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4	Repertoire size, frequently determined by the number of discrete call types, has been used as
5	a means to assess vocal complexity in animals. However, species can also increase their
6	communicative complexity by using graded signals or by combining individual calls together.
7	Animal call sequences can be divided into two main categories, each subdivided into two
8	classes: repetitions, with either an unlimited or finite number of iterations of the same call
9	type, and mixed call combinations, composed of two or more graded or discrete call types.
10	Social contexts involve a wide range of behaviours and, unlike predation contexts, can be
11	associated with both positive and negative emotions. Therefore, interactions linked to social
12	contexts may place additional demands on an animal's communicative system and lead to the
13	use of call combinations. We systematically documented call combinations produced by wild
14	meerkats (Suricata suricatta), a highly social carnivore, in social contexts in their natural
15	habitat. We observed twelve distinct call combinations belonging to all four different classes
16	of combination, emitted in all of the observed behavioural contexts. Four combinations were
17	each produced in a specific context whereas the remaining eight were produced in several
18	contexts, albeit in different proportions. The broad use of combinations suggests that they
19	represent a non-negligible part of meerkat social communication and that they can be used in
20	flexible ways across various behavioural contexts. Comparison with combinations produced
21	in predation contexts indicated that social call combinations are more varied in number of
22	classes and structural complexity than the former, perhaps due to the greater variety of social
23	contexts. However, in meerkats, combinations of functionally referential calls have been

documented in predation but not social contexts, suggesting that both social and predation pressures may play a role in the evolution of combinatoriality in animal communication.

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Key Words: call combination - meerkat – natural observations – social context – vocal communication

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Communicative complexity related to signal diversity can be measured in two main ways: through assessing the number of distinct signals produced or by calculating the bits of information contained in the system (Freeberg, Dunbar, & Ord, 2012). To date, acoustic communicative complexity has mostly been assessed using vocal repertoire size (Oller & Griebel, 2008). However, most vocal repertoires only list the acoustically discrete call types the species produce and, for the majority of species, the number of these call types is physically constrained, limiting the size of their repertoire (Fitch, 2000). To achieve a higher communicative flexibility despite this limitation, some animal species produce intermediate call types, leading to a graded call system (Marler, 1976). An additional way to increase communicative flexibility is to combine individual calls (Arnold & Zuberbühler, 2006; Engesser, Crane, Savage, Russell, & Townsend, 2015). Combining calls has frequently been argued to be a more efficient way of conveying new messages than creating new calls (Jackendoff, 1999; Nowak, Plotkin, & Jansen, 2000) and may reduce the risk of perception errors from the receiver's side (Nowak & Krakauer, 1999; Nowak, Krakauer, & Dress, 1999). Through dividing call combinations described in the literature into categories based on the number of component call types, we can identify two main groups: repetitions and mixed call combinations. Repetitions are combinations composed of only one call type and can be subdivided into two classes: unlimited and finite. Unlimited repetitions are combinations that

are not characterised by the number of times the call is repeated. Examples of such combinations are corncrakes' (Crex crex) aggression calls (Rek, 2013), and alarm calls emitted repeatedly in many species (non-primate mammals: Blumstein & Armitage, 1997; Manser, 2001; non-human primates: Macedonia, 1990; Lemasson, Ouattara, Bouchet, & Zuberbühler, 2010; Schel, Candiotti, & Zuberbühler, 2010). On the contrary, finite repetitions are always composed of the same number of calls, for example the Bulwer's petrel's (Bulweria bulwerii) double calls are always composed of two calls (James & Robertson, 1985). Here we define mixed call combinations as sequences that include at least two different call types and can be either graded or discrete or both. Graded call combinations are sequences of calls that grade along a structural or temporal continuum between two discrete call types (Keenan, Lemasson, & Zuberbühler, 2013). Gradation can occur in the frequency parameters (e.g. peak frequency, frequency range), amplitude, or duration of the call. Examples of such combinations can be found in diverse taxa from amphibians to non-human primates (hereafter primates). One case of such a graded sequence is the Blanchard's cricket frog's (Acris crepitans blanchardi) aggression calls that become more aggressive with the approach of a simulated intruder (Wagner Jr, 1989), as expressed in the calls by an increase in length and number of pulses. In another case, the Senegal bushbaby (Galago senegalensis senegalensis) produces sequences of calls when excited that grade from one call type to another as the caller gets more aroused (Zimmermann, 1985). Moreover, combinations may contain graded calls that are not graded into each other during the sequence, as seen in banded mongoose (Mungos mungo) lost sequences that contain both close calls and lost calls, which are two distinct graded calls (Jansen, 2013). Discrete mixed call combinations are composed of several discrete call types with no intermediate forms. For example, male Túngara frogs (Physalaemus pustulosus) produce calls composed of two distinct components, a whine

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73 followed by up to six chucks to attract females (Ryan, 1980). In primates, female Diana 74 monkeys (Cercopithecus diana) produce several social calls, used to communicate over short 75 distances with other group members in non-predatory contexts, in combinations integrating 76 two distinct call types (Candiotti, Zuberbühler, & Lemasson, 2012). Examples of discrete 77 mixed call combinations include the assembly of functionally referential acoustic units 78 resulting in a new or related meaning, as seen in the alarm call systems of some forest guenon 79 species (putty-nosed monkeys, Cercopithecus nictitans: Arnold & Zuberbühler, 2006; 80 Campbell monkeys, Cercopithecus campbelli: Ouattara, Lemasson, & Zuberbühler, 2009). 81 Recent attention has focused on call combination production in non vocal-learning species. 82 Unlike vocal learning species such as songbirds, hummingbirds, and parrots in birds, and 83 humans, some marine mammals, and bats in mammals (Slater & Janik, 2010), non vocal-84 learners cannot expand their vocal repertoire by learning to produce new sounds. Hence non 85 vocal-learning species could be expected to use call combinations as a means to increase their 86 communicative output (Nowak & Krakauer, 1999; Nowak et al., 1999). Many studies on call 87 combinations in animal communication systems have focused on non-human primates, in 88 particular their alarm or long calls (black-fronted titi monkeys, Callicebus nigrifrons: Cäsar, 89 Byrne, Young, & Zuberbühler, 2012; Bornean orang-utans, *Pongo pygmaeus wurmbii*: 90 Spillmann et al., 2010; Campbell monkeys: Ouattara et al., 2009; putty-nosed monkeys: 91 Arnold & Zuberbühler, 2006; white-handed gibbons, Hylobates lar: Clarke, Reichard, & 92 Zuberbühler, 2006). However, an emerging body of data suggests quieter social calls may 93 represent a suite of calls also open to combinatorial operations (chimpanzees, Pan 94 troglodytes: Crockford & Boesch, 2005; bonobos, Pan paniscus: Clay & Zuberbühler, 2009; 95 red-capped mangabeys, Cercocebus torquatus: Bouchet, Pellier, Blois-Heulin, & Lemasson, 96 2010; Diana monkeys: Candiotti et al., 2012).

