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# Wireless Powered Communication Networks Using Peer Harvesting

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**Abstract**—In this work, we consider a wireless powered communication (WPC) network consisting of one hybrid access point (H-AP) and  $K$  wireless nodes. The H-AP broadcasts wireless energy to nodes in the downlink and receives information from  $K$  nodes abided by TDMA protocol in the uplink. The wireless nodes have energy harvesting (EH) capabilities and can harvest energy from H-AP and other nodes in different assigned time slots. We propose two new schemes for the WPC network that perform energy harvesting among peer nodes. In the first scheme, each wireless node harvests energy from peer nodes transmitting in the previous time slots, while each wireless node harvests energy from all nodes in the second scheme. The maximization of the sum achievable throughput and the minimization of the required harvested energy are studied. An effective heuristic optimization algorithm is proposed to solve them. The contribution of this work includes the proposal of two new peer harvesting schemes, the formulation of two relevant optimizations and their solutions using heuristic optimization algorithm, which has better technical adaptability for solving complicated objective functions. Simulation results demonstrate the effectiveness of the proposed schemes in WPC networks.

**Index Terms**—Energy harvesting, maximization of sum achievable throughput, minimization of required harvested energy, particle swarm optimization, wireless power.

## I. INTRODUCTION

FOR an energy-constrained wireless network, energy harvesting (EH) is a promising technology to prolong the network life. Whether traditional near-field wireless power transfer (WPT) using inductive and resonant coupling or far-field WPT via radiated electromagnetic waves, both of them

draw considerable research interests these years [1][2]. In particular, the far-field WPT is meaningful for wireless powered communication (WPC) networks. A fundamental tradeoff was first studied for simultaneous wireless information and power transfer (SWIPT) in [3][4]. These results aroused the interest of researchers. Subsequently, wireless communication with EH technology was presented in [5][6].

Since then, various perspectives of EH, with different system models or applications, emerged in large numbers. Among these typical research studies, Zhang considered SWIPT problem in multiple-input multiple-output (MIMO) broadcasting system with separated or co-located receiver [7]. For the co-located receiver, the results of time switching and power splitting mode provide some meaningful references for subsequent researches. The SWIPT problem was also studied for a broadband communication system with one multi-antenna base station and passive mobiles [8]. Orthogonal frequency division multiplexing (OFDM) and transmitting beamforming were used for realizing information transmission and wireless power transfer in this paper.

Furthermore, wireless power transfer was investigated based on relay networks [9]-[13]. The maximization of achievable throughput was considered for a relay-assisted WPC system [9]. Energy-harvesting relaying system has taken into account the Nakagami- $m$  fading and interference in [10]. Reference [11] considered a two-way amplify-and-forward OFDM relay networks to realize the SWIPT with time switching mode. A multicell network deployment where the base station of each cell communicates with its cell-edge user with the assistance of an amplify-and-forward relay node was optimized to achieve feasible joint resource allocation [12]. Relaying schemes and deploying antenna numbers were studied in wireless powered MIMO relay networks [13].

Besides, for EH communication networks, Tutuncuoglu and Yener showed the optimum transmission policies, and Yang and Ulukus presented the optimal packet scheduling method [14][15]. Both of their works revealed the storage constraints of the rechargeable batteries should be taken into account in designing efficient transmission strategies. Ju studied a wireless powered communication system using one hybrid access point (H-AP) and a set of users without any energy sources [16]. A similar wireless communication network consisting of a full-duplex H-AP and a set of wireless users with energy harvesting capabilities is considered in [17]. Two optimization problems of sum throughput maximization and total time minimization were characterized for the proposed

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system model. A wireless powered cooperative communication network was considered in [18]. Two types of models, where the wireless nodes move with fixed APs or the APs move with fixed wireless nodes, were studied in [19]. A joint optimal design for multiple-input single-output (MISO) WPC network was proposed in [20]. Che also proposed a co-channel energy and information transfer scheme for WPC system [21]. Zhong considered a point-to-point wireless powered communication system, and presented its closed-form expressions of the average throughput for delay intolerant and delay tolerant transmission modes in [22]. A unified framework was proposed to jointly study wireless EH and interference alignment (IA) in [23]. Simultaneously, SWIPT based on opportunistic communications was proposed for IA network by Zhao too [24]. By allocating transmitting power, round-trip energy efficiency (EE) was optimized for a SWIPT massive MIMO system with frequency division duplex [25]. In [26], its springboard was not quite the same as traditional optimization objectives of wireless powered networks, authors optimized the weighted sum of multiple users' energy efficiencies based on time allocation and power control for WPC systems.

Recently, around the network secure, the research of EH problems raised suddenly [27]-[31]. For example, aiming at relay energy harvesting efficiency, a minimum problem of source transmission power was studied for relay-aided multicast network with authorized and unauthorized users in [27]. The maximum ratio transmission and transmitting antenna selection schemes were investigated for wireless powered wiretap channel, and the closed-form expressions of two schemes were derived for the achievable secrecy outage probability and average secrecy rate [28]. Reference [29] maximized the achievable secrecy sum rate under transmitting power constraint and energy harvesting constraint. For multiuser MISO network, Zhu studied the minimum transmitting power under secrecy rate outage probability of authorized users, and harvested energy outage probability of EH receivers [30]. Tang and Li derived the maximum secrecy throughput for a secrecy system with an H-AP node, a wireless powered source node, a destination node and multiple eavesdroppers [31].

#### A. Prior Related Work

A related system model was considered in [16] and [17]. Reference [16] presented an EH network model which a set of users can harvest energy in downlink and transmit information in uplink. In [17], the difference is that a dual-function H-AP is assumed to be equipped with two antennas to perform downlink energy transfer and uplink communication, respectively. Comparatively speaking, the optimum time allocation between energy harvesting and information transmission is complex. Chen considered a half-duplex single antenna wireless powered communication network [18]. In this system model, there are one H-AP, one relay and one source. A time switching cooperative communication scheme is studied to achieve downlink wireless energy transfer and uplink wireless information transmission. In all of these works, the wireless nodes only harvest energy from the H-AP. This is different

from our work using peer harvesting. In some applications, energies carried by the transmitted signals of the nodes may not be trivial and therefore, can be harvested. For example, in a cafeteria with several laptops, the received power from a neighboring laptop may be comparable to that from the base station outside the cafeteria, although the laptop has a smaller transmission power.

