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# A non-local probabilistic method for modelling of crack propagation

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## ABSTRACT

Damage process in engineering systems is strongly affected by spatial heterogeneity and local discontinuities in the materials, which are significantly influencing the reliability and integrity of the systems. In this paper, we present a new stochastic approach as a tool for performing uncertainty quantification in simulating damage evolution in heterogeneous brittle materials. One of the advantages of the proposed method is its ability to capture the influence of uncertainty in the mechanical properties of whole simulation domain, not just the properties of the immediate neighbourhood around the crack tip, on direction of crack propagation. In fact, through this approach the direction of crack propagation at a specified point of localised damage can be probabilistically determined based on nonlocal mechanics theory, in which the influence of local discontinuities and weak points located at further distances from the crack tip, in addition to those located at the immediate neighbourhood of the local damage, are incorporated into the model. The reliability and performance of the methodology are examined through simulation of numerical examples and comparison with analytical results and experimental data. The case studies show how the crack initiation angle can be reasonably estimated with this methodology and how this approach provides realistic values of fracture toughness  $K_{IC}$  and fracture energy  $G_f$ .

**Key Words:** *stochastic crack initiation angle; fracture toughness; mixed-mode fracture; nonlocal approach; non-Gaussian random field*

## 33 **1. Introduction**

34 In recent years, many researchers have focused on the problem of modelling heterogeneous  
35 material systems containing discontinuities. Numerous methodologies for inclusion of  
36 heterogeneity in numerical frameworks for simulating material failure behaviour have been  
37 developed, which can be grouped into two main categories: multi-scale models and stochastic  
38 approaches.

39 Multi-scale methods have offered a significant progress in explicitly describing local  
40 heterogeneities [1]. In fact, for the heterogeneous materials, like concrete, rocks or composites,  
41 often a local fine-scale definition of micro-structure of the materials that influence their  
42 macroscopic mechanical response is needed [2]. Developed understanding of multiple phase  
43 concepts is used in multi-scale techniques, where it is aimed to predict the joint multi-phase  
44 response of structures. Although multi-scale modelling has been proved to be a powerful  
45 method for incorporation of the heterogeneity, difficulties may arise when a detailed  
46 knowledge of the material micro-structure for identifying the representative elementary  
47 volume, is not available. For this reason, an increasing interest has now been directed towards  
48 stochastic approaches, as they allow probabilistic estimation of degree of heterogeneity in the  
49 materials by quantifying fluctuations of mechanical properties [3-6, 46].

50

51 The two main processes for brittle failure of materials are crack initiation and crack  
52 propagation. From a physical point of view, when a body is deformed, the corresponding stored  
53 strain energy increases. If there is a high enough imbalance in the energy of the system is high  
54 enough, fracturing occurs due to progressive degradation of material strength. The failure  
55 process can be therefore broken down into a number of steps based on the level of material  
56 degradation and stiffness softening. [7]. Within these steps, crack initiation denotes the stress  
57 level in which micro-fracturing is occurring [8]. Crack growth happens at the instance of  
58 critical energy release and lasts until when the micro-cracks have joined and the structure can  
59 no longer support an increase in the load.

60

61 One of the elements appreciably influenced by the material heterogeneity, is the crack initiation  
62 angle, in particular for those systems that are subjected to mixed-mode loading conditions [9-  
63 11]. In a recent work, Lin and his co-workers [12] proved, with experimental measurements on  
64 acoustic emissions of mortar materials, that the crack angle is correlated with the magnitude of  
65 the initiation and the failure stresses. The importance of crack initiation angle has also been

66 recognised by Park and Lange [13], in which a new fracture parameter, named critical crack  
67 opening angle, describing the crack opening resistance, has been introduced for cement-based  
68 materials. Yang et al. [14] studied the effect of loading type and heterogeneity on the crack  
69 geometry, initiation and propagation processes, and concluded that local stresses control crack  
70 initiation process, while the loading configuration is responsible for crack inclination and  
71 curving. Evangelatos and Spanos [15] used the peridynamic theory to study the effect of the  
72 inclination of crack initiation angle on the total energy of a system, estimation of its reliability  
73 and its probability of failure.

74 Another crucial material property, influencing crack initiation and propagation process, is  
75 fracture toughness, which represents the critical stress intensity factor (SIF) at crack tip, that  
76 can introduce catastrophic crack growth. Fracture toughness is a function of applied loading,  
77 crack size and structural geometry, and it is representative of the level of “stress” at the tip of  
78 the crack [11]. A high value of fracture toughness makes materials resistant to catastrophic  
79 crack extension; alternatively, it may be considered as requiring a large amount of strain energy  
80 to create new surfaces.

81 An accurate and rigorous evaluation of fracture toughness is therefore indispensable for  
82 application of fracture mechanics methods in structural integrity assessment. The American  
83 Society for Testing and Materials (ASTM) provides standard terminology and formulations  
84 with regards to experimental measurements of fracture toughness [16-17]. In parallel with the  
85 experimental methods, closed form solutions for analytical calculation of fracture toughness,  
86 for determined geometries and loading configurations, have also been developed, and they are  
87 expressed as linear combination of SIFs for different crack opening modes [18-24].

88 If for a given problem that has to be examined, no experimental measurement of fracture  
89 toughness is conducted, often values for fracture toughness are chosen from the literature.  
90 However, not necessarily a specific value can be used for specific case studies, as fracture  
91 toughness depends not only on the constituents of the material, but also on other factors such  
92 as geometrical configurations and loading conditions. This assumption may therefore lead to  
93 erroneous results and, possibly, to an overestimation of the material resistance.

94 One of the analytical criteria, which is most frequently used for investigating mixed mode  
95 fracture toughness, is the maximum tangential stress (MTS) criterion, where fracture toughness  
96 is explicitly expressed as a function of mode I and II SIFs and of the crack initiation angle.  
97 Several studies (e.g. [25-26]) revealed that this method, which considers the tangential stresses  
98 in the vicinity of the crack tip, especially in the case of mixed mode fracture may not provide  
99 reliable values of fracture toughness. Ayatollahi and Aliha [25], for example, conducted a

100 detailed study on this matter, reporting experimental values of fracture toughness of four  
101 different types of rock materials and comparing them with the analytical results from the MTS  
102 method; they showed that if the effect of a non-singular stress term, called  $T$ -stress, is  
103 considered, then a better agreement between analytical and experimental results can be  
104 achieved. This modified criterion, called generalised maximum tangential stress (GMTS)  
105 method, has been applied for several specimens subjected to mixed-mode loading, but none of  
106 them includes the effect of material heterogeneity in the calculation of the fracture toughness.  
107 The aim of this study is therefore to extend and implement the definition of the GMTS criterion  
108 for materials with heterogeneous structure.

109 The computational framework used in this study for extracting a probabilistic distribution of  
110 the crack initiation angle, employs a phase-field formulation [27], in which the initiation and  
111 evolution of crack are described by a scalar damage variable assuming values in the range  $(0,1)$ ,  
112 where 1 means sound material, and 0 means totally broken material. The non-local analysis of  
113 the damage field evolution in an area in proximity of the crack initiation point allows to  
114 determine in which direction crack is most likely to propagate. Crack propagation direction is  
115 predicted using a probabilistic approach which includes a linear combination of different  
116 Probability Density Functions (PDF) of crack initiation angle.