It has been hypothesized that, unlike most predation contexts where an immediate change in behaviour in response to a call is adaptive, in the majority of social situations, latency to respond is not necessarily crucial for survival. Therefore both the caller and the receiver should have more time to produce and process longer strings of acoustic units in social contexts (Collier, Bickel, van Schaik, Manser, & Townsend, 2014). Moreover, social contexts can involve a highly variable range of behaviours and, unlike predation contexts, they can be associated with both positive and negative emotions. Thus, interactions during social contexts may place additional demands on the communication system that could promote combinatoriality. Data from primates seem to support this (Bouchet et al., 2010; Candiotti et al., 2012; Clay & Zuberbühler, 2009; Crockford & Boesch, 2005), and some non-primate species have also been described as producing call combinations in non-predation contexts (banded mongooses: Jansen, Cant, & Manser, 2012; corncrakes: Rek, 2013; chestnutcrowned babblers, *Pomatostomus ruficeps*: Engesser et al., 2015). However, a systematic documentation of the presence and extent of combinatorial communication within a species repertoire is rarely undertaken (but see Crockford & Boesch, 2005 for a study on wild chimpanzees and Bouchet et al., 2010 for a study on captive red-capped mangabeys). Quantifying the extent and use of combinations within a species' communication system is key to understanding both the diversity of combinations produced in animal communication, and the extent to which they result from different combinatorial production mechanisms. Furthermore, elucidating the variance in distribution of combination types between social and predation contexts in different species could shed light on interspecies differences and subsequently on the contexts promoting communicative complexity. This could ultimately lead to a better understanding of the factors influencing the evolution of combinatoriality more generally.

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Some animal calls have been termed functionally referential due to their high context specificity and link to an external object or event (Macedonia & Evans, 1993), while other calls seem to mainly reflect the animal's internal state and are referred to as motivational/emotional calls (Darwin, 1872; Morton, 1977). An animal's internal state includes both motivation, which is the behavioural state the animal experiences adjusted to its external environment and internal physiological state, and emotion, a short but intense affective reaction to a stimulus which can be measured along two dimensions: arousal (high or low) and valence (positive or negative) (Briefer, 2012). It is now recognised that the same call can encode both types of information, functional reference and internal state (Manser, Seyfarth, & Cheney, 2002). Given that call combinations are built from several different calls, the combinations themselves have the potential to carry similar types of information, pertaining to the internal state or external event experienced by the signaller. Furthermore, as they comprise several calls, combinations could also inform receivers on mixed motivations/emotions, more than one external event, or even combine the two types of information expressing both the caller's internal state and an external event. Here, we aimed to test the hypothesis that social contexts promote the production of call combinations in animal communication through investigating the combinatorial vocal behaviour of meerkats. In line with previous work in primates showing broad usage of call combinations in social situations, we expected call combinations to be widely used in social situations. Furthermore, if social contexts represent an additional relevant pressure favourable to the production of call combinations, we would expect meerkats to produce at least the same combinatorial structures with the same relative frequency, in social as in predation contexts. Meerkats (Suricata suricatta) are a highly social species of cooperative breeding mongoose, living in groups of 3 to 50 individuals (Clutton-Brock et al., 2006), with a well-studied vocal

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repertoire, making them an ideal species in which to explore the extent of call combination production and usage. They possess a rich vocal repertoire consisting of more than 30 discrete and graded call types (see supplementary material; Manser, 1998; Manser et al., 2014). Meerkat call combinations have already been documented in predation contexts (Manser, 2001; Manser, 2009). They produce unlimited repetitions of the same alarm call type such as barks (Manser et al., 2014; Townsend, Charlton, & Manser, 2014). Meerkats also produce graded mixed call combinations in which the aerial or terrestrial alarm calls grade in urgency (Manser, Bell, & Fletcher, 2001). Finally, they emit discrete mixed call combinations consisting of terrestrial predator alarm calls and 'animal moving' alarm calls (Manser, 2009; Manser et al., 2014). However, little is known about meerkats' social call combinations. We therefore established a repertoire of meerkat call combinations produced specifically in social contexts. We analysed in which behavioural contexts call combination types were produced and how context specific they were. Furthermore, to assess if there were systematic differences in composition of the structurally more variable call combinations between contexts, we noted what type the first call was, the proportions of their different component call types and their context specificity.

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# **MATERIAL & METHODS**

Study Site and Animals

Long term observational data from the Kalahari Meerkat Project (KMP) collected between 1995 and 2014 has been the basis for identifying the different types of vocal combinations in meerkats. An observer (KC) collected systematic data for this study between December 2013 and February 2014. The KMP is located in the South African Kalahari near Van Zylsrus (26°58'S, 21°49'E) (for more details about the habitat and climate of the study site see

Clutton-Brock et al., 1998). All meerkats were habituated to human observers to the extent that they allowed detailed observations and recordings within 0.5-3m. All individuals were tagged with subcutaneous transponders as part of the long term data collection of the KMP and marked with a unique combination of dye-marks for identification in the field (Jordan, Cherry, & Manser, 2007).