In this work, we propose a WPC network consisting of one H-AP and  $K$  wireless nodes where EH among nodes is also performed. At the same time, we propose two EH schemes for this WPC network. In serial EH (SEH) scheme, the  $k$ th node only harvests energy from the previous  $k-1$  transmitting nodes and goes to sleep after data transmission. In circular EH (CEH) scheme, the  $k$ th node not only harvests energy from the previous  $k-1$  transmitting nodes, but also from the following  $K-k$  nodes. Although CEH can always achieve better performance, it is more complicated than SHE and requires the energy harvester to be turned on all the time without sleeping. Therefore, the proposed schemes can offer different tradeoffs between performance and complexity, and can be applied to different scenarios. SEH is suitable for a network with mobile nodes and unbalanced topology structure, where some nodes are a bit far away from the H-AP but closer to the pervious nodes. SEH is also suitable for applications with simple energy storage and management. CEH is suitable for a network with fixed and clustered nodes, where all nodes are close to each other. CEH is also suitable for applications where energy storage and management are not restricted by complexity.

On basis of the proposed schemes, both the maximization of sum achievable throughput and the minimization of required harvested energy are considered. Generally speaking, global optimization problems can be solved by stochastic global optimization algorithms or deterministic global algorithms. For the maximization of sum achievable throughput problems, we show that they are convex optimization problems. A heuristic numerical optimization algorithm framework consisting of recursion and particle swarm optimization (PSO), which is a feasible stochastic global optimization method [32]-[34], is proposed to solve these optimization problems. One can see that the proposed optimization algorithm is effective and straightforward way. For the minimization of required harvested energy problems, the considered network models are not convex optimization problems. In addition, the considered problems have complicated target functions, and they are hard to realize convexification or get satisfactory boundaries. Therefore, we present their numerical solutions based on the proposed effective heuristic optimization algorithm.

#### B. Summary of challenges and contributions

The new technical challenges brought by our new idea of peer harvesting include the following.

- The peer harvesting have not been studied in the literature, although it is straightforward that harvesting energy from other devices besides the HAP will improve the performance. However, the implementation and the analysis of such system are more challenging due to the coupling among all nodes to optimize the time of EH and

transmission. Thus, we need to analyze the extra harvested energy at each node.

- Two optimization problems need to be formulated for practical designs. Since the optimization is more complicated than the existing works without peer harvesting and the objective functions of proposed schemes are difficult, we have to use feasible and low complexity method to achieve the optimization process.

The main merits of this paper are listed as follows.

- This paper presents two new schemes for WPC system. Effective peer harvesting methods are used to improve the gain of WPC system. Specifically, in SEH, the  $k$ th node harvests energy serially from the H-AP and previous  $k-1$  transmitting nodes and goes to sleep after data transmission. For the CEH, each node can harvest energy from the H-AP and other nodes when it doesn't transmit information. They are suitable to different scenarios. That is, the network has moderate energy gain by SEH with fewer computational complexity. Otherwise, the network can offer better achievable throughput performance, when it adopts CEH scheme.
- This paper proposes a heuristic recursive optimization algorithm using PSO to search optimum solutions of two optimizations based on different working modes. The proposed recursive optimization method can effectively solve the optimization problems, regardless of the complexity of objective functions. Put another way, it has better adaptability technically to solve some objective functions that are complex multidimensional problem. As a result, it doesn't need too many extra works to simplify the objective function to fit the needs of solving process. Otherwise, it will occupy more time on expression derivation instead of optimization. Relatively speaking, the proposed methods can offer a more simple way if someone just wants to satisfy an engineering requirement.

The rest of this paper is organized as follows. Section II introduces the WPC system model. The proposed schemes are presented in Section III. Section IV optimizes the sum achievable throughput and minimization of the required harvested energy, and presents the heuristic algorithm flow charts. Numerical simulation results and discussions are presented in Section V. Section VI is the conclusions.

## II. SYSTEM MODEL

Consider a wireless powered communication network with one H-AP (node 0) and  $K$  wireless nodes (nodes  $1, \dots, K$ ). Assume that all nodes are equipped with a single antenna. In addition, assume that the H-AP has a constant energy and that the  $K$  nodes do not have any embedded energy supply. In the first time slot, the H-AP transfers the initial energy to all the wireless nodes in the down link for  $t_0T$  seconds, where  $T$  is the total duration of communication and  $0 < t_0 < 1$ . In the second time slot, node 1 transmits information to the H-AP for  $t_1T$  seconds, followed by node 2 for  $t_2T$  seconds, until node  $K$  for  $t_KT$  seconds. One has  $t_0 + t_1 + \dots + t_K = 1$ . WPC system model is shown in Fig.1, and adopts two operating schemes. In the SEH scheme,

the  $k$ th node only harvests energy serially from the previous  $k-1$  nodes when they transmit information to the H-AP. In the CEH scheme, the  $k$ th node not only harvests energy from the previous  $k-1$  nodes, but also from the  $(k+1)$ th to the  $K$ th nodes.

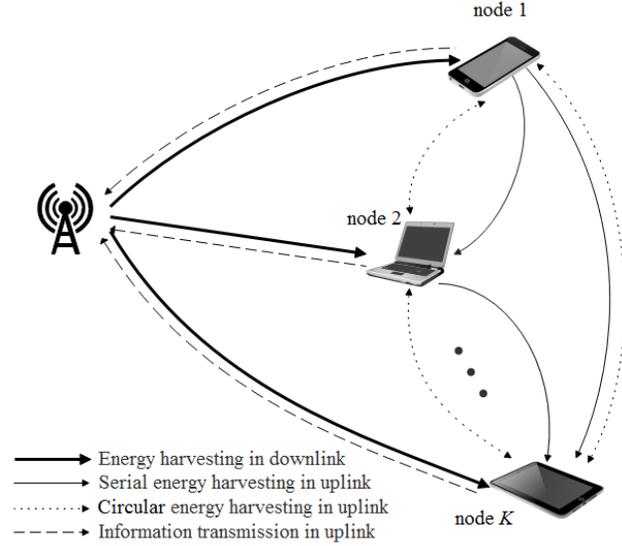


Fig. 1. WPC network model

Assume that the H-AP assigns the random transmission order and initial time slots via the control channel, and the WPC system abides by the TDMA protocol [35]. This means that the nodes can transmit signals in the assigned time slot and then harvest energy or go to sleep in their idle time slots. Because each time slot just exists one user node to transmit data, other nodes can estimate their CSI between themselves and working node, respectively. Finally, H-AP achieves optimization and schedule based on nodes' feedback information.