117 Finally, in the context of stochastic modelling, energy release rate is defined as a function of  
118 the randomly variable fracture toughness and a probabilistic distribution of the damage  
119 initiation in the fracturing body is sought. Therefore, the damage state in proximity of the crack  
120 initiation point is considered to define realistic values of fracture toughness, which is a function  
121 of initial crack angle, loading condition and geometry. A probabilistic distribution for crack  
122 propagation direction is then defined and used for sampling the angle and calculating fracture  
123 toughness for the heterogeneous materials.

124 The main advantage of the method proposed in this work is the possibility to simply and  
125 practically quantify the uncertainty in the fracture toughness value evaluation as a function of  
126 other mechanical properties of the material which are directly introduced in a phase-field theory  
127 based framework for crack propagation. The material length scale, representative of the size of  
128 the damage zone, contributes in defining the degree of heterogeneity of the material. In this  
129 way, the statistical information (mean value, standard deviation and correlation length) needed  
130 for sampling random values for crack initiation angle will be automatically provided by the  
131 numerical simulations using the phase-field theory. Furthermore, it will be proved that the non-  
132 Gaussian nature of the fracture toughness and fracture energy can be automatically captured  
133 with this method using a Gaussian approach for the crack initiation angle, without the need to

134 any translation function for sampling random values of these material properties [4-5].

135

## 136 **2. Fracture advancement methodology and damage state of the body**

137 In this section, the basic ingredients of the phase-field model used to determine the initiation  
138 and propagation of fracture are presented. The variational model proposed in [27-28] is  
139 considered, where smeared fracture in an elastic body  $\Omega$  is described by means of a scalar  
140 damage field  $s$ , which assumes values in the range  $(0, 1)$ ; when  $s = 1$  the material is sound, and,  
141 when  $s = 0$ , it is totally damaged. The internal energy assigned to  $\Omega$  is

142

$$E(\mathbf{u}, s) = \int_{\Omega} \left\{ k \frac{1}{2} \text{tr}^-(\nabla \mathbf{u})^2 + s^2 \left[ k \frac{1}{2} \text{tr}^+(\nabla \mathbf{u})^2 + \mu \left( \nabla \mathbf{u}^2 - \frac{2}{3} \text{tr}(\nabla \mathbf{u})^2 \right) \right] \right\} dx \quad (1)$$
$$+ \frac{G_f}{2} \int_{\Omega} \left( \varepsilon \nabla s^2 + \frac{(1-s)^2}{\varepsilon} \right) dx$$

143

144 which depends on the displacement field  $\mathbf{u}$  and on the damage  $s$ . The first integral in Eq. (1)  
145 represents the bulk energy, where  $k = \lambda + 2\mu/3$  is the bulk modulus,  $\mu$  and  $\lambda$  are the Lamé's  
146 coefficients, and the decomposition  $\text{tr}^+(\nabla \mathbf{u}) = \max\{\text{tr}(\nabla \mathbf{u}), 0\}$  and  $\text{tr}^-(\nabla \mathbf{u}) = \{\text{tr}(\nabla \mathbf{u}), 0\}$  in  
147 positive and negative parts of the trace of  $\nabla \mathbf{u}$  is used. The second integral is the fracture energy,  
148 which is the sum of a local and a non-local contributions.  $G_f$  is the unit fracture energy, and  $\varepsilon$   
149 is an internal length associated to damage non-locality. The length  $\varepsilon$  is related to the size of the  
150 process zone, as discussed in the following. The energy (1) is minimised under the  
151 irreversibility condition  $\dot{s} \leq 0$ , introduced to forbid material self-healing.

152 By using the energy (1), different fracture processes are reproduced when tensile or  
153 compressive loadings are applied. Indeed, in regions of  $\Omega$  subjected to tensile states, where  
154 volume changes are positive, the opening and evolution of brittle fractures are allowed; while,  
155 in compressed regions, where volume changes are negative, cracks are partially forbidden, and  
156 only shear fractures can develop, when shear stresses are generated by compressive loadings.

157 When a fracture forms, the damage parameter  $s$  assumes the value  $s = 0$  on the fracture surface,  
158 and it increases by moving away from that surface. The optimal profile of  $s$  in the direction  
159 normal to the fracture surface was determined in [29], and its expression is

160

$$s(x) = 1 - e^{-\frac{|x-x_0|}{\varepsilon}}, \quad (2)$$

161

162 where  $x$  is the coordinate in the direction normal to the surface, and  $x_0$  is the intersection point  
 163 between the normal axis and the surface. From Eq. (2), at distances larger than  $2.5\varepsilon$  from the  
 164 surface ( $|x-x_0| > 2.5\varepsilon$ ), damage attains values  $s > 0.9$ , and the material can be considered  
 165 practically sound. Thus the damaged band around the fracture surface has a thickness of about  
 166  $5\varepsilon$ , which represents the size of the process zone.

167 The functional (1) is numerically minimised by using the incremental procedure first proposed  
 168 in [30], and described in the following. We denote with  $t$  the loading parameter of the problem  
 169 (load or displacement applied on a portion of the body boundary), which is monotonically  
 170 increased from 0 by means of finite increments. At each loading step, an iterative procedure is  
 171 performed. Let  $(\mathbf{u}_{i-1}, s_{i-1})$  be the solution at the  $(i-1)$ th loading step, the pair  $(\mathbf{u}_i, s_i)$  at the  $i$ th step  
 172 is evaluated by solving the iterative double minimisation procedure shown below.

- 173 1. *Initiation.* Set  $(\mathbf{u}_i^0, s_i^0) = (\mathbf{u}_{i-1}, s_{i-1})$
- 174 2. *Iteration j.* For given  $(\mathbf{u}_i^{j-1}, s_i^{j-1})$ 
  - 175 i. compute  $\mathbf{u}_i^j$  by minimizing  $E(\cdot, s_i^{j-1})$
  - 176 ii. compute  $s_i^j$  by minimizing  $E(\mathbf{u}_i^j, \cdot)$
  - 177 iii. *Irreversibility condition:* set  $s_i^j(x) = \min\{s_i^j(x), s_{i-1}(x)\}, x \in \Omega$
- 178 3. Iterate step 2 until  $\|s_i^j - s_i^{j-1}\|_{L^\infty} < s_{\max}$ , with  $s_{\max}$  being a fixed tolerance.

179 At the step  $i = 0$  it is set that  $(\mathbf{u}_0, s_0) = (\mathbf{0}, 1)$ , so the body is assumed undeformed and uncracked  
 180 in the initial configuration.

181 The minimizations at steps *i.* and *ii.* are performed by finding the stationarity point of (1),  
 182 keeping  $s$  and  $\mathbf{u}$  fixed, respectively. The corresponding problems are linear elliptic and  
 183 solutions are numerically found by means of the finite element method. Within the Matlab  
 184 environment, an in-house code is developed based on triangular elements with affine shape  
 185 functions. To improve the accuracy in the determination of the field  $s$ , the program includes a  
 186 mesh refinement algorithm, which automatically subdivides those elements at which the values  
 187 of  $s$  become smaller than a given threshold. As a result, within each loading step, in the  
 188 algorithm an iterative macro-scheme, which includes the process described above, allows for  
 189 the mesh refinement. While the convergence of the developed algorithm has not been proven  
 190 theoretically, however the numerical experiments show a fast convergence.