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# Recordings and Combination Analysis

We systematically recorded the vocal combinations produced by 47 adult meerkats over one year of age (17 females, 30 males) residing in eight different groups. Ten minute focal recordings (Altmann, 1974) were made using a portable recorder (Roland R-26, Roland Corporation, Hamamatsu, Japan) attached to a directional microphone (Sennheiser ME66/K6, Sennheiser Electronic Corp., Old Lyme, CT, USA) (sampling frequency 44.1 kHz, 16 bits). Comments on the meerkats' behaviour were recorded simultaneously onto the second channel. The focal recordings took place in the morning, between the times when meerkats emerged from the sleeping burrow and when they started to rest during the hottest part of the day and again in the afternoon, from when they resumed foraging until they went back into their sleeping burrow in the evening. These were the periods of the day when the meerkats were the most active, socially and vocally. On average 60 minutes of usable recordings were obtained each day (range: 10 – 130min). The subject's behaviour was classed as belonging to one of eight categories which include the majority of behaviours meerkats perform on a daily basis: relaxed, sunning, babysitting, digging, moving, vigilance, aggression or submission (for definitions see Table 1). In an attempt to document all meerkats' social call combinations, we included 'food

In an attempt to document all meerkats' social call combinations, we included 'food aggression call sequences' in our descriptions of meerkat call combinations, despite not

recording any during the two month focal observation period. This absence of food aggression call sequences was potentially due to the high rainfall, and therefore high food availability, during this short study period. Descriptions of this combination were based on spectrograms from our long term recording database. In particular, we used food aggression sequences elicited through food presentation experiments where a focal meerkat was fed a scorpion and its vocalisations were recorded from a close distance. These calls were, however, only used in a descriptive way and were not included in the quantitative analysis. Praat software (www.praat.org) was used to visualise and categorise the call combinations recorded. Systematically and objectively defining call combinations in animal communication is problematic and many previous studies lack a quantitative approach (Kershenbaum et al., 2014). In line with Crockford and Boesch (2005), who documented the repertoire of social call combinations in chimpanzees, we defined a call combination as a series of two or more calls that was clearly separated from the preceding and following calls by a longer silence than those separating the calls within the combination. These combinations could easily be distinguished by ear and the time separating two calls within a combination was never longer than 1sec and often, depending on the length of the discrete call types comprising the combination, much shorter, in the order of 0.01sec. Based on a randomly selected subset of recordings (amounting to 4.5 hours of recording), mean (±SE) silence duration between two calls within a combination was 0.05±0.003sec (min=0, max=0.36), whereas the mean duration of a silence between two individual calls was 9.6±0.6sec (min=0.03, max=328) (Appendix Figure A1). Contrary to Crockford and Boesch (2005), however, we also included sequences of the same call type as call combinations as we aimed to document all combinations, including repetitions. The combinations and their individual component calls were identified by visual and audio inspection of the corresponding spectrograms. Additionally, two naïve observers independently classified a

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randomly selected subset of the call combinations (N=560 combinations, 10% of total dataset). Observer reliability was calculated using Cohen's Kappa coefficients, which indicated substantial agreement ( $\kappa$ =0.74 and  $\kappa$ =0.80) (Landis & Koch, 1977). Combinations were then classified according to their component calls: for example, combinations composed of only one call type were identified as repetitions whereas combinations containing several different call types were categorised as mixed combinations. The context of emission of a combination was determined by the behaviour of the caller at that time. To control for a potentially varying number of combinations emitted in each context, we then looked at the proportions of each combination for each behavioural context. For combinations of three or more calls comprising at least two call types, named 'long sequences', the length of the combination in number of calls and the proportions of the different call types in each combination were noted. Given that the first call-type of a sequence may encode initial information or function to alert the receiver, as seems to be the case in certain guenon species where the first call of a sequence functions as an attention getter (putty-nosed monkey: Arnold & Zuberbühler, 2012), we also specifically noted the first call of the sequence.

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# Statistical Analysis

All statistical analyses were carried out using R version 3.2.1 (R Core Team, 2015) and the packages lme4 (Bates, Maechler, Bolker & Walker, 2015) and asbio (Aho, 2016). We compared the production rate of call combinations in different continuous behavioural contexts (babysitting, digging, sentinel and sunning) using a Mack-Skillings test. The Mack-Skillings test is a Friedman-type statistic that can be used for block designs with missing data (Chatfield & Mander, 2009). When a significant result was found, we carried out pairwise

243 Wilcoxon tests and corrected *P*-values for multiple testing using false discovery rate

244 (Benjamini & Hochberg, 1995).

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random effect (Harrison, 2014).

In order to determine if the proportions of each combination type varied in relation to behavioural context we ran a Generalized Linear Mixed Model (GLMM; Baayen, 2008) with a binomial family and a logit link function for each combination type produced in more than one context (8 GLMMs, data obtained from 45 individuals belonging to 8 groups). Context was fitted as fixed effect and individual nested within group as random effect to control for potential group or individual differences. Random slopes for context (Schielzeth & Forstmeier, 2009) were specified for both random effects: group and individual. Additionally, as we had several recordings from the same individual in the same context, we controlled for pseudo-replication by fitting an observation level random term as random effect. This random effect also controlled for over-dispersion (Harrison, 2014) which is sometimes an issue with such models. We verified the dispersion of the models using overdisp fun from glmm funs.R (Bolker et al., 2009). P-values close to 1 indicated that models were not over-dispersed. A GLMM of the same format was run for each call type produced in a long sequence (5 GLMMs, N individuals=28, N groups=7) to analyse the proportions of the different call types within the long sequences, again depending on context. Random intercept GLMMs were run for each call type initiating long sequences (4 GLMMs, N individuals=28, N groups=7), to determine if call type initiating long sequences varied with context. A GLMM (N individuals=28, N groups=7) with a Poisson family and a log link function was used to analyse the number of calls in the long sequence. Context was fitted as fixed effect with random slopes and individual nested within group as random effect. We controlled for over-dispersion of the data by creating an observation level random term that was fitted as

For all models overall *P*-values were obtained using likelihood ratio tests, in which the full model was compared to a null model containing only the random factors, slopes and intercept. For pairwise comparisons of contexts, *P*-values were obtained from the coefficients of the model summary. GLMMs were relevelled to obtain *P*-values for all pairwise comparisons. When multiple GLMMs were carried out on the same dataset, *P*-values were adjusted to correct for multiple testing using false discovery rate (Benjamini & Hochberg, 1995).