Let  $h_{k,i}$  and  $|h_{k,i}|^2$  be the channel gain and channel power from the  $i$ th node to the  $k$ th node ( $i, k = 0, \dots, K, i \neq k$ ), respectively. Also, since all nodes transmit data in different time slots, there is no interference. In the time slot  $t_iT$ , the received signal at the  $k$ th node is then expressed as

$$y_k(t_iT) = h_{k,i}(t_iT)x_i(t_iT) + z_k(t_iT), \quad (1)$$

where  $x_i(t_iT)$  is the transmitted signal with  $\mathbb{E}[|x_i(t_iT)|^2] = P_i$ ,  $P_i$  is the transmission power of the  $i$ th node,  $z_k(t_iT)$  is the additive white Gaussian noise with mean 0 and variance  $\delta^2$ . For avoiding cumbersome notation, the index  $(t_iT)$  will be suppressed. Assume that the harvested energy is stored in a rechargeable battery, and that the transmitting power  $P_0$  of the H-AP is sufficiently large such that the harvested energy from receiver noise is negligible. Thus, the energy of the  $k$ th node harvested from the  $i$ th node is

$$E_k = \zeta_k P_i t_i T D_{k,i}^{-\alpha_{k,i}} |h_{k,i}|^2, \quad k = 1, \dots, K, \quad (2)$$

where  $0 < \zeta_k < 1$  is the conversion efficiency of the  $k$ th node,  $D_{k,i}$  and  $\alpha_{k,i}$  are the distance and path loss exponent from the  $i$ th node to the  $k$ th node, respectively. According to Shannon-Hartley theorem, uplink channel capacity of the  $k$ th node in bits per second (bps) is

$$R_k = B_k \cdot \log_2(1 + P_k/\delta^2), \quad (3)$$

where,  $B_k$  is the bandwidth of channel from the  $k$ th node's to H-AP,  $P_k$  is the average transmitting power of the  $k$ th node over the bandwidth  $B_k$ .

### III. PEER HARVESTING SCHEMES

#### A. Serial Energy Harvesting

In SEH, the  $k$ th node only harvests energy from the 1st, 2nd, ...,  $(k-1)$ th nodes that have transmitted before it, and then goes to sleep after its own transmission. The timing diagram of SEH for energy harvesting and information transmission is shown in Fig. 2.

The harvested energy of the  $k$ th node is thus

$$E_k = \zeta_k \sum_{i=0}^{k-1} P_i t_i T D_{k,i}^{-\alpha_{k,i}} |h_{k,i}|^2, \quad k=1, \dots, K, \quad (4)$$

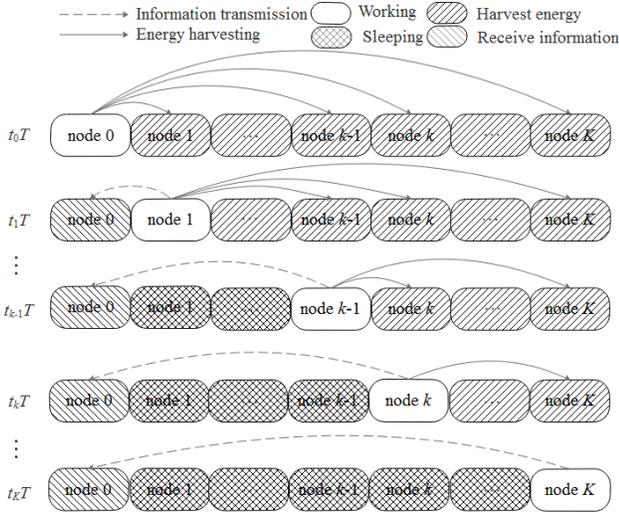


Fig. 2. The timing diagram of SHE

Using (4), the transmitting power of the  $k$ th node is

$$P_k = \eta_k E_k / (t_k T), \quad (5)$$

where  $\eta_k$  determines the portion of harvested energy used for information transmission. Similar to [16] and [18], we assume that all the nodes exhaust the harvested energy for uplink data transmission. Thus, the achievable throughput of the  $k$ th node in bps/Hz can be get based on (3) and [16]

$$C_k(\mathbf{t}) = t_k \log_2(1 + |h_{0,k}|^2 P_k / \delta^2), \quad (6)$$

where  $\mathbf{t} = [t_0 \ t_1 \ \dots \ t_K]$ .

#### B. Circular Energy Harvesting

For CEH scheme, the timing diagram of energy harvesting and information transmission is shown in Fig. 3. In CEH, the  $k$ th node not only harvests energy from the previous  $k-1$  nodes that have transmitted information before it, but also harvests energy from the following  $K-k$  nodes that will transmit after it. In other words, the  $k$ th node does not go to sleep after its own data transmission but keeps harvesting energy from others. Therefore, its optimization and derivation are more

mathematically involved. Assume that all nodes exhaust the harvested energy for transmitting information and do not consider energy storage and power allocation for future transmission like many existing works, such as [16] and [18]. Otherwise, complicated power control over multiple frames have to be used, which is beyond the scope of this work and also increases overheads [14] [15]. From the second transmission on, the harvested energy of the  $k$ th node is

$$F_k = F_{P,k}^{[n]} + F_{F,k}^{[n-1]}, \quad k=1, \dots, K$$

$$= \left( \zeta_k \sum_{i=0}^{k-1} Q_i t_i T D_{k,i}^{-\alpha_{k,i}} |h_{k,i}|^2 \right)^{[n]} + \left( \zeta_k \sum_{i=k+1}^K Q_i t_i T D_{k,i}^{-\alpha_{k,i}} |h_{k,i}|^2 \right)^{[n-1]}, \quad (7)$$

where  $(\cdot)^{[n]}$  is the harvested energy from nodes transmitting before it in the  $n$ th communication, and  $(\cdot)^{[n-1]}$  represents the harvested energy from nodes transmitting after it in the  $(n-1)$ th transmission. Thus, each node in CEH has more energy than that in SEH. The transmitting power of the  $k$ th node is

$$Q_k = \eta_k F_k / (t_k T), \quad (8)$$

and the achievable throughput of the  $k$ th node is

$$D_k(\mathbf{t}) = t_k \log_2(1 + |h_{0,k}|^2 Q_k / \delta^2). \quad (9)$$

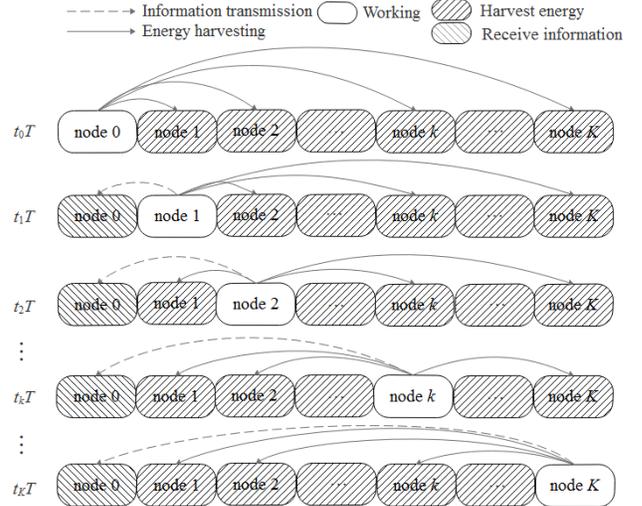


Fig. 3. The timing diagram of CEH

### IV. OPTIMIZATION

#### A. Maximization of the Sum Achievable Throughput

For SEH, in each block, the sum achievable throughput is

$$C(\mathbf{t}) = \sum_{k=1}^K C_k(\mathbf{t}). \quad (10)$$

For CEH, the sum achievable throughput after the first transmission is given by

$$D(\mathbf{t}) = \sum_{k=1}^K D_k(\mathbf{t}). \quad (11)$$

Thus, the maximization problem becomes

$$(P1): \max_{\mathbf{t}} \{C(\mathbf{t}) \text{ or } D(\mathbf{t})\} \quad (12)$$