191 In the next sections, two dimensional simulations are performed by assuming the hypothesis  
192 of plane strain state.

193

### 194 **3. Fracture toughness calculation: the GMTS criterion**

195 In the context of linear elastic fracture mechanics, elastic stresses in proximity of the crack tip  
196 can be written as linear combinatio of angular functions expanded according to infinite series  
197 [25]. Based on the GMTS criterion, for a brittle material, crack propagates radially and  
198 perpendicular to the direction of maximum tangential stress; the crack initiation point is where  
199 the tangential stress  $\sigma_{\theta\theta}$  reaches its critical value, and along this direction crack initiates at  $r_c$   
200 defined as the critical distance from the crack tip. It is considered that  $r_c$  is a constant material  
201 property; it is usually considered to be equal to the radius of the process zone. Several methods,  
202 both experimental and numerical, have been proposed to estimate the size of this zone for brittle  
203 materials [25, 31]. In this work,  $r_c$  is considered to be compatible with the size of the process  
204 zone estimated on the basis of the theory discussed in the Section 2, therefore, equal to  
205  $5\varepsilon$ . Formulation of the tangential stress in the vicinity of crack tip is therefore explicitly given  
206 as series expansion in [25] as

207

$$\sigma_{\theta\theta} = \frac{1}{\sqrt{2\pi r}} \cos \frac{\theta}{2} \left[ K_I \cos^2 \frac{\theta}{2} - \frac{3}{2} K_{II} \sin \theta \right] + T \sin^2 \theta + O(\sqrt{r}) \quad (3)$$

208

209 where  $r$  and  $\theta$  are the polar coordinates of a point with respect to the crack tip,  $K_I$  and  $K_{II}$  are  
210 the SIFs for mode I and II respectively and  $T$  is the  $T$ -stress, which is a constant term defining  
211 the stress parallel to the crack and independent of  $r$ , the higher order term  $O(\sqrt{r})$  of the  
212 expansion can be neglected in proximity of the crack tip.

213 Recalling that crack initiates and propagates in the direction of maximum tangential stress, the  
214 crack initiation angle  $\theta_0$  (angle that indicates the direction with respect to the direction of the  
215 initial notch, where the maximum stresses are found) can be calculated by imposing the  
216 condition

217

$$\frac{\partial \sigma_{\theta\theta}}{\partial \theta} \Big|_{\theta=\theta_0} = 0. \quad (4)$$

218

219 The calculated angle is used for obtaining the value of the fracture toughness of mixed-mode  
220 fracture. Brittle failure happens when  $\sigma_{\theta\theta}$  reaches its critical value  $\sigma_{\theta\theta c}$ . This condition

221 provides the following expression [25]

222

$$\sqrt{2\pi r_c} \sigma_{\theta\theta c} = \cos \frac{\theta_0}{2} \left[ K_I \cos^2 \frac{\theta_0}{2} - \frac{3}{2} K_{II} \sin \theta_0 \right] + T \sin^2 \theta_0. \quad (5)$$

223

224 If now the pure mode-I fracture case is considered,  $K_{II}$ ,  $T$  and  $\theta_0$  all become equal to zero.

225 Therefore, when fracture occurs  $K_I$  reaches its critical value  $K_{Ic}$  which corresponds to the  
226 mode-I fracture toughness

227

$$\sqrt{2\pi r_c} \sigma_{\theta\theta c} = K_{Ic}. \quad (6)$$

228

229 Eq. (5) can be rewritten using Eq. (6) to obtain the value for fracture toughness  $K_{Ic}$

230

$$K_{Ic} = \cos \frac{\theta_0}{2} \left[ K_I \cos^2 \frac{\theta_0}{2} - \frac{3}{2} K_{II} \sin \theta_0 \right] + T \sin^2 \theta_0. \quad (7)$$

231

232 The expression in Eq. (7) represents the final form of the GMTS criterion. Closed form  
233 solutions for  $K_I$ ,  $K_{II}$  and  $T$  have been calculated for defined geometries and loading  
234 configurations [25-26, 32-37].

235 General expression for  $K_I$  and  $K_{II}$  takes the general form

236

$$K_I = \sigma^* \sqrt{\pi a} F_I \left( \frac{a}{W} \right) \quad (8)$$

$$K_{II} = \sigma^* \sqrt{\pi a} F_{II} \left( \frac{a}{W} \right), \quad (9)$$

237

238 where  $\sigma^*$  represents the stress field in correspondence of the crack tip,  $a$  provides information  
239 about the position and the length of the crack,  $W$  is a measure of the body geometry,  $F_I \left( \frac{a}{W} \right)$   
240 and  $F_{II} \left( \frac{a}{W} \right)$  are dimensionless functions of the geometry of the notched body and of the  
241 experimental setup. For calculating the values for  $T$ , one of the most common methods is based  
242 on its calculation from finite element analysis as shown by Ayatollahi et al. [26].

243

#### 244 **4. Uncertainty quantification: the spectral representation method**

245 In this work, uncertainty is included in the model by sampling random values of  $\theta_0$  using the

246 spectral representation method. With this method, a stochastic field of a two dimensional  
 247 problem is expressed as [5]

$$\begin{aligned} \theta_g^{(i)}(x, y) = \theta_0 + \sqrt{2} \sum_{n_1=0}^{N_1-1} \sum_{n_2=0}^{N_2-1} [A_{n_1 n_2}^{(1)} \cos(\kappa_{1n_1} x + \kappa_{2n_2} y + \phi_{n_1 n_2}^{(1)(i)}) \\ + A_{n_1 n_2}^{(2)} \cos(\kappa_{1n_1} x - \kappa_{2n_2} y + \phi_{n_1 n_2}^{(2)(i)})] \end{aligned} \quad (10)$$

248

249 where  $\phi_{n_1 n_2}^{(1)(i)}$  and  $\phi_{n_1 n_2}^{(2)(i)}$  are the realisation for the  $i$ th simulation of the independent random  
 250 phase angles which follow a uniform distribution. Furthermore,

$$A_{n_1 n_2}^{(1)} = \sqrt{2S_{gg}(\kappa_{1n_1}, \kappa_{2n_2})\Delta\kappa_1\Delta\kappa_2} \quad (11a)$$

$$A_{n_1 n_2}^{(2)} = \sqrt{2S_{gg}(\kappa_{1n_1}, -\kappa_{2n_2})\Delta\kappa_1\Delta\kappa_2} \quad (11b)$$

251

$$\kappa_{1n_1} = n_1\Delta\kappa_1 \quad (12a)$$

$$\kappa_{2n_2} = n_2\Delta\kappa_2 \quad (12b)$$

252

$$\Delta\kappa_1 = \kappa_{1u}/N_1 \quad (13a)$$

$$\Delta\kappa_2 = \kappa_{2u}/N_2 \quad (13b)$$

253

254 with

$$n_1 = 0, 1, \dots, N_1 - 1; \quad n_2 = 0, 1, \dots, N_2 - 1. \quad (14)$$

255

256  $N_1$  and  $N_2$  are the number of intervals where the wave number axes are split,  $\kappa_{1u}$  and  $\kappa_{2u}$  are  
 257 defined as the upper cut-off wave numbers defining the active region of the spectral density  
 258 function (SDF)  $S_{gg}$ . Therefore, the effect of  $S_{gg}$  is operative only for the range

259

$$-\kappa_{1u} \leq \kappa_1 \leq \kappa_{1u} \quad \text{and} \quad -\kappa_{2u} \leq \kappa_2 \leq \kappa_{2u}; \quad (15)$$

260

261 outside of this range,  $S_{gg}$  is assumed to be equal to 0.