In order to check whether any one individual strongly affected our results, we re-ran each model, removing sequentially each individual from the dataset, and compared the coefficients to those obtained from the model with the full dataset (Hedwig, Mundry, Robbins, & Boesch, 2014). Where our findings were significant, we observed little variation in the coefficients of the models when an individual was removed from the model. However, there were some appreciable differences in coefficients related to some of our non-significant results, indicating that effects could be stronger than suggested by our models (Hedwig et al., 2014).

#### Ethical Note

All data collection adhered to ASAB guidelines. This study was purely observational, with no invasive or experimental procedures conducted as part of it. The study population was habituated to observers following them at a close distance all day and to microphones. Care was taken not to disturb the meerkats' daily routine during observations. All research was conducted under the permission of the ethical committee of Pretoria University and the Northern Cape Conservation Service, South Africa (Permit number: EC011-10).

# **RESULTS**

Over a period of two months we obtained more than 2700 minutes (around forty five hours) of focal recordings (mean $\pm$ SE=57 $\pm$ 4 (range 10 to 117) minutes of observation per meerkat). Forty-five out of the forty-seven meerkats produced call combinations (122 $\pm$ 20 (range 2 to 571) combinations recorded per meerkat). On average the meerkats that combined calls emitted 2.6 $\pm$ 0.7 (range 0.1 to 10.2) combinations per minute of recording. Rate of production of call combinations varied between the different continuous behavioural contexts that typically last more than a few seconds (Mack-Skillings, MS<sub>46</sub> test statistic=87, P<0.001; Figure 2). Subjects produced call combinations at lower rates while digging (0.2 $\pm$ 0.1 combinations/min) than while sunning (3.6 $\pm$ 0.8 combinations/min), babysitting (5.0 $\pm$ 1.4 combinations/min.) or while on sentinel (7.0 $\pm$ 1.2 combinations/min) (pairwise Wilcoxon test, respectively P<0.001, P<0.001 and P<0.001). They also produced combinations at significantly lower rates while sunning than during sentinel behaviour (Wilcoxon test, P=0.04). There were no significant differences in combination production rates between sunning and babysitting, and between babysitting and sentinel behaviour (Wilcoxon test, respectively P=0.33 and P=0.34).

# Meerkat Call Combination Types and Contexts of Production

Based on our long-term adlib vocal data and focal recordings over the two-month study period, meerkats produced twelve different types of combinations from seven discrete call types (see Figure 1). All four classes, belonging to both categories of combination were represented: unlimited and finite repetitions and graded and discrete mixed call combinations (see Table 2). The call combinations differed in how frequently they were recorded during the two-month focal observation period, with 'two short calls' (hereafter sc.2) being recorded the most often (3361 times) whereas 'chatter call sequences' were recorded the least (9

times), and no food aggression call sequences were recorded during the same period (see
 supplementary material). The discrete call types that were recorded as part of a call
 combination are described in Figure 3.

babysitting, digging, moving, relaxed, submission, sunning and vigilance (see Table 1). Four call combinations, composed of context-specific calls, were produced exclusively in one behavioural context. 'Moving call sequences' were only emitted in the moving context, chatter call sequences were emitted only in the aggression context and 'submission call sequences' only in the submission context. Additionally, food aggression call sequences were only obtained during food competition events.

Focal subjects produced call combinations in all eight of the predefined contexts: aggression,

The eight other call combination types were produced in more than one behavioural context. Whilst longer 'short call sequences' (sc.>4), 'mixed short call sequences' (sc+) and 'quasi-combinations' (qc) were never produced in the digging context the remaining call combinations (sc.2, 'three short calls' (sc.3), 'four short calls' (sc.4), long sequences and 'didrrr calls') were produced in all contexts. The proportions of specific call combinations emitted in relation to the total number of call combinations produced varied with context: this was the case for sc.2 (GLMM,  $\chi^2_{5}$ =19, P=0.002,  $P_{adj}$ =0.005), sc.4 (GLMM,  $\chi^2_{2}$ =11, P=0.003,  $P_{adj}$ =0.006), di-drrr calls (GLMM,  $\chi^2_{5}$ =19, P=0.002,  $P_{adj}$ =0.005) and long sequences (GLMM,  $\chi^2_{3}$ =17, P=0.001,  $P_{adj}$ =0.005) (see Table 3 and Figure 4). Meerkats produced a lower proportion of sc.2 and a higher proportion of long sequences in the moving context than in any other context (see Table 3). Sc.2, the most frequently produced combination, was given in higher proportions in the vigilance and sunning contexts. Di-drrr combinations were

produced in the lowest proportions in the vigilance contexts.

340 Long sequences, whose component calls include 'short calls' (sc), qc, di-drrr calls, 'lead 341 calls' and 'moving calls', were produced by meerkats in six out of the eight contexts, with the 342 majority produced in the moving context (131/194). Of the 194 long sequences produced, few were emitted in the digging and relaxed contexts (recorded 2 and 5 times respectively) 343 344 and so these contexts were excluded from the analysis. Five other sequences were not of sufficient quality to identify the calls composing them. In total 182 long sequences were of 345 346 high enough quality to include in the analysis. No long sequences were produced in the 347 aggression and submission contexts The length (number of calls) of long sequences varied with the context (GLMM,  $\chi^2_3=9$ , 348 349 P=0.035) (see Figure 5). Long sequences contained the most calls when produced in moving 350 contexts ( $10\pm0.6$ ) and the fewest calls when produced in babysitting contexts ( $5.3\pm0.6$ ). We 351 found no significant difference in number of calls in the long sequences between sunning  $(7.9\pm1.4)$  and vigilance  $(6.6\pm0.9)$  contexts. 352 353 Investigating the call types that initiated long sequences, we found that only the proportion of long sequences starting with a di-drrr call varied with context (GLMM,  $\chi^2 = 11$ , P = 0.004, 354  $P_{\text{adi}}=0.02$ ). Specifically, there was a higher proportion of long sequences initiated by a di-drrr 355 356 call in the babysitting context (14/28) than in the other contexts. A lower proportion of long 357 sequences started with a di-drrr call in the moving and vigilance contexts (respectively 358 24/126 and 1/18), and no long sequences started with a di-drrr call in the sunning context 359 (0/10). The proportion of long sequences starting with the other call types did not vary between contexts (GLMM, sc:  $\chi^2_3=4$ , P=0.4,  $p_{adj}=0.3$ ; lead calls:  $\chi^2_2=2$ , P=0.4,  $P_{adj}=0.4$ ; 360 moving calls:  $\chi^2_3=4$ , P=0.3,  $P_{adj}=0.4$ ; qc:  $\chi^2_3=4$ , P=0.2,  $P_{adj}=0.4$ ). 361