$$\text{s.t. } \sum_{k=0}^K t_k = 1, t_k \geq 0.$$

**Lemma:**  $C_k(\mathbf{t}), D_k(\mathbf{t})$  are concave functions of  $\mathbf{t}$  for  $k \in \{1, \dots, K\}$ .

*Proof:*

$$E_1 = \zeta_1 P_0 t_0 T D_{1,0}^{-\alpha_{1,0}} |h_{1,0}|^2,$$

$$P_1 = \eta_1 \zeta_1 P_0 D_{1,0}^{-\alpha_{1,0}} |h_{1,0}|^2 \cdot t_0 / t_1 \Rightarrow P_1 = f_1(t_0 / t_1),$$

$$E_2 = \zeta_2 \left( P_0 t_0 T D_{2,0}^{-\alpha_{2,0}} |h_{2,0}|^2 + P_1 t_1 T D_{2,1}^{-\alpha_{2,1}} |h_{2,1}|^2 \right),$$

$$P_2 = \eta_2 \zeta_2 P_0 \left( D_{2,0}^{-\alpha_{2,0}} |h_{2,0}|^2 + \eta_1 \zeta_1 D_{1,0}^{-\alpha_{1,0}} D_{2,1}^{-\alpha_{2,1}} |h_{1,0}|^2 |h_{2,1}|^2 \right) t_0 / t_2$$

$$\Rightarrow P_2 = f_2(t_0 / t_2),$$

⋮

$$E_K = \zeta_K \sum_{i=0}^{K-1} P_i t_i T D_{K,i}^{-\alpha_{K,i}} |h_{K,i}|^2,$$

$$P_K \propto t_0 / t_K \Rightarrow P_K = f_K(t_0 / t_K).$$

Thus,

$$C_1(t_0, t_1) = t_1 \log_2 \left[ 1 + |h_{0,1}|^2 / \delta^2 \cdot f_1(t_0 / t_1) \right]$$

$$C_2(t_0, t_2) = t_2 \log_2 \left[ 1 + |h_{0,2}|^2 / \delta^2 \cdot f_2(t_0 / t_2) \right]$$

⋮

$$C_K(t_0, t_K) = t_K \log_2 \left[ 1 + |h_{0,K}|^2 / \delta^2 \cdot f_K(t_0 / t_K) \right]$$

From the above,  $C_k(\mathbf{t})$  is only a function of  $t_k$  and  $t_0$ . Because Hessian of  $C_k(\mathbf{t})$  is a negative semi-definite matrix,  $C_k(\mathbf{t})$  is a concave function of  $\mathbf{t}$  for any given  $k \in \{1, \dots, K\}$  [36]. For CEH,  $F_{F,k}^{[n-1]}$  is determined by the previous communications and can be considered as a constant for the current transmission. In this case,  $D_k(\mathbf{t})$  is also a function of  $t_k$  and  $t_0$ , and is a concave function of  $\mathbf{t}$ . This completes the proof of Lemma. ■

From this Lemma,  $C(\mathbf{t}), D(\mathbf{t})$  are concave functions of  $\mathbf{t}$  since they are the sums of  $C_k(\mathbf{t}), D_k(\mathbf{t})$ , respectively. This means that (12) has an optimum solution. In addition to the convex optimization, in this work, we propose a much easier but heuristic optimization framework based on PSO, and utilize recursive method to search for the optimum solution. The proposed numerical optimization algorithm has better technical adaptability to solve more complicated objective functions, unlike convex optimizations that require extra work to simplify the objective function. The PSO[ $A(\mathbf{t})$ ] represents the process that iteration optimization algorithm searches the optimal solution of  $A(\mathbf{t})$  using standard PSO method, and when the difference of the previous and current solutions is smaller than  $10^{-3}$ , the algorithm will stop. The proposed algorithm has the following pseudo-code.

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Algorithm 1 Recursive maximum achievable throughput

---

1: *Initial* :  $P_0, t_k, h_{k,i}$ ,  $\max C = 0, \max D = 0$

2: *Do*

3:   *for*  $k = 0$  to  $K$

4:     compute  $E_k, F_k$

5:     compute  $P_k, Q_k$

6:     compute  $C_k(\mathbf{t}), D_k(\mathbf{t})$

7:   *end for*

8:   PSO[ $C(\mathbf{t})$ ], PSO[ $D(\mathbf{t})$ ]

9:   *if*  $C(\mathbf{t}) > \max C$

10:      $\max C = C(\mathbf{t})$ ,

11:     update  $t_k$

12:   *end if*

13:   *if*  $D(\mathbf{t}) > \max D$

14:      $\max D = D(\mathbf{t})$ ,

15:     update  $t_k$

16:   *end if*

17: *End*

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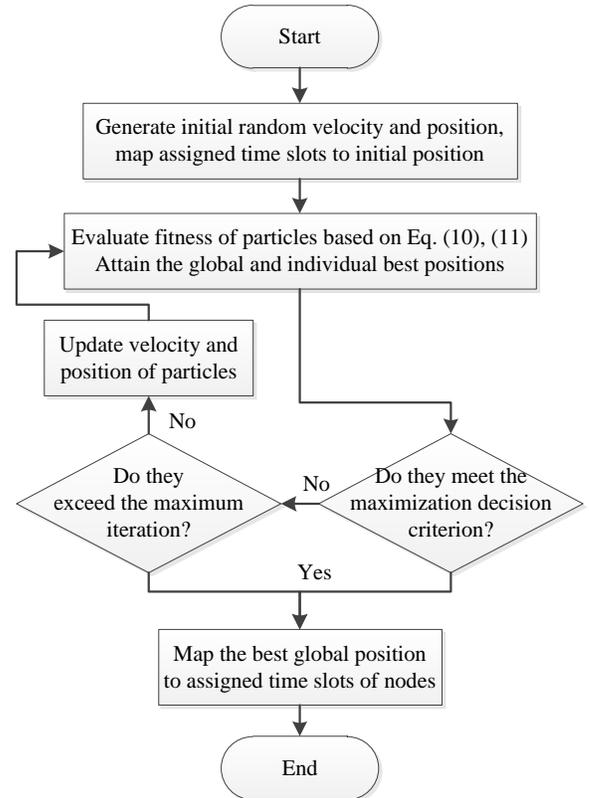


Fig. 4. Basic procedure for maximization of the sum achievable throughput based on PSO

Fig. 4 shows a basic procedure of numerical optimization algorithm PSO-based to search the maximum sum achievable throughput (corresponding to Step 8 to 16 of Algorithm 1). Initial velocities are uniform distribution from 0 to 0.1, initial

positions represent the initial time slots  $\mathbf{t}$  which abide by uniform distribution between 0 and 1. Learning factors are 2.8 and 1.3, respectively. After initialization of velocity and position, fitness function is calculated and evaluated based on Eq. (10), (11). Then, requisite parameters are computed based on updating formulas. At last, the optimal solution is found through continuous iteration. Jointly Algorithm 1 and Fig. 4, the proposed optimization framework can avoid complicated mathematical calculations based on recursive computation and attain the optimal solution in a probabilistic manner with limited steps. Compared with convex optimization, the merit of heuristic optimization is that its computational cost is mainly used for solving the fitness function.