262 In this work, the SDF takes the form of [5]

263

$$S_{gg} = \sigma_g^2 \frac{b_1 b_2}{4\pi} \exp \left[ -\frac{1}{4} (b_1^2 \kappa_1^2 + b_2^2 \kappa_2^2) \right] \quad (16)$$

264

265 where  $\sigma_g$  is the standard deviation of the field, while  $b_1$  and  $b_2$  represent the correlation length  
266 along the two dimensions.

267

## 268 **5. PDF of the crack initiation angle $\theta_0$**

269 The uncertainty in the material behaviour is related to heterogeneity of the materials strength  
270 that is modelled by defining a random distribution of damage inside of simulation domain.

271 Therefore, similar to the work presented by Gutierrez and de Borst [45], damage parameter  
272 instead of material stiffness or fracture energy has been selected as a random parameter.

273 However, due to lack of experimental data and information about the statistics of damage  
274 distribution throughout of the material, a computational model has been used to generate a

275 hypothetical possible spatially random field for damage parameters associated to materials with  
276 different micro-structure and length scales. The random distribution of damage parameter is

277 linked with the material length scale and particle size distribution (as an index of material  
278 heterogeneity) through specifying several threshold values for  $\bar{s}$ . This aspect also overcomes

279 the issue of the mesh dependency, as the size of the mesh is directly connected to the material  
280 length scale as shown in Section 6 in the definition of the parameters for Eq. (1). Different

281 threshold values for damage parameter  $\bar{s}$  have been selected in a way to take into account both  
282 the influence of distribution of imperfection in the whole specimen and the possible variations

283 in the size of the specimens. Without this, the approach would not be non-local, as it would  
284 consider only the damage in proximity of the crack tip.

285

286 Therefore, for a given body discretised in finite elements and for a given crack initiation point,  
287 positions of the finite element nodes with respect to the crack tip and associated values of  $s$  are

288 considered. In order to accurately take into account the contribution of the damage state of the  
289 body in the definition of  $\theta_0$ , the so-called fracture process zone (FPZ) should be adequately

290 identified. The FPZ can be identified numerically with the phase-field theory described above.

291 In fact, the damage will spread from the crack tip at a distance which will be included within  
292 typical FPZs identified by several works [25, 38-39].

293 The values for damage in each node provide information about the direction that the crack is  
 294 most likely to initiate and propagate: in particular, it is likely that the crack spreads through  
 295 those nodes with a lower value of damage. Therefore, the degree of damage that develops in  
 296 the body is considered in the procedure formed by the following steps:

- 297 1. Calculate the values for damage parameter by using the iterative procedure described  
 298 in Section 2;
- 299 2. For different threshold values  $\bar{s}$ , select the nodes with  $s \leq \bar{s}$ ;
- 300 3. Calculate the polar coordinates with respect to the crack tip of the nodes selected in step  
 301 2;
- 302 4. Estimate mean value of  $\theta_0$  for each threshold value  $\bar{s}$ ;
- 303 5. Calculate the overall mean value and the standard deviation of  $\theta_0$  from the values  
 304 estimated in step 4 for each  $\bar{s}$ ;
- 305 6. Sample values of  $\theta_0$  using the spectral method described in Section 4 and calculate the  
 306 corresponding values of  $K_{Ic}$  using Eq. (7).

307 Through this method,  $\theta_0$  becomes the parameter with stochastic nature and can be then  
 308 expressed as a vector  $\boldsymbol{\theta}_{0g} = [\theta_g^{(1)}, \theta_g^{(2)}, \dots, \theta_g^{(n_{FE})}]$ , with  $n_{FE}$  being the number of elements  
 309 forming the finite element mesh that discretises the problem under investigation. Therefore,  
 310 the probabilistic generalised maximum tangential stress (PGMTS) criterion can be achieved in  
 311 terms of  $\theta_{0g}$  using Eq. (7) as

$$312 \quad K_{Ic}(\boldsymbol{\theta}_{0g}) = \cos \frac{\boldsymbol{\theta}_{0g}}{2} \left[ K_I \cos^2 \frac{\boldsymbol{\theta}_{0g}}{2} - \frac{3}{2} K_{II} \sin \boldsymbol{\theta}_{0g} \right] + T \sin^2 \boldsymbol{\theta}_{0g}. \quad (17)$$

313 Finally, fracture energy  $G_f$  can also be calculated using the elastic crack-tip solution and a  
 314 simple relationship between  $K_{Ic}$  and  $G_f$  as [40]:  
 315

$$\frac{K_{Ic}^2}{E'} = G_f, \quad (18)$$

316 which is developed based on the theories of Griffith [7]. In the Eq. 18,  $E' = E$  for the plane  
 317 stress conditions, and  $E' = E/(1 - \nu^2)$  for the plane strain conditions with  $E$  being Young's  
 318 modulus and  $\nu$  Poisson's ratio.

319

## 320 6. Numerical analyses and discussion of the results

### 321 6.1. Notched concrete slab

322 In order to verify the proposed methodology, the first example considered in this study is a  
323 finite element model of a concrete slab with size of 500 mm x 400 mm (see Fig. 1). This  
324 example was also simulated by Huang et al. [41]. Young's modulus  $E$  and Poisson's ratio  $\nu$  are  
325 chosen equal to 25000 N/mm<sup>2</sup> and 0.18 respectively. An initial deterministic value for  $G_f$  equal  
326 to 0.15 N/mm is assigned to the model [3]. A value of  $\varepsilon = 8$  mm is selected, while the size of  
327 the mesh is chosen to be equal to 8 mm. The value for  $\varepsilon$  is chosen, following the considerations  
328 listed in [29], on the basis of the average size of the material constituents; in particular,  $\varepsilon$  is  
329 typically assumed to be 2-3 times the characteristic material length scale. As concrete is formed  
330 by constituents of different sizes, an average dimension of 4-5 mm is here considered and,  
331 consequently, the value of 8 mm for  $\varepsilon$  is selected. An initial crack of dimension 4 x 40 mm is  
332 modelled in the middle of the specimen. In order to create a typical mixed mode crack  
333 condition, the inclination of the crack with respect to the distributed load is set to be 45°. The  
334 simulation is performed in quasi-static displacement-controlled condition.