There was a trend for the proportions of lead calls within a long sequence to vary with context (GLMM,  $\chi^2_2=8$ , P=0.014,  $P_{adj}=0.070$ ) (see Figure 6). Long sequences produced in the moving context consisted of a lower proportion of sc than the sunning contexts. We found no significant difference in the proportion of the other call types in long sequences between contexts (GLMM, di-drrr:  $\chi^2_3=6$ , P=0.12,  $P_{adj}=0.20$ ; sc:  $\chi^2_3=6$ , P=0.09,  $P_{adj}=0.20$ ; moving calls:  $\chi^2_3=1$ , P=0.70,  $P_{adj}=0.70$ ; qc:  $\chi^2_3=3$ , P=0.45,  $P_{adj}=0.57$ ).

# DISCUSSION

In this study we quantified the production of call combinations by wild meerkats in social contexts in order to test the prediction that call combinations should be widespread in such contexts. We first discuss call combinations as part of social communication. Secondly, we consider possible mechanisms underlying call combination production. Thirdly, we compare call combination use in social and predation contexts. Finally, we discuss potential implications of this study for research into human language evolution.

# Call Combinations as part of Social Communication

In this study, we have shown that meerkats produce twelve different types of call combinations from seven discrete call types and these call combinations were emitted across all of the eight main social contexts. This frequent and broad occurrence implies that call combinations represent a non-negligible part of social communication for this species. These results fall in line with previous research in some primate species for which high rates of call combination production overall were also shown. For example 49% of chimpanzee calls (Crockford & Boesch, 2005) and 38% of wedge-capped capuchin (*Cebus olivaceus*) calls were produced in combinations (Robinson, 1984).

We identified call combinations produced in social contexts that fitted the definitions of the two main categories of combination: repetitions of the same call type and mixed call combinations, comprising several discrete call types. Repetitions, containing only one call type, differed from one another either in terms of the call type repeated (e.g. chatter calls vs short calls) or by the number of repetitions (e.g. within short call sequences: sc.2 vs sc.3). Mixed call combinations likewise differed in component call types (for example, di-drrr calls comprised two distinct call types, a short call and a wheek call whereas call sequences in the context of food competition comprised various gradations of aggression calls). Mixed call combinations also showed more variation within a combination type, for example individual long sequences differed in component calls, number of calls and call order. Additionally, some long sequences seemed to have a higher structural complexity with combinations embedded inside other combinations, such as long sequences including di-drrr calls, which are themselves mixed combinations (see above). Structurally complex combinations that include other combinations have been observed in the closely related banded mongoose. Specifically, banded mongooses can combine their close calls with distinct, additional calls producing new combinations in three contexts: leading the group, lost from the group or in excitement at rain or wet ground (Jansen, 2013). The close calls themselves are composed of two acoustic segments, an initial noisy segment and a second harmonic segment. Acoustic analysis has shown that the initial noisy part carries information about the caller's identity whereas the second harmonic part carries information about the caller's activity (Jansen et al., 2012). Hence, in these combinations, banded mongoose could potentially indicate the caller's identity, its activity and an external event such as the beginning of rain. However, so far it has not been tested what information receivers actually extract from such a combination. In line with this, we have yet to investigate what information receivers extract from call combinations, and in particular from

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long sequences, in meerkats. One possibility is that more complex combinatorial structures encode a greater variety of information. However, in some cases, the variation in complexity itself may carry information, regarding, for example, the caller's quality, as is the case in European starling (*Sturnus vulgaris*) song (Mountjoy & Lemon, 1991).

The fact that combinations of similar structural complexity are found in two closely related mongoose species could indicate that combinatorial tendency per se is a shared trait inherited through common descent. However, these species also share similarities in their social structure, both being group living, cooperative breeders, albeit with meerkats having a more despotic hierarchy (Manser et al., 2014). This social structure may have favoured the production of call combinations in these species given that it has been hypothesized that new inferential processes evolve when communication is driven by more cooperative motives (Vygotsky, 1980 cited by Pika & Bugnyar, 2011). Comparative analyses of the communication systems of species from different taxa and/or social systems are needed to shed light on the evolution of communicative complexity and combinatoriality which could in turn help disentangle these two alternative possibilities.

# Mechanisms of Call Combination Production

Through systematically documenting the structural variance underlying sequences of calls, our work suggests there may be two primary combinatorial operations that guide meerkat call combination production. The first is where each individual call within the combination is associated with the caller's internal state and the caller emits these calls sequentially as the situation unfolds. The resulting call combinations could therefore reflect the persistence of a single internal state of the caller, as is probably the case for unlimited repetitions such as meerkat submission or chatter call sequences. Alternatively, the call combinations could

reflect the caller's changing internal states, potentially induced by changes in external events (e.g. approach of a rival), which can emerge in two ways. Firstly, the change in internal state could be due to variations in emotion, in particular arousal. For example, in graded food aggression call sequences, the individual calls can reflect varying levels of aggression, where the motivation stays the same, but the arousal changes. Secondly, the change in internal state leading to the production of a call combination could be linked to varying motivations. In meerkats, long sequences may be an example of such a combination with the different component calls reflecting different motivations, though this remains to be tested. The production of combinations linked to differing motivations has been reported in several primate species (Cleveland & Snowdon, 1982; Robinson, 1984; Crockford & Boesch, 2005; Rothacher, 2013) where combinations are produced in contexts intermediate to those of the individual component calls. The production of such call combinations that might depend on internal state could be argued to rely on relatively simple proximate mechanisms and our work suggests that changes in arousal could lead to the use of graded mixed call combinations whereas changes in motivation can lead to the use of discrete mixed call combinations. The second combinatorial operation by which other call combinations seem to be produced is less flexible. In these combinations the component calls cannot be freely combined, they always appear in a stereotyped order and/or number of occurrences. One example of such a combination from our data set would be the di-drrr calls which always consisted of a short call followed by a wheek call, with call order and call number remaining unchanged for all of the 530 exemplars recorded. Such call combinations do not seem to be the result of changing

or conflicting internal states but may reflect a particular consistent internal state or external

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To determine which of these two mechanisms is used for the production of a combination, callers could be observed in situations leading either to i) varying levels of arousal or to ii) several motivations. One could then record if the individual component calls reflect the immediate arousal or the motivational state of the caller or, rather, if they are always emitted in a stereotyped order. Documenting the proximate mechanisms by which calls come to be associated with other calls is particularly important as it will lead to a better understanding of the evolutionary scenario accompanying the emergence of combinatoriality in general.