### B. Minimization of the Required Harvested Energy

For applications with miniaturization of batteries, another optimization can be performed to minimize the required consumed energy. In this case, the nodes will harvest minimum energy to maintain operations. As mentioned above, the complicated power control and energy management produced by accumulated energy are not considered, as this is beyond the scope of the paper and also makes WPC too complicated for simple applications that the EH aims for.

For the network model of [16], where all nodes only harvest energy from H-AP, the required consumed energy of the  $k$ th node can be expressed as following equation according to (3)

$$G_k(\mathbf{t}) = \frac{2^{I_k/(t_k T)} - 1}{|h_{0,k}|^2} \delta^2 t_k T, \quad (13)$$

where  $\mathbf{t} = [t_0 \ t_1 \ \dots \ t_K]$ ,  $I_k$  is the  $k$ th user's targeted information of unit bandwidth, and (13) considers the influence of uplink channel power.

Because the harvested energy of  $k$ th node is

$$E_k = \zeta_k P_0 t_0 T D_{k,0}^{-\alpha_{k,0}} |h_{k,0}|^2, \quad k = 1, \dots, K. \quad (14)$$

The required harvested energy of the  $k$ th node can be normalized as

$$G_{k,0}(\mathbf{t}) = \frac{2^{I_k/(t_k T)} - 1}{\zeta_k D_{k,0}^{-\alpha_{k,0}} |h_{0,k}|^2 |h_{k,0}|^2} \delta^2 t_k T, \quad (15)$$

where (15) shows the required harvested energy from H-AP.

Based on (4), in SHE, the required harvested energy of the  $k$ th node comes from both the H-AP and the previous transmitting nodes as

$$E_{k,0}(\mathbf{t}) = \left\{ \delta^2 \left( 2^{I_k/(t_k T)} - 1 \right) t_k T / \left( \zeta_k |h_{0,k}|^2 \right) - \sum_{i=1}^{k-1} \left[ \delta^2 D_{k,i}^{-\alpha_{k,i}} \cdot \left( |h_{k,i}|^2 / |h_{0,i}|^2 \right) \left( 2^{I_i/(t_i T)} - 1 \right) t_i T \right] \right\} / \left( D_{k,0}^{-\alpha_{k,0}} |h_{k,0}|^2 \right). \quad (16)$$

Similarly, the required harvested energy in CEH is the same as (16) in the first communication based on (7). From the second communication, it is

$$F_{k,0}(\mathbf{t}) = \left\{ \delta^2 \left( 2^{I_k/(t_k T)} - 1 \right) t_k T / \left( \zeta_k |h_{0,k}|^2 \right) - \sum_{i=1}^{k-1} \left[ \delta^2 D_{k,i}^{-\alpha_{k,i}} \cdot \left( |h_{k,i}|^2 / |h_{0,i}|^2 \right) \left( 2^{I_i/(t_i T)} - 1 \right) t_i T \right] - F_{F,k}^{[n-1]} \right\} / \left( D_{k,0}^{-\alpha_{k,0}} |h_{k,0}|^2 \right). \quad (17)$$

The minimization problem becomes

$$(P2): \min_{\mathbf{t}} \left\{ \max_k G_{k,0}(\mathbf{t}) \text{ or } \max_k E_{k,0}(\mathbf{t}) \text{ or } \max_k F_{k,0}(\mathbf{t}) \right\} \\ \text{s.t. } \sum_{k=0}^K t_k = 1, t_k \geq 0. \quad (18)$$

This optimization problem P2 aims to minimize the maximum required harvested energy. As the second-order derivative of (15) with respect to  $t_k$  exists, it is a strict convex function and has an optimal solution. However, the Hessian of (16) and (17) are indefinite matrices, and their object functions are complicated. In order to facilitate comparison of three models, the numerical solutions of (18) can also be searched by using the proposed heuristic optimization framework.

The proposed algorithm has the following pseudo-code in Algorithm 2, the required harvested energy  $G_{k,0}(\mathbf{t}), E_{k,0}(\mathbf{t}), F_{k,0}(\mathbf{t})$  can be computed recursively by general expressions (15), (16) and (17). The optimization PSO-based complies with the following flowchart Fig. 5.

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#### Algorithm 2 Recursive minimum required harvested energy

