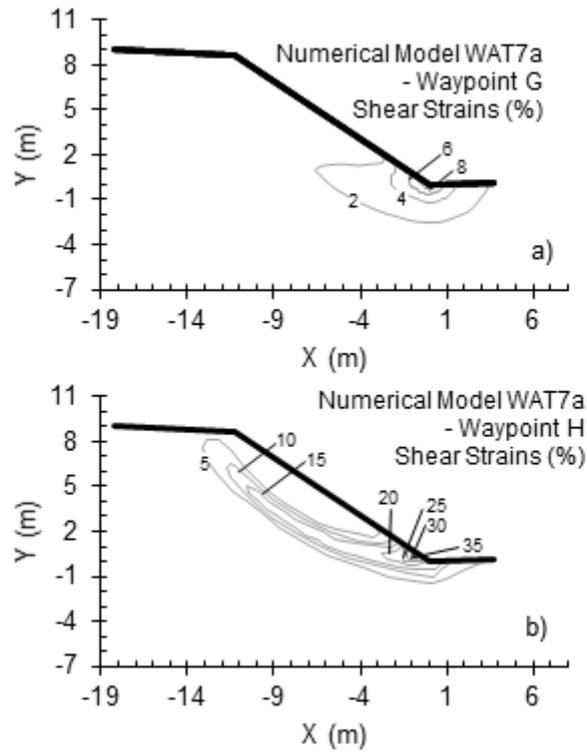
854 Figure 12 Comparison of physical and numerical modelling shear strains – WAT7a
 855 (experimental data after, Take, 2003); a) physical modelling waypoint D; b)
 856 numerical modelling waypoint D; c) physical modelling waypoint G; d) numerical
 857 modelling waypoint G



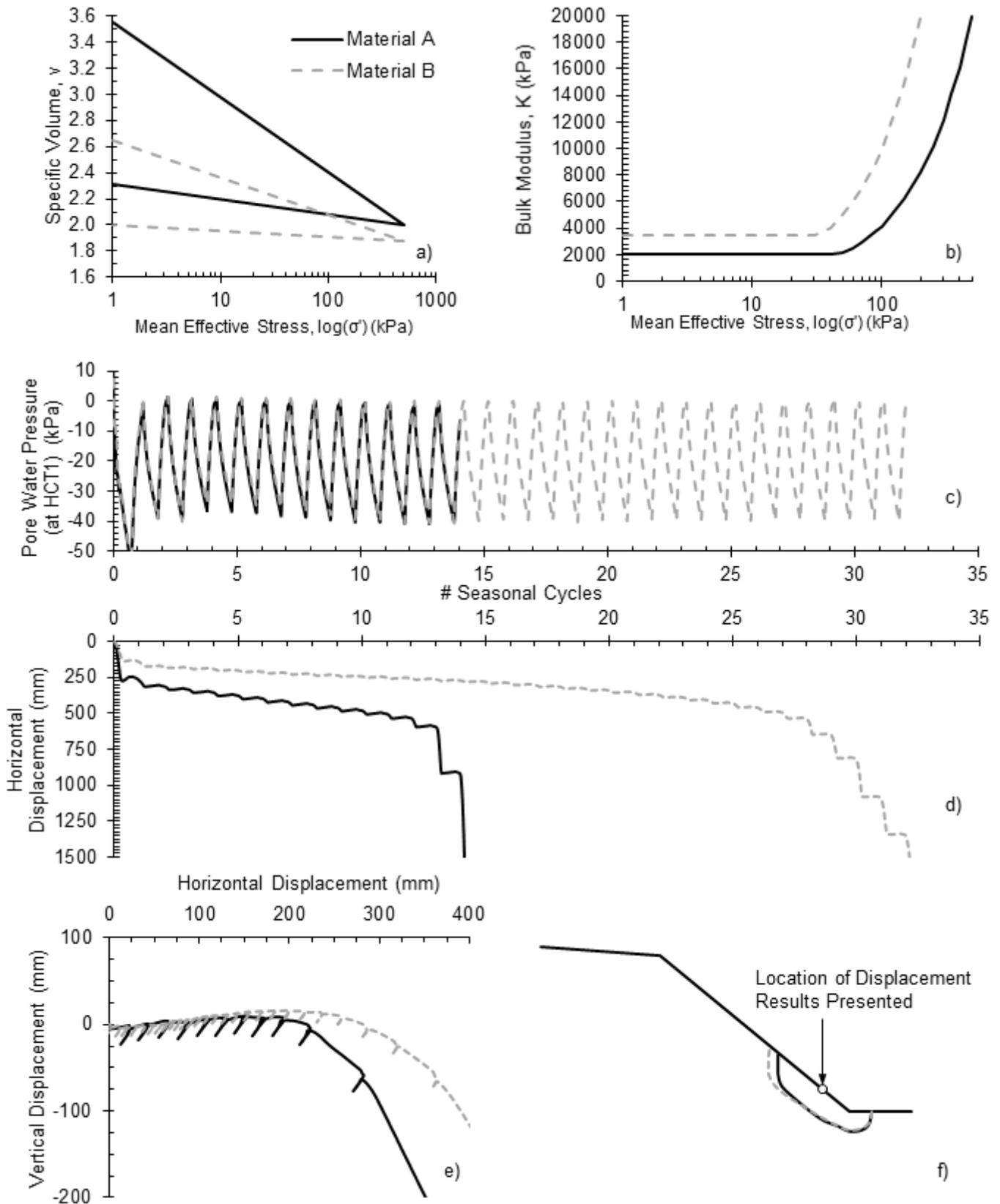
858 Figure 13 Comparison of void ratios within numerical model at different times –
 859 WAT7a; a) after wetting – waypoint F; b) after drying – waypoint G



860 Figure 14 Comparison of physical and numerical modelling mechanical behaviour –
 861 WAT8a (experimental data after, Take, 2003); a) lower slope displacements; b) toe
 862 displacements



863 Figure 15 Shear strain contours at different points in WAT7a numerical analysis; a)
 864 waypoint G; b) waypoint H



865 Figure 16 Comparison of materials with different stiffness under continued seasonal
 866 cycles of wetting and drying; a) specific volume; b) bulk modulus; c) pore water
 867 pressure cycles at HCT1; d) horizontal displacements; e) seasonal ratcheting
 868 displacements; f) shear surfaces