# Social vs Predation Contexts

When analysing social call combinations, we noticed certain similarities with call combinations produced in predatory contexts. Specifically, meerkats emit three of the combination classes in both contexts: unlimited repetitions, graded and discrete mixed call combinations. Unlimited repetitions in social contexts, such as submission or chatter call sequences, seem to have the same function as those produced in predation contexts, such as bark call sequences (Manser et al., 2014; Townsend et al., 2014): to indicate the persistence of a state either internal or external of the signaller. In the case of graded mixed call combinations, graded alarm call sequences seem to be produced in a similar way to food aggression call sequences with the variation in structure of the calls reflecting a change in the caller's arousal, here in terms of alertness or aggressiveness respectively. However, the discrete mixed call combinations in the social and predation situations seem to present some differences. This type of combination in social contexts seems to either be produced as a single unit such as the di-drrr call or perhaps, in the case of the long sequences, may reflect the caller's multiple or conflicted motivations. On the other hand, in the terrestrial-animal moving sequence meerkats produce sequences of terrestrial alarm calls and animal moving

calls, normally given to moving animals regardless of whether they are dangerous or not, in response to moving terrestrial predators (Manser, 2009; Manser et al., 2014). This sequence combines two functionally referential calls to produce a new meaning derived from the meaning of the component calls. It is possible to compare this combination with a simple two-expression package akin to those seen in early developing languages or when children initiate their syntactic development (Hurford, 2011). This sequence could therefore be considered as a more syntax-like combination, where syntax is the level of combinatoriality in which meaningful morphemes or words are combined into larger structures such as sentences in human language (de Boer, Sandler, & Kirby, 2012). Lastly, finite repetitions seem to be a class of combinations specific to social contexts in meerkats as they are not found in predation contexts (Manser et al., 2014). Thus, whilst meerkats do seem to produce more classes of combinations in social contexts as opposed to predation contexts, at present, they do not seem to produce meaningful syntax-like combinations in the former. Meerkat call combinations in the social context could be argued to surpass those in predatory contexts in variety, both in classes and complexity. This would seem to support the hypothesis that social contexts are important in selecting for combinations because of the variety of behaviours and interactions they involve that are coordinated by vocalisations (Collier et al., 2014). In line with this, previous modelling work has indicated that when behaviours and interactions outweigh the number of discrete vocalisations in the species vocal repertoire one solution to this pressure involves the concatenation of calls (Nowak et al., 2000). The extent to which social and ecological pressures contribute to promoting combinatoriality requires further work, though comparisons with other species, particularly in terms of the forms sequences take in social and ecological contexts, is one valuable way to do this.

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Despite apparent differences in terms of types and complexity of call combinations emitted in social and predation contexts, meerkats seem to produce an arguably more syntax-like combination in the predation but not social context. Other well-known examples of syntaxlike call combinations, such as Campbell monkey alarm calls (Ouattara et al., 2009), are also produced in a predation context. It therefore appears that certain combinations in predation contexts seem to be, at least on the surface level, more similar to human forms of combinatoriality than those produced in social situations. Given the survival benefits associated with efficiently transferring more specific information in dangerous contexts, it could be hypothesised that alarm contexts may select for less ambiguous (and hence referential) sequences. Deconstructing the meaning of the combination as a function of the meaning of the individual calls may then be easier compared to combinations composed of non-referential calls which could, in turn, lead to a bias in identifying syntax-like combinations in predation as opposed to social contexts. Whilst these considerations should be taken into account when investigating the form and function of animal call combinations, our data indicates that both social and predation pressures play important roles in the emergence of cognitive abilities facilitating the production and perception of call combinations.

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# Human Language Evolution

Comparative studies looking at call combinations in animal communication systems are one method of exploring the evolution of language and in particular its combinatorial layers, phonology and syntax. These forms of articulation have received renewed empirical interest over the years given that they are fundamental in facilitating the creation of a large lexicon out of relatively few sounds: a central feature of human language (Hockett, 1960; Hurford,

2008; Hurford, 2011). An increased focus on call combinations, particularly in social contexts may reveal combinations to be more widespread in animal vocal communication than previously documented. However, in meerkats it is worth noting that the production of at least some of these combinations seem to result from simple mechanisms far removed from the complexity of human syntax. Whilst in meerkats, combinations in predation contexts might be more syntax-like and therefore afford better opportunities for comparative research, studying more "primitive" social combinations could also help better understand, at the proximate level, how combinations emerge in the first place.

# Conclusion

In conclusion, meerkats frequently use call combinations across a wide variety of social contexts. Although several classes of combination are found in both social and predation contexts, there seems to be more classes of combinations, some of which present a higher complexity, in the social situations. Whilst animal call combinations have been often described in alarm contexts, our study on meerkats indicates that social contexts are at least as important for the study of call combinations in animal communication as predation contexts. Future research needs to complement our findings by investigating exactly how receivers perceive social call combinations in meerkats in order to fully identify the function of call combinations in animal communication.

limited number of signals. Despite its importance, particularly in the case of vocal communication, little is known about the pressures that select for combinatoriality. Further research on call combinations between and across species and contexts is necessary to shed more light on how and why combinatoriality emerged.

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Figure 1: Spectrograms of the different call combinations produced by meerkats. A: unlimited repetitions, including a) submission call sequence, b) chatter call sequence, c) moving call sequence, and d) short call sequence. B: finite repetitions, including e) two short calls, f) three short calls, g) four short calls, and h) quasi-combination. C: graded call combinations, including i) food aggression call sequence. D: discrete mixed call combinations, including j) di-drrr, k) mixed short call sequence and l) long sequence. The time and frequency scales apply to all spectrograms.