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```

1: Initial :  $I_k, t_k, h_{k,i}$ 
2: Do
3:   for  $k = 0$  to  $K$ 
4:     compute  $G_{k,0}(\mathbf{t}), E_{k,0}(\mathbf{t}), F_{k,0}(\mathbf{t})$ 
5:   end for
6:    $\min G = G_{k,0}(\mathbf{t}), \min E = E_{k,0}(\mathbf{t}), \min F = F_{k,0}(\mathbf{t})$ 
7:   PSO[ $G_{k,0}(\mathbf{t})$ ], PSO[ $E_{k,0}(\mathbf{t})$ ], PSO[ $F_{k,0}(\mathbf{t})$ ]
8:   if  $G_{k,0}(\mathbf{t}) < \min G$ 
9:      $\min G = G_{k,0}(\mathbf{t}),$ 
10:    update  $t_k$ 
11:   end if
12:   if  $E_{k,0}(\mathbf{t}) < \min E$ 
13:      $\min E = E_{k,0}(\mathbf{t}),$ 
14:    update  $t_k$ 
15:   end if
16:   if  $F_{k,0}(\mathbf{t}) < \min F$ 
17:      $\min F = F_{k,0}(\mathbf{t}),$ 
18:    update  $t_k$ 
19:   end if
20: End

```

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Fig. 5 presents a basic procedure of numerical

optimization algorithm PSO-based to search the required minimum harvested energy (corresponding to Step 7-19 of Algorithm 2). According to Fig. 5, we can know that its implementation and parameters are similar to Fig. 4, and its process can also avoid complicated mathematical calculations and attain the optimal solution in a probabilistic manner with limited steps. To save space, the details are not repeated here. But by comparing the two algorithms and their flowcharts respectively, we can find that the proposed heuristic optimization algorithms, which consist of recursive algorithm and particle swarm optimization, don't need to make too many changes and have good technical adaptability and flexibility to solve the proposed schemes.

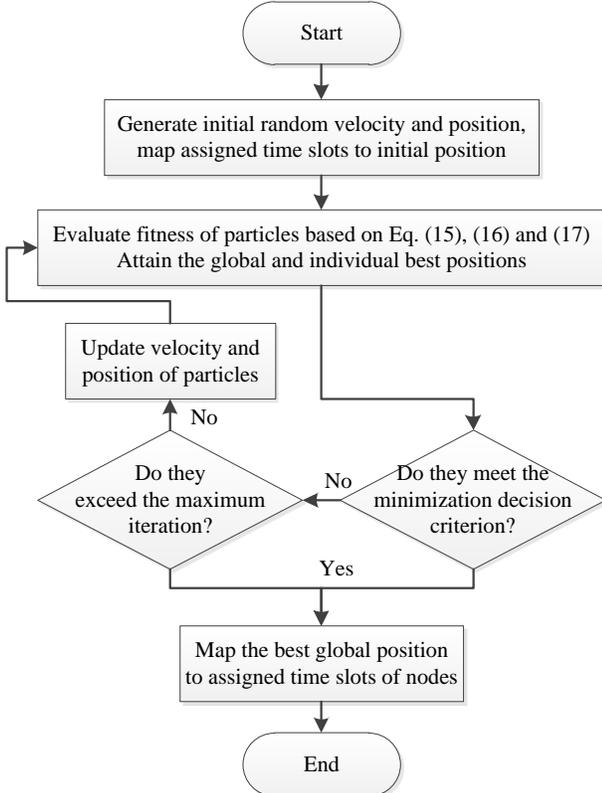


Fig. 5. Basic procedure for minimization of the required harvested energy based on PSO

### C. Schedule

The random transmission order mentioned in Section II, which is assigned by H-AP, simulates a time access priority communication network actually, i. e., “first-come, first-serve” basis. If these user nodes work with a scheduling order based on channel state information (CSI), it should make some gains. However, for the proposed two schemes, their targets are complicated functions of CSI, which are between H-AP and nodes, and between nodes to nodes. We can't get straightforward scheduling orders of nodes in terms of the channel gain. Even though assume the channel of network is reciprocity, there are still three kinds of orders, which are downlink, uplink and energy harvesting link among the nodes, coexisting in the network. They are complex coupling problems and not suitable to a WPC network which is normally for

simple applications. Thus, we schedule work order by considering channel gain of uplink only, which has the most direct influence on optimization objectives. That is, ascending order schedule and descending order schedule are considered based on uplink channel gain. The problems P1 and P2 also become as follows

$$(P3): \max_t \{C(t) \text{ or } D(t)\} \\ \text{s.t. } \sum_{k=0}^K t_k = 1, t_k \geq 0; \text{ sort} \left\{ |h_{0,i}|^2 \right\}, i = 1, 2, \dots, K, \quad (19)$$

$$(P4): \min_t \left\{ \max_k G_{k,0}(t) \text{ or } \max_k E_{k,0}(t) \text{ or } \max_k F_{k,0}(t) \right\} \\ \text{s.t. } \sum_{k=0}^K t_k = 1, t_k \geq 0; \text{ sort} \left\{ |h_{0,i}|^2 \right\}, i = 1, 2, \dots, K, \quad (20)$$

where  $\text{sort}\{\cdot\}$  denotes to get the ascending or descending order of uplink channel power, respectively. Their solutions can be still solved using the proposed algorithms without too much change, and the H-AP only allocates transmission order according to the ranking results of channel power but not random access.

### D. Fairness

In order to offer fair access for SEH, we propose a schedule by extending time dimension to meet the fairness requirement of each node. Fig. 6 is the diagram of schedule, the ‘dot arrow’ denotes a connector because of limited line-width space. For example, the time orders of fair access will be  $\{1, 2, 3; 1, 3, 2; 2, 1, 3; 2, 3, 1; 3, 1, 2; 3, 2, 1\}$  for 3 nodes. That is, in this network, every access nodes have to obey a protocol that exchange their time extension for reducing computational complexity, and there are  $K$  factorial time extensions for  $K$  nodes in this schedule. Luckily, there should be not too many nodes generally, so that it will not need too many time extensions in such a WPC network. Of course, if some nodes can't perform the protocol, they will not be allowed to access the network. Alternatively, these nodes which regard time as the important resource can choose CEH scheme to get fair harvesting energy. Compared with the proposed fair access schedule of SEH, the nodes can transfer information and harvest energy at all the time slots in CEH scheme to make sure fair chance.