335 In order to calculate  $K_{Ic}$  using Eq. (7), the value of  $r_c$  has been selected according to the  
336 recommendations proposed in [25 and 38-39]. In [25]  $r_c$  is calculated for the brittle materials  
337 as a function of  $K_{Ic}$  and a range of values between 45 and 60 N/mm<sup>3/2</sup> was assumed for  $K_{Ic}$ ,  
338 which gives a range of values between 35 and 45 mm for  $r_c$ , approximately. In [38] and [39] a  
339 combination of analytical and experimental investigations on concrete specimens subjected to  
340 both pure mode-I and mixed-mode loading provided a range of values for the size of FPZ,  
341 which vary from a minimum of 40 up to a maximum of 140 mm. Therefore, the value of  $r_c$  for  
342 this example is chosen equal to 40 mm which is within the range proposed in the literature.

343 For this specific example, the explicit formulation of Eq. (8) and (9) are expressed, together  
344 with the explicit expression for  $T$ , as [32]

345

$$K_I = \sigma \sqrt{\pi a} \sin^2 \beta \quad (19a)$$

$$K_{II} = \sigma \sqrt{\pi a} \sin \beta \cos \beta \quad (19b)$$

$$T = \sigma \cos 2\beta \quad (19c)$$

346

347 where,  $\sigma$  is applied stress to the body,  $a$  is half length of the initial notch, and  $\beta$  is inclination  
348 angle of the notch with respect to the loading direction. For this example  $\sigma = 8.6$  N/mm<sup>2</sup>,  $a =$   
349 20 mm and  $\beta = 45^\circ$  [41].

350 Fig. 2 shows the evolution of the damage in proximity of the crack tip that has been taken into  
 351 account to generate PDFs of  $\theta_0$ . For simplicity, only the upper half of the specimen is  
 352 considered and presented in Fig. 2. The area where the damage spreads, is smaller than the size  
 353 of FPZ considered in literature [38-39], which vary from a minimum of 40 mm up to a  
 354 maximum of 140 mm for pure mode I failure.

355 Table 1 summarizes the values obtained for crack initiation angle with respect to the direction  
 356 of the notch, considering different values of  $\bar{s}$  together with the calculated mean value and  
 357 standard deviation. In order to validate the result, the mean value is compared with the results  
 358 from literature [41] and with the value calculated considering the condition [25]

$$[K_I \sin \theta_0 + K_{II} (3 \cos \theta_0 - 1)] - \frac{16}{3} T \sqrt{2\pi r_c} \cos \theta_0 \sin \frac{\theta_0}{2} = 0 \quad (20)$$

360 which is the explicit form of Eq. (4). For this example, Huang et al. [41] provided a value for  
 361 crack initiation angle equal to  $53.1^\circ$ , while the result obtained using Eq. (20) is  $52.7^\circ$ . The  
 362 summary of all the results can be found in Table 1. It can be observed that the value reported  
 363 in [41] and the value calculated through the methodology proposed in this work differ about  
 364  $4^\circ$ .

365  
 366 The mean value and standard deviation shown in Table 1 are then considered as an estimate to  
 367 sample random values for  $\theta_0$  using the Gaussian process shown in Eq. (10).

368 In the first instance, a deterministic value of the fracture toughness is calculated using Eq. (7)  
 369 and the mean value of  $\theta_0$ . The fracture toughness is therefore equal to  $60.9 \text{ N/mm}^{3/2}$ . Griffith's  
 370 Energy  $G_f$  is then calculated as  $G_f = 0.14 \text{ N/mm}$ , consistent with the range of values of  $G_f$  for  
 371 concrete found in literature [3, 42].

372 This example is one of those used in literature to study mixed-mode conditions for the  
 373 materials. For this reason, this example has been used with the main purpose of comparing the  
 374 crack initiation angle available in literature with the value crack initiation angle as mean value  
 375 of the probabilistic distribution obtained.

376 With regards to the parameters involved in the stochastic approach described in section 4, the  
 377 number of terms used for the spectral representation series is chosen as  $N_1 = N_2 = 20$ , the cut-  
 378 off wave numbers  $\kappa_{1u} = \kappa_{2u} = 2\pi$  and  $b_1 = b_2 = 1$  [30]. Once the mean value and standard  
 379 deviation for  $\theta_0$  are defined, they are used to sample values of  $\theta_0$  according to a Gaussian  
 380 distribution, as shown in Fig. 3. This sample for  $\theta_0$  is then substituted into the expression for  
 381  $K_{Ic}$  of Eq. (7), and a sample for  $K_{Ic}$  is then obtained as shown in Fig. 4. The sample shown has

382 a mean value of  $60.5 \text{ N/mm}^{3/2}$ . The calculated values of  $K_{Ic}$  can finally be used to get a  
383 distribution, shown in Fig. 5, of the values for  $G_f$  with mean value  $0.14 \text{ N/mm}$  and standard  
384 deviation of approximately 5%. It is worth noting, as shown in the Figs. 4 and 5, that the values  
385 of  $K_{Ic}$  and  $G_f$  don't follow the same Gaussian trend of  $\theta_0$ , but a non-Gaussian trend. In  
386 particular, the probability functions plotted in the Figs. 4 and 5 follow a Weibull distribution.  
387 This trend is consistent with the conclusion from several works [3, 5] that heterogeneous  
388 distributions of  $G_f$  follow a non-Gaussian (either lognormal or Weibull) distributions. This  
389 results show that the proposed methodology is capable to automatically capture the non-  
390 Gaussian distribution of a given normally-distributed statistical information (e.g. mean value,  
391 standard deviation, correlations), using the translation field functions, which satisfy specific  
392 constrains and compatibility conditions associated to the related random field [5]. In fact,  
393 despite the simplicity of the Gaussian distributions for sampling from simple statistical  
394 information, their use for creating a sample of fracture toughness may lead to the generation of  
395 negative, and therefore physically meaningless, values. With the method proposed in this work,  
396 we will be able to benefit from the simplicity of Gaussian field theory while generating a  
397 realistic and physically meaningful distribution for  $K_{Ic}$ .

398

### 399 6.2 The four-point Single-Edge Notched Shear (SENS) beam

400 The second example used in this study is the four-point SENS beam studied in [43]. This  
401 benchmark is one of the most widely used to validate numerical models for simulating mixed-  
402 mode crack propagation in concrete. A wide range of experimental data is available in  
403 literature, and a satisfactory crack scatter is available and has been summed up in [44].  
404 Specimen geometry, boundary conditions and material properties about this benchmark are  
405 shown in Fig. 6. Young's modulus  $E$  is equal to  $24800 \text{ N/mm}^2$ , and Poisson's ratio is equal to  
406 0.18. Because also for this second case study a concrete specimen is considered, a value for  
407  $\varepsilon = 8 \text{ mm}$  is again selected, while the size of the mesh is chosen equal to  $5 \text{ mm}$ . For the same  
408 reason, the values for the parameters involved in the definition of the spectral representation  
409 method are chosen as in the previous case study.