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580	Figure 2: Mean production rate of call combinations in relation to continuous behavioural context.
581	Significance: *: P<0.05; ***: P<0.001.
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583	Figure 3: Description of the main call types comprising meerkat call combinations and the contexts
584	they are produced in. The time and frequency scales apply to all spectrograms.
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587	Figure 4: Proportions of the eleven different call combination types collected in the two-month field
588	period in the eight different behavioural contexts. ls: long sequence; qc: quasi-combination; sc.>4:
589	short call sequence; sc.2: two short calls; sc.3: three short calls; sc.4: four short calls; sc+: mixed short
590	call sequence. N indicates the number of combinations recorded in a context
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593	Figure 5: Length of long sequences, in number of component calls, produced in different behavioural
594	contexts. Boxplot shows the median, interquartiles and range.
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597	Figure 6: Mean proportions of the different call types composing long sequences produced in different
598	behavioural contexts.
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Figure A1: Duration of silence between calls within a combination and between combinations or individual calls, measured for a randomly selected subset of sound files amounting to 4.5 hours of recordings.

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Table 1: Description of the behavioural contexts in which the meerkats produced call combinations.

Context	Description
Relaxed	Includes huddling, where several meerkats gather together in a tight group; autogrooming and allogrooming (delBarco-Trillo et al., 2016); contact lying (Habicher, 2009)
Sunning (or sunbathing)	Sitting or standing on hind legs in the sun, often in close proximity to the sleeping burrow (Habicher, 2009)
Babysitting	Remaining at the sleeping burrow with pups while the rest of the group forages (Clutton-Brock et al., 1998)
Digging	Includes foraging for food (Doolan & Macdonald, 1996) and renovating sleeping burrows (Manser & Bell, 2004)
Moving	Walking or running (Habicher, 2009)
Vigilance	Includes sentinel behaviour and scanning the environment for predators while on all fours, sitting or standing on hind legs (delBarco-Trillo et al., 2016)
Aggression	Food competition, displacement and fights (delBarco-Trillo et al., 2016)
Submission	Approaching a dominant individual in a crouched position (delBarco-Trillo et al., 2016)

Table 2: The different types of combinations produced by meerkats in non-urgent contexts.

Category	Class	Combination	Description
Repetitions	Unlimited	Submission call sequence	Repetition of submission calls of undetermined length
		Chatter call sequence	Repetition of chatter calls of undetermined length
		Moving call sequence	Repetition of moving calls of undetermined length
		Short call sequence (sc.>4)	Repetition of more than 4 short calls
	Finite	2 short calls (sc.2)	Repetition of 2 short calls
		3 short calls (sc.3)	Repetition of 3 short calls
		4 short calls (sc.4)	Repetition of 4 short calls
		Quasi-combination (qc)	Repetition of 2 short calls with no silence between them
Mixed call combinations	Graded	Food aggression sequence	Two acoustically different aggression calls grading into each other with intermediate calls, likely related to low and high arousal
	Discrete	Di-drrr calls	A short call followed by a longer wheek call, potentially with modulation
		Mixed short call sequence (sc+)	Sequence containing a short call and one or two quasi-combinations or di-drrrs
		Long sequence	Sequence containing 3 or more calls and at least two different call types

Table 3: Comparison of the proportions of call combination types produced in different behavioural contexts.

		Sunning	Relaxed	Babysitting	Digging	Moving	Vigilance
Sunning	sc.2		↑ than relaxed; P<0.001	↑ than babysitting; P<0.001	↑ than digging; P<0.001	↑ than moving; P<0.001	$\downarrow$ than vigilance; P<0.001
	sc.3		NS overall	NS overall	NS overall	NS overall	NS overall
	sc.4		_	NS; P=0.451	_	_	NS; P=0.294
	sc.>4		_	NS overall	_	NS overall	NS overall
	sc+		_	NS overall	_		NS overall
	qc		_	NS overall	_		NS overall
	di-drrr		NS; P=0.418	$\downarrow$ than babysitting; P=0.043	$\downarrow$ than digging; P<0.001	$\downarrow$ than moving; P<0.001	NS; P=0.483
	ls		_	NS; P=0.198	_	$\downarrow$ than moving; P<0.001	NS; P=0.198
Relaxed	on 3	than cumping D-0.022		NC. D_0 620	NS; P=0.638	A than maying, B-0 001	L than vigilance, P-0 051
Relaxeu	sc.2	↓ than sunning; P=0.033  NS as a sell.		NS; P=0.638	·	↑ than moving; P=0.001	↓ than vigilance; P=0.051
	sc.3	NS overall		NS overall	NS overall	NS overall	NS overall
	sc.4	_		_	_	_	_
	sc.>4	_		_	_	<del></del>	_
	sc+	_		_	_	_	
	qc	_		_	_	_	<del></del>
	di-drrr	NS; P=0.418		NS; P=0.199	NS; P=0.138	NS; P=0.138	NS; P=0.330
	ls	_		_	_	_	_
	sc.2	↓ than sunning; P=0.028	NS; P=0.638		NS; P=0.414	↑ than moving; P<0.001	↓ than vigilance; P=0.075
Baby -sitting	sc.3	NS overall	NS overall		NS overall	NS overall	NS overall
J	sc.4	NS; P=0.451	_		_		NS; P=0.294
	sc.>4	NS overall	_		_	NS overall	NS overall
	sc+	NS overall	_		_	NS overall	NS overall
	qc	NS overall	_		_	_	NS overall
	di-drrr	↑ than sunning; P=0.043	NS; P=0.199		NS; P=0.145	NS; P=0.138	NS; P=0.106
	ls	NS; P=0.207	_		_	↓ than moving; P=0.025	↑ than vigilance; P=0.046
		•					