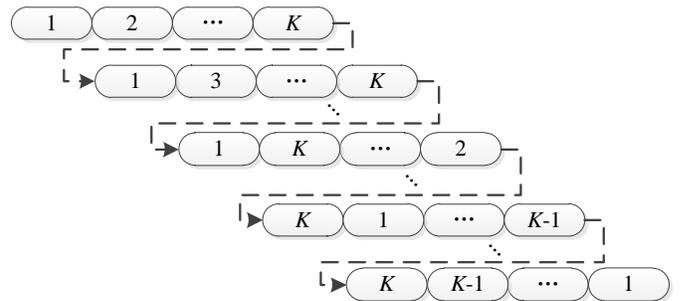


Fig. 6. The fairness-based scheduling diagram

## V. NUMERICAL RESULTS AND DISCUSSION

In this section, a wireless powered network with one H-AP and three nodes in Rayleigh fading is used. Consider

harvest-then-transmit and TDMA protocol. The transmitting power at the H-AP is 23dBm. The noise power is -70dBm. The conversion efficiency of all nodes is 0.6. The number of particles is 50, initial velocities and positions are uniform distribution between 0 to 0.1 and 0 to 1, respectively, and learning factors  $c_1=2.8$ ,  $c_2=1.3$ . Simulation environment is Windows 7 (32-bit), Matlab R2012b, Intel(R) Core(TM) i3 CPU M330@2.13GHz, RAM 2 GB.

Fig. 7 presents the achievable throughput of each node in three modes, SEH, CEH and OEH, where OEH represents the result in [10]. In this experiment, the time slots of AP and three nodes are fixed as  $t_0, t_1, t_2, t_3=0.7, 0.1, 0.1, 0.1$  without optimization. One sees that the achievable throughput of each node is close to 2 bps/Hz in OEH. In SEH, node 1 is about 2 bps/Hz, node 2 is about 2.065 bps/Hz and node 3 is about 2.117 bps/Hz. In CEH, node 1 is about 2.117 bps/Hz, node 2 is about 2.125 bps/Hz and node 3 is about 2.130 bps/Hz. The first node in SEH has the same performance as that in OEH, because it does not have any extra harvested energy. However, node 2 and node 3 have more harvested energy. For CEH, the three nodes have about 6% gain over OEH. Also, practical systems have bandwidths on the order of kHz or MHz, which could magnify the throughput gain. Thus, the gain is considerable.

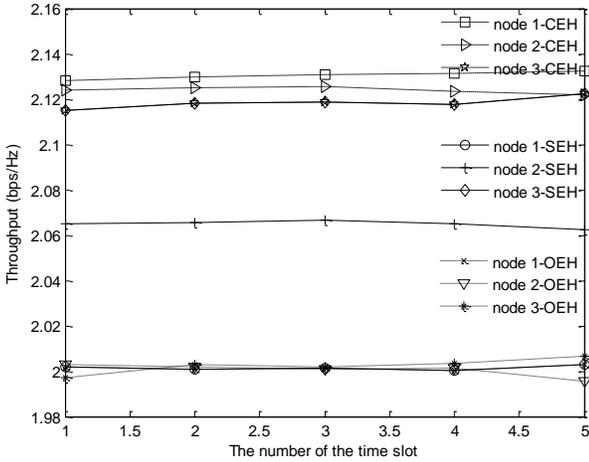


Fig. 7. The achievable throughput of nodes in different blocks with  $D_{k,0}=10m, D_{k,i}=2m, \alpha_{k,0}=4, \alpha_{k,i}=2$ .

The optimized sum achievable throughput is shown in Fig. 8. CEH-COV denotes the result from convex optimization instead of Algorithm 1. In the first transmission, the maximum sum achievable throughput of SEH, OEH, and CEH are 15.2468 bps/Hz, 15.2196 bps/Hz, 15.2471 bps/Hz using the proposed algorithms, respectively. One sees that the optimal throughputs of the SEH and CEH are almost the same, both of which are larger than OEH. In the second transmission, the maximum sum achievable throughput of CEH is 17.4662 bps/Hz. Thus, it is about 10% better than OEH in [10], and the performance gain is more significant with larger bandwidth. Also, Algorithm 1 and convex optimization algorithm give almost identical maximum throughput for CEH in the first transmission. However, in the second transmission, it is 0.1% worse than convex optimization algorithm. Fortunately, the gap of

throughput is small and their convergence are almost the same so that it can meet the actual requirements.

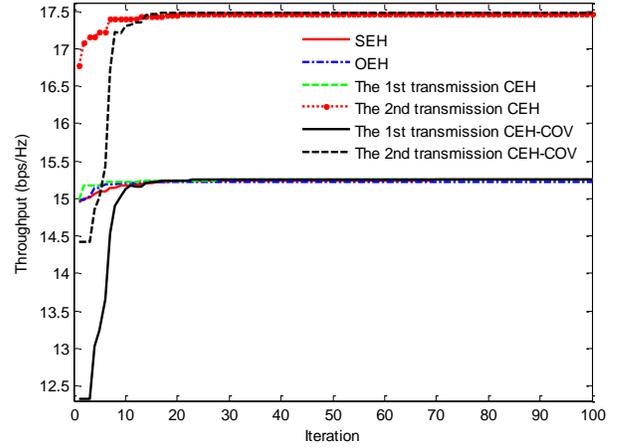


Fig. 8. The maximization of sum achievable throughput with  $D_{k,0}=10m, D_{k,i}=2m, \alpha_{k,0}=4, \alpha_{k,i}=2$ .

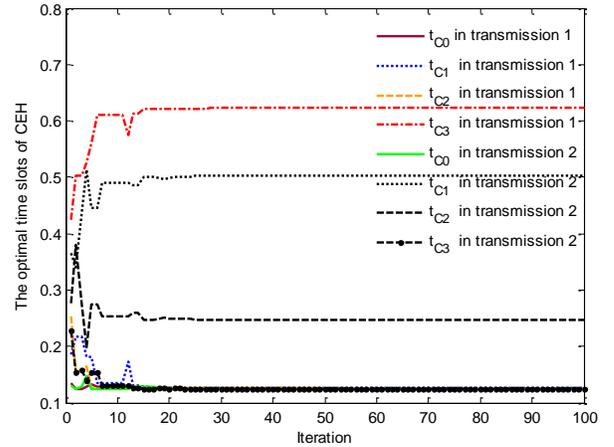


Fig. 9. The optimal time slots of CEH for sum achievable throughput with  $D_{k,0}=10m, D_{k,i}=2m, \alpha_{k,0}=4, \alpha_{k,i}=2$ .

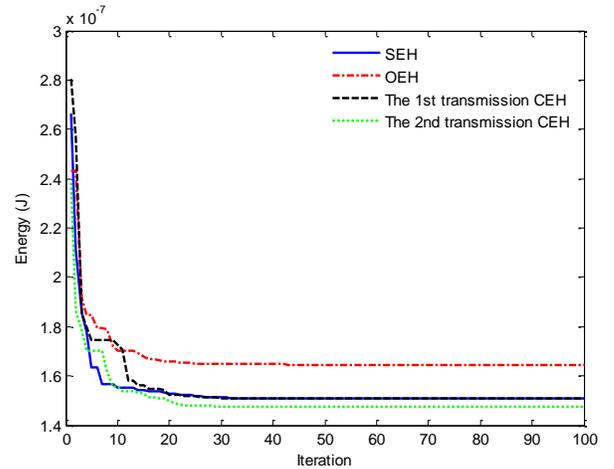


Fig. 10. The minimization of required harvested energy with  $I=1.35b/Hz, D_{k,0}=10m, D_{k,i}=5m, \alpha_{k,0}=4, \alpha_{k,i}=3.5$ .

Fig. 9 presents the optimal time slots of CEH for sum achievable throughput in different transmissions. Let  $t_{Ck}$  denotes the time slot of the  $k$ th node in CEH. In the first transmission,  $t_{C3}$  of node 3 is the largest time slot, and other nodes' time slots are similar. It implies that the node 3 should be assigned more time to achieve better performance. This is particularly true as node 3 can harvest more energy in the first transmission. In the second transmission, node 1 has the largest time slot, node 2 has a smaller time slot, and the H-AP and node 3 have similar time slots. From the second transmission on, the optimal time slots are primarily determined by the path loss and the channel gain, because all nodes experience similar energy harvesting and accumulating processes.