410 For this benchmark, the explicit form of Eq. (8) and (9) for  $K_I$  and  $K_{II}$  take the form [18]

411

$$K_I = \frac{F}{BW} \left(1 - \frac{d}{L}\right) F_{I1} \sqrt{\pi a} \quad (21a)$$

$$K_{II} = \frac{F}{BW} \left(1 - \frac{d}{L}\right) F_{II1} \sqrt{\pi a} \quad (21b)$$

412

413 where  $F$  is the force applied to the specimen, and is selected equal to 132.2 kN,  $B$  is the  
414 specimen thickness equal to 152 mm,  $W$  is the specimen height equal to 306 mm,  $d = 61$  mm  
415 is the distance from the middle of the specimen of the force applied and the pin,  $L$  is half of  
416 the total length of the specimen equal to 458 mm and  $a$  is the length of the initial notch equal  
417 to 82 mm.  $F_I$  and  $F_{II}$  are geometry functions depending on specimen geometry and their values  
418 for these two functions are available in [18]. Value for  $T$  is equal to  $-0.04 \text{ N/mm}^2$ , calculated  
419 in [35] from Finite Elements analysis. As discussed by Smith et al. [32],  $T$  can have negative  
420 values.

421 For this example, from Eq. (21a) and (21b),  $F_I = -0.1$  and  $F_{II} = 1.12$ . Mode-I and Mode-II SIFs  
422 can be hence calculated and they are equal to  $-3.9 \text{ N/mm}^{3/2}$  and  $44.5 \text{ N/mm}^{3/2}$ . It is worth  
423 noticing that Mode-I SIF has also a negative value. This happens when (i) shear-mode is  
424 prevalent on opening-mode mechanisms and (ii) crack lips closure prevails over crack opening  
425 [35]; therefore, physically this means that mode-I opening mode has a very small influence of  
426 the fracturing process. With this regards, Fig. 7 shows the variation of  $F_I$  over the variation of  
427 the ratio  $d/W$  (as  $d/W$  increases, the shear failure prevails over opening failure). It can be seen  
428 that when  $d/W$  decreases, shear effect increases, making the value for  $F_I$  smaller, until it  
429 disappears for  $d/W > 1.5$ .

430 Fig. 8 shows the evolution of damage in proximity of the initial notch, and it is considered for  
431 the generation of the mean value and standard deviation of  $\theta_0$ . As can be seen, also for this  
432 case study the area where the damage spreads is compatible with the size of FPZ considered in  
433 literature [25, 38-39].

434 Table 2 summarizes the values of crack initiation angle with respect to the direction of the  
435 initial notch, obtained considering different values of  $\bar{s}$  together with the calculated mean value  
436 and standard deviation.

437 The obtained mean value of  $\theta_0$  is equal to  $74.1^\circ$  with respect to the direction of the initial notch.  
438 The value of  $\theta_0$  calculated using Eq. (20) is equal to  $72.2^\circ$ , which is in good agreement with  
439 the value obtained numerically. As for the previous example, the deterministic values of  
440 fracture toughness and fracture energy are first calculated:  $K_{Ic}$  is equal to  $48.1 \text{ N/mm}^{3/2}$  while  
441 Griffith's Energy  $G_f$  is then calculated as  $G_f = 0.095 \text{ N/mm}$ .

442 Once the mean value and standard deviation for  $\theta_0$  are defined as listed in Table 2, different  
443 values of crack initiation angle are sampled using the spectral approach, as shown in Figure 9.  
444 This sample is then used together with the expression for  $K_{Ic}$  (i.e., Eq. (7)), and a sample for  
445  $K_{Ic}$  is then obtained as shown in Fig. 10. The sample has a mean value of  $48.22 \text{ N/mm}^{3/2}$ . The

446 calculated values of  $K_{Ic}$  is finally used to get a distribution of the values for  $G_f$  which have  
447 mean value of 0.094 N/mm and standard deviation of approximately 4%. It is worth noting, as  
448 shown in Figs. 10 and 11, that also for this example  $K_{Ic}$  and  $G_f$  follow a log-normal trend,  
449 consistent with the conclusion from the previous example and from literature [3,5] that  
450 heterogeneous distributions of  $K_{Ic}$  and  $G_f$  follow a non-Gaussian trend.

451

## 452 **7. Conclusions**

453 A novel approach for uncertainty quantification of the random fields in the physical domains  
454 is presented. The uncertainty in the mechanical properties of the bodies subjected to damage is  
455 quantified by considering the damage state developed in the vicinity of the crack initiation  
456 points. Distribution of the damage, predicted using a phase-field model capable of reproducing  
457 mixed mode loading conditions, is then employed to estimate the mean value and the standard  
458 deviation for direction of crack evolution in the body. This statistical information is then used  
459 to create samples for the crack initiation angle by means of the Gaussian spectral representation  
460 approach. The calculated sample is finally used to calculate spatially-varying values of the  
461 fracture toughness, and consequently the fracture energy for the mixed-mode crack propagation  
462 conditions. In first instance, a concrete slab with an internal notch with an inclination of  $45^\circ$   
463 and subjected to uniaxial traction is studied. Calculated mean value for the crack initiation  
464 angle ( $57.1^\circ$ ), is in a good agreement with value of the crack initiation angle found in literature  
465 ( $53.1^\circ$ ), with a difference of only  $4^\circ$ . The second example studied is the four-point bending  
466 beam, one of the examples most widely used to validate models considering the mixed-mode  
467 conditions. Also for this case study, the mean value for the crack initiation direction ( $74.1^\circ$  with  
468 respect to the direction of the initial notch) is in very good agreement with the value calculated  
469 analytically ( $72.2^\circ$ ). For both examples, the calculated values of the fracture toughness and the  
470 fracture energy are in excellent agreement with values from literature. Furthermore, the most  
471 interesting aspect of this method is its capability, by using Gaussian-related statistical  
472 information, to capture the non-Gaussian nature of the statistical distribution of the fracture  
473 toughness and fracture energy for brittle materials.

474

## 475 **Acknowledgement**

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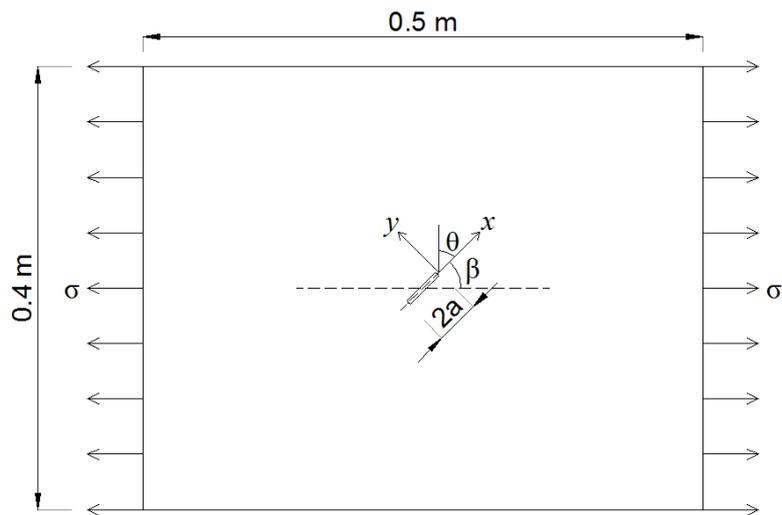
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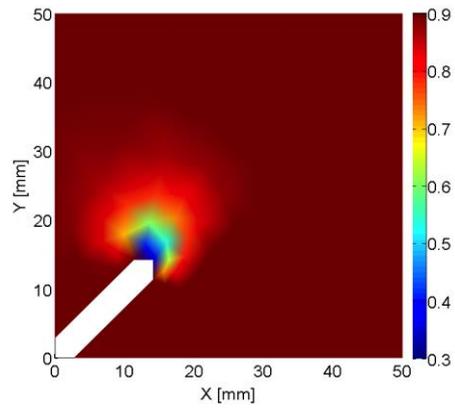
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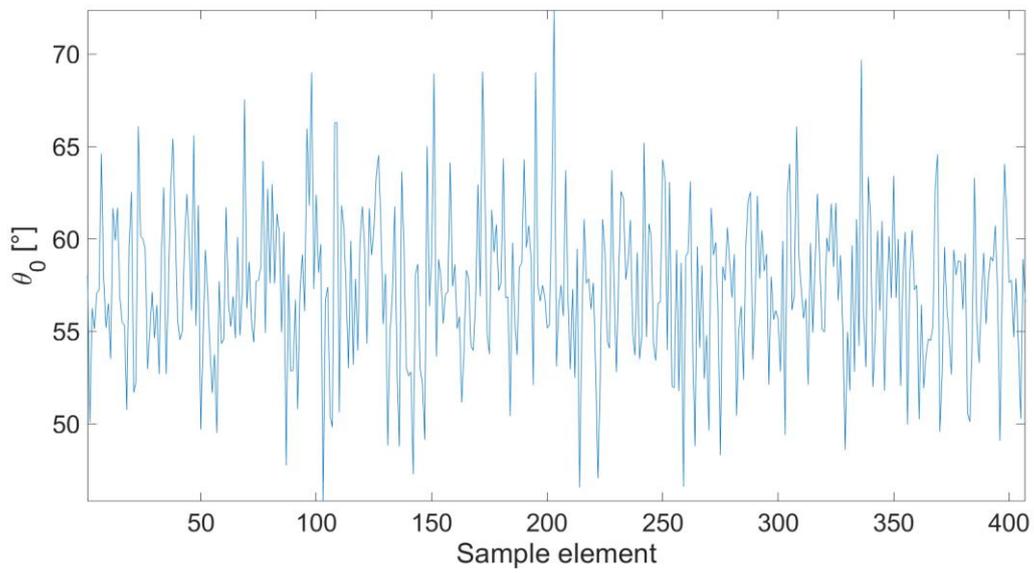
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**Fig 1.** Geometry and loading condition of the considered concrete panel with an inclined central notch.

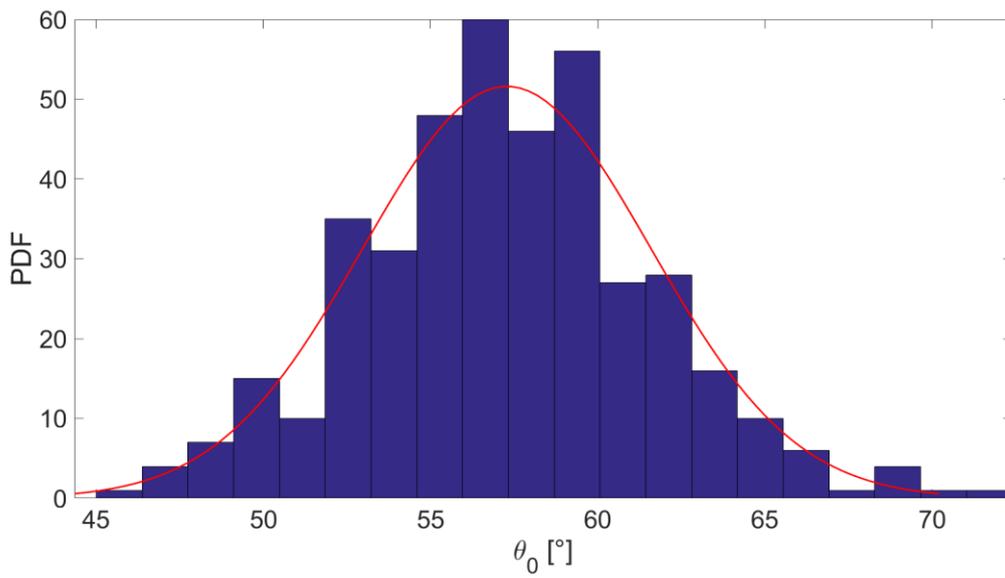


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**Fig 2.** Local area in proximity of the crack tip for the notched concrete panel: the effect of the damage influences the direction of crack initiation considering the damage state at the time step immediately before failure starts.

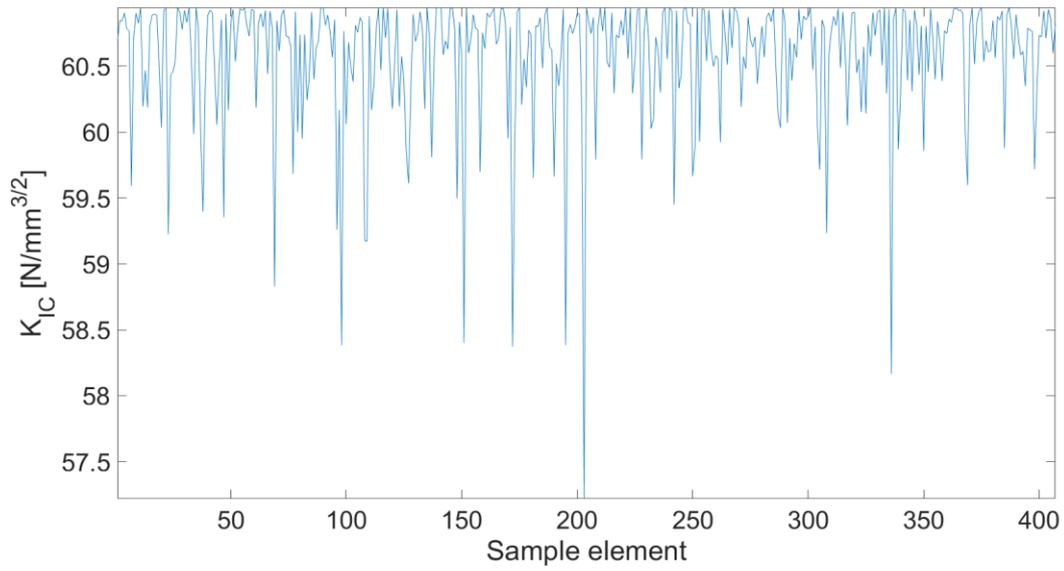


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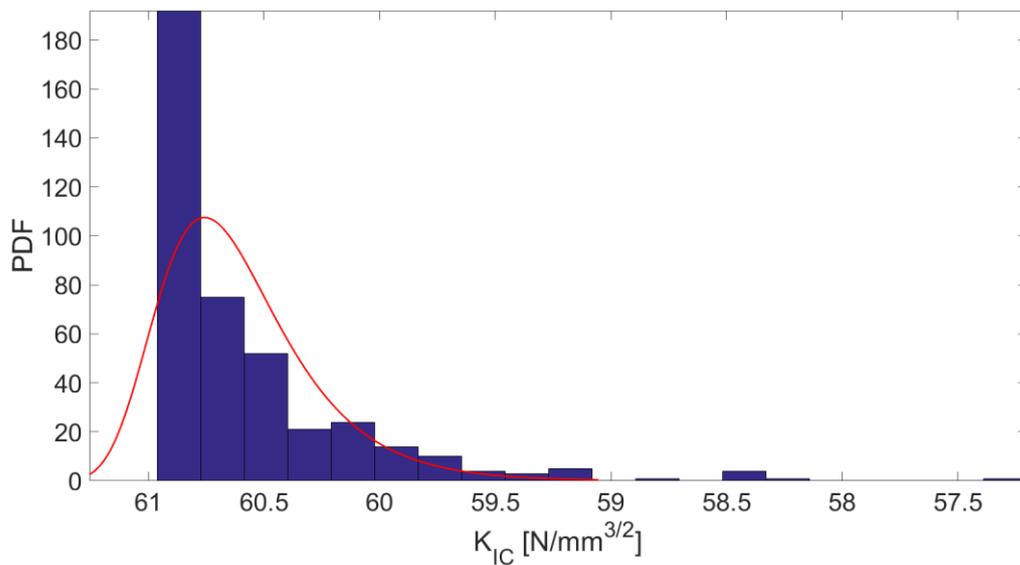


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613 **Fig 3.** Sample for 350 values of  $\theta_0$  (top) and PDF with Gaussian nature (bottom). The method shown in Eq. (10)  
 614 is used to generate each sample.



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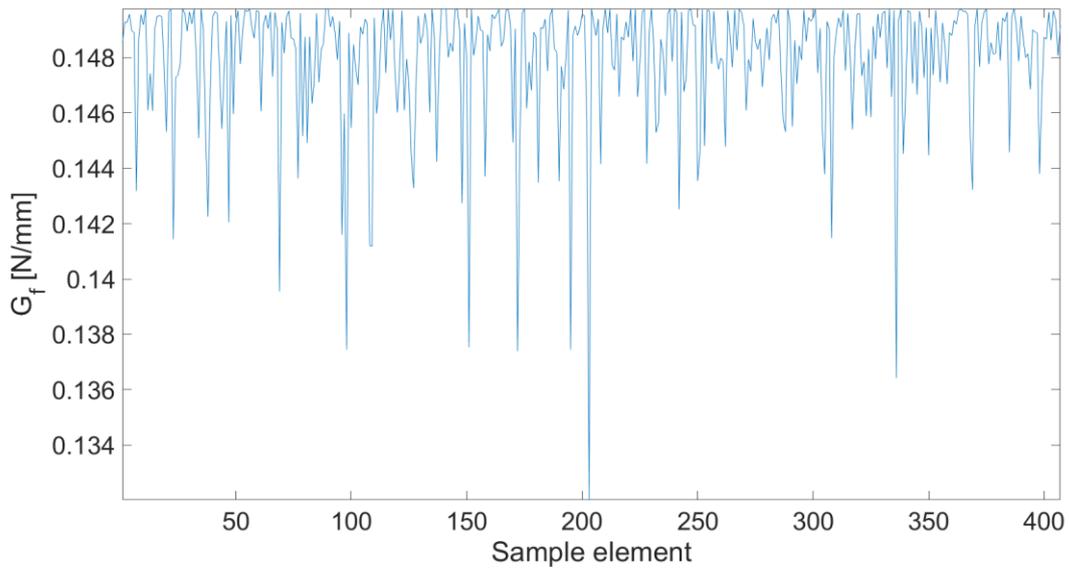


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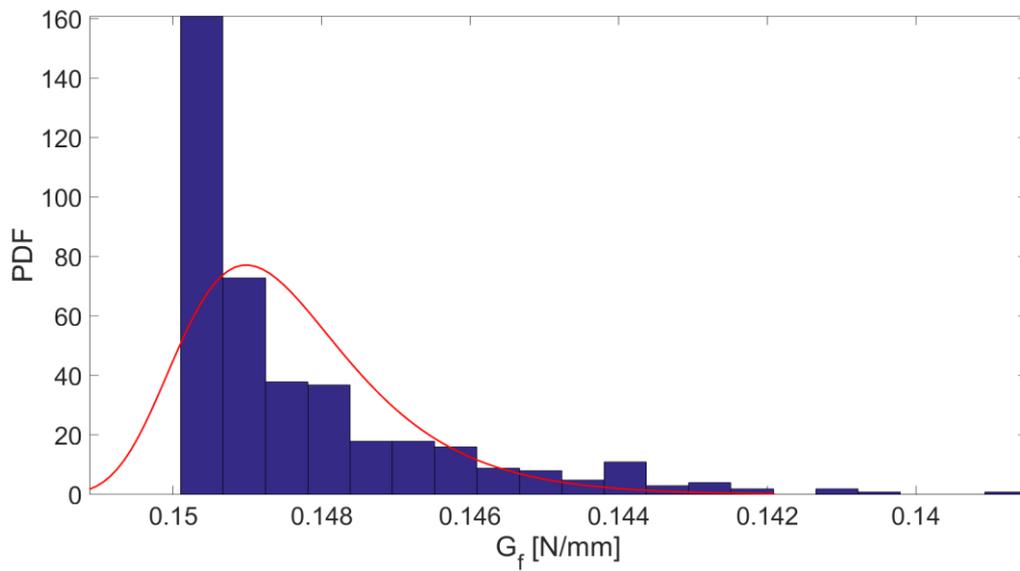
617 **Fig 4.** Sample of  $K_{IC}$  generated from the sample of crack initiation angle (top) and relative PDF (bottom): it can  
 618 be observed that the PDF follows a non-Gaussian distribution, result consistent with assumptions from literature  
 619 [3-5].  
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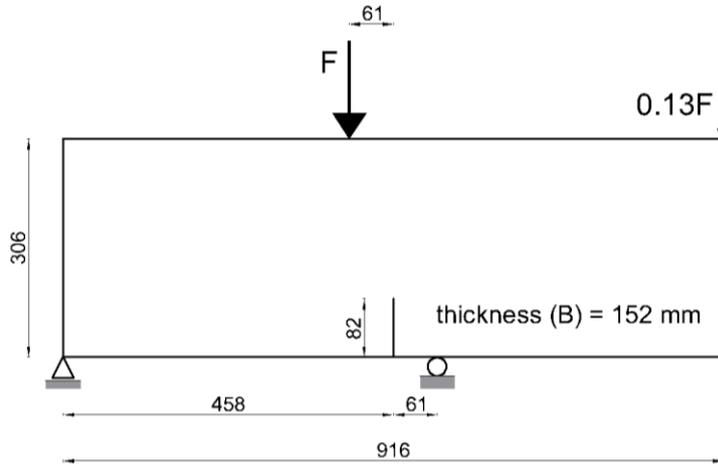
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