		Sunning	Relaxed	Babysitting	Digging	Moving	Vigilance
Digging	sc.2	$\downarrow$ than sunning; P=0.012	NS; P=0.563	NS; P=0.293		↑ than moving; P=0.022	↓ than vigilance; P=0.012
	sc.3	NS overall	NS overall	NS overall		NS overall	NS overall
	sc.4	_	_	_		_	_
	sc.>4	_	_	_		_	_
	sc+	_	_	_		_	_
	qc	_	_			_	
	di-drrr	↑ than sunning; P<0.001	NS; P=0.138	NS; P=0.145		NS; P=0.760	↑ than vigilance; P=0.001
	ls	_	_	_		_	_
Moving	sc.2	$\downarrow$ than sunning; P<0.001	$\downarrow$ than relaxed; P=0.001	$\downarrow$ than babysitting; P<0.001	$\downarrow$ than digging; P=0.028		$\downarrow$ than vigilance; P<0.001
	sc.3	NS overall	NS overall	NS overall	NS overall		NS overall
	sc.4	_	_	_	_		_
	sc.>4	NS overall	_	NS overall	_		NS overall
	SC+	_	_	_	_		_
	qc	NS overall	_	_	_		_
	di-drrr	_	NS; P=0.138	NS; P=0.139	NS; P=0.537		↑ than vigilance; P<0.001
	ls	↑ than sunning; P<0.001	_	↑ than babysitting; P=0.025	_		↑ than vigilance; P=0.001
Vigilance	sc.2	NS; P=0.945	↑ than relaxed; P=0.052	NS; P=0.193	↑ than digging; P=0.021	↑ than moving; P<0.001	
	sc.3	NS overall	NS overall	NS overall	NS overall	NS overall	
	sc.4	NS; P=0.294	_	NS; P=0.294	_	NS; P=0.746	
	sc.>4	NS overall	_	NS overall	_	NS overall	
	sc+	NS overall	_	NS overall	_	NS overall	
	qc	NS overall	_	NS overall	_	NS overall	
	di-drrr	NS; P=0.483	NS; P=0.317	NS; P=0.106	$\downarrow$ than digging; P=0.001	$\downarrow$ than moving; P<0.001	
	ls	NS; P=0.192	_	$\downarrow$ than babysitting; P=0.046	_	$\downarrow$ than moving; P=0.001	

<sup>↑:</sup> higher proportion; ↓: lower proportion; NS: Non-significant difference; —: combination type not produced in this context. *P*-values adjusted using false discovery rate. sc.2: two short calls; sc.3: three short calls; sc.4: four short calls; sc.>4: short call sequence; sc+: mixed short call sequence; qc: quasi-combinations; ls: long sequence.

Table A1: Meerkat calls and the contexts they are produced in according to Manser (1998).

Context	Call	Single/Multiple element	Discrete/Graded
	Close call	Single	Discrete
	Joining call	Multiple	Discrete
Spatial coordination	Leading call	Single/Multiple	Graded
	Lost call	Single	Discrete
	Moving call	Single/Multiple	Graded
	Aggression call	Single/Multiple	Graded
Conial internation	Chatter call	Multiple	Discrete
Social interaction	Grooming call	Single/Multiple	Discrete
	Submissive call	Multiple	Discrete
Social interaction & sentinel duty	Single note call	Single	Discrete
	Di-drrr call	Multiple	Discrete
	Double note call	Multiple	Discrete
Sentinel duty	Triple note call	Multiple	Discrete
·	Multiple note call	Multiple	Discrete
	Wheek call	Single	Discrete
	Aerial alarm call	Single/Multiple	Graded
	High pitched barking	Single/Multiple	Discrete
	Moderate alarm call	Single/Multiple	Graded
	Panic call	Single	Graded
Alarm call	Recruitment call	Single/Multiple	Graded
	Rolling alarm call	Single	Graded
	Spitting call	Single/Multiple	Discrete
	Terrestrial alarm call	Single/Multiple	Graded
	Worry call	Single/Multiple	Graded
Alarm call & spatial coordination	Barking call	Single/Multiple	Discrete
	Begging call (pup)	Single/Multiple	Graded
	Chatter call (pup)	Single/Multiple	Graded
	Digging call (pup)	Single	Graded
	Eating call (pup)	Single	Graded
C-11 ' 1	Excited call (pup)	Multiple	Graded
Calls given by pups	Joining call (pup)	Multiple	Discrete
	Lost call (pup)	Single	Discrete
	Moving off call (pup)	Multiple	Discrete
	Sleeping call (pup)	Single	Discrete
	Spitting call (pup)	Single/Multiple	Discrete

Following Catchpole & Slater (2003) an element is defined as a continuous trace on a spectrograph.

Table A2: Number of times each combination type was recorded during the two-month study Period.

Combination	Occurrence
Submission call sequence	24
Chatter call sequence	9
Moving call sequence	22
sc.>4	150
sc.2	3361
sc.3	666
sc.4	178
qc	198
Di-drrr	530
Food aggression call sequence	0
sc+	149
Long sequence	195

Table A3: GLMM information.

Model	Data	Levels per fixed effect	Levels per random effect	
	Number of rows	Context	Group	Individual
Binomial GLMMs testing proportion of combinations in relation to context				
sc.2	270	Babysitting Digging Moving Relaxed Sunning Vigilance	8	45
sc.3	270	Babysitting Digging Moving Relaxed Sunning Vigilance	8	45
sc.4	135	Babysitting Sunning Vigilance	8	45
sc.>4	180	Babysitting Moving Sunning Vigilance	8	45
sc.+	135	Babysitting Sunning Vigilance	8	45
qc	135	Babysitting Sunning Vigilance	8	45
di-drrr	270	Babysitting Digging Moving Relaxed Sunning Vigilance	8	45
long sequence	180	Babysitting Moving Sunning Vigilance	8	45

# Binomial GLMMs testing proportions of call types within long sequences in relation to context

sc	182	Babysitting Moving Sunning Vigilance	7	28
qc	182	Babysitting Moving Sunning Vigilance	7	28
di-drrr	182	Babysitting Moving Sunning Vigilance	7	28
lead calls	172	Babysitting Moving Vigilance	7	28
move calls	182	Babysitting Moving Sunning Vigilance	7	28
Binomial GLMMs testing initial call type of long sequences in relation to context				
sc	112	Babysitting Moving Sunning Vigilance	7	28
qc	112	Babysitting Moving Sunning Vigilance	7	28
di-drrr	84	Babysitting Moving Vigilance	7	28
lead calls	84	Babysitting Moving Vigilance	7	28
move calls	112	Babysitting Moving Sunning Vigilance	7	28
Poisson GLMM testing long sequence length in relation to context				
Number of calls	182	Babysitting Moving Sunning Vigilance	7	28