Fig. 10 shows the minimization of required harvested energy based on the proposed algorithms. In the first transmission, the minimum required harvested energies of SEH and CEH are both  $1.5087 \times 10^{-7} \text{ J}$ , and the minimum required harvested energy of OEH is  $1.6460 \times 10^{-7} \text{ J}$ . From the second transmission of CEH, its minimum required harvested energy becomes  $1.4759 \times 10^{-7} \text{ J}$ , less than that for the first transmission. Thus, CEH could be 10% better than OEH in this case as well.

In following simulations, we evaluate the impact of scheduling order and the fair time slots allocation to SEH, respectively. In two experiments, their CSI are same. Fig. 11 presents sum achievable throughput, and Fig. 12 shows required harvested energy. It can be observed that the maximum sum achievable throughput is achieved by descending schedule in Fig. 11, and the minimum required harvested energy is attained by the schedule fairness-based in Fig. 12. Their performance trends are not uniform in two figures, but are bigger sum achievable throughput corresponding to smaller required harvested energy, and vice versa. Compare with original SHE scheme, schedule sort-based can't always realize better performance with arbitrary CSI. Similarly, the schedule fairness-based can achieve -1% and 2% gains in Figs. 11 and 12, respectively.

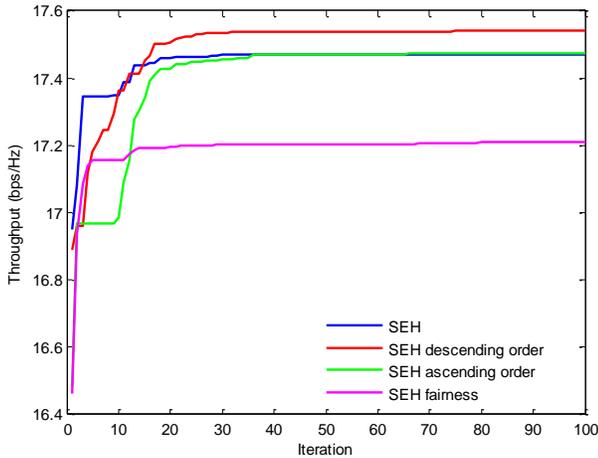


Fig. 11. The maximization of sum achievable throughput with  $D_{k,0} = 10\text{m}$ ,  $D_{k,i} = 2\text{m}$ ,  $\alpha_{k,0} = 4$ ,  $\alpha_{k,i} = 2$ .

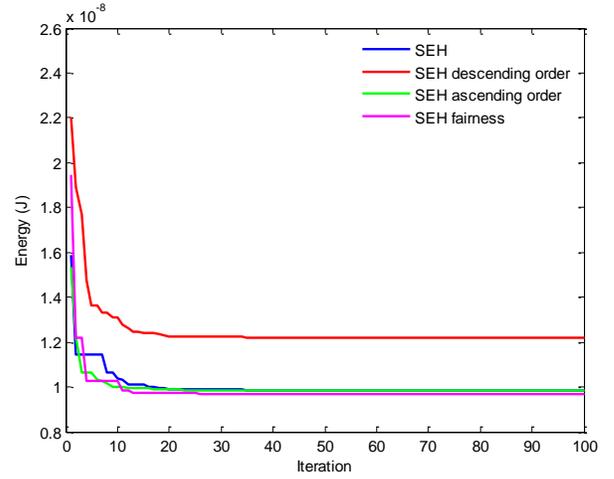


Fig. 12. The minimization of required harvested energy with  $I = 1.35\text{b/Hz}$ ,  $D_{k,0} = 10\text{m}$ ,  $D_{k,i} = 5\text{m}$ ,  $\alpha_{k,0} = 4$ ,  $\alpha_{k,i} = 3.5$ .

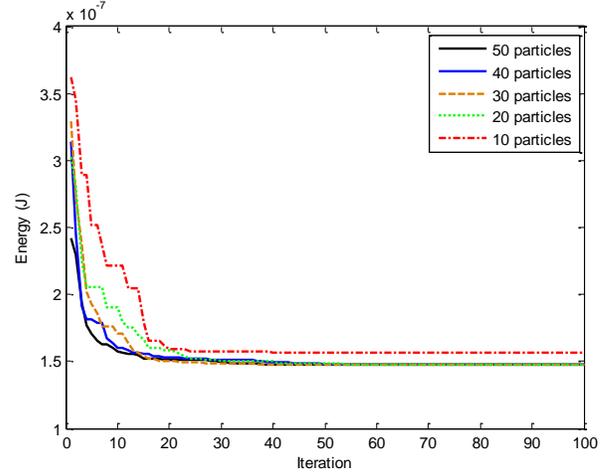


Fig. 13. The minimum required harvested energy of SEH with different number of particles with  $I = 1.35\text{b/Hz}$ ,  $D_{k,0} = 10\text{m}$ ,  $D_{k,i} = 5\text{m}$ ,  $\alpha_{k,0} = 4$ ,  $\alpha_{k,i} = 3.5$ .

TABLE I  
The cost of primary programs of PSO with 20 and 50 particles

Function Name	Calls	Total Time (S)	Self Time (S) <sup>3</sup>	Particles
Main Program	1	3.439 <sup>1</sup>	0.449	50
Update Particles	5000	1.708	0.865	
Compute Fitness	5000	0.843	0.330	
Recursive Process	2801	0.513	0.513	20
Main Program	1	1.924 <sup>2</sup>	0.454	
Update Particles	2000	0.657	0.267	
Compute Fitness	2000	0.390	0.108	
Recursive Process	1238	0.282	0.282	

The minimum required harvested energy of SEH with different numbers of particles are shown in Fig. 13. The numbers of particles are from 10 to 50. One can see that the

performance is improved with particles numbers increasing. However, the improvement is minor when the number is close to 50. In other words, while the number of particle increases continuously, the performance of the proposed algorithms is not improved obviously, but the computational complexities are growing.

Table I shows the cost of primary programs of the proposed heuristic recursive optimization algorithm using PSO with 20 and 50 particles. The larger number of particles leads to more costs, although it achieves better performance in Fig. 13. Therefore, a just right particle number is more favorable for the proposed numerical optimization algorithm PSO-based. In Table I, <sup>1, 2</sup> The total time of main program includes other processing time, such as storage data, plotting figures and file configuration et al. <sup>3</sup> Self time is the time spent in a function excluding the time spent in its child functions. Self time also includes overhead resulting from the process of profiling.

## VI. CONCLUSIONS AND FUTURE WORKS

This paper has proposed two energy harvesting schemes to optimize sum achievable throughput and required harvested energy. Both of them are presented numerical optimization solutions based on heuristic algorithms. To achieve the maximum sum achievable throughput, CEH is better than SEH, but CEH is more computationally complicated. Also, to achieve minimum required harvested energy, SEH and CEH have similar performances. Simulation results have shown the considerable performance gain of the new schemes.

For WPC system, there are still many challenges to be tackled. For example, power control may be used to improve its performance further, the tradeoff between optimal transmission order and implementation complexity should be investigated, although they are complicated coupling problems, and how can user-centric fairness be guaranteed is also an important target for future works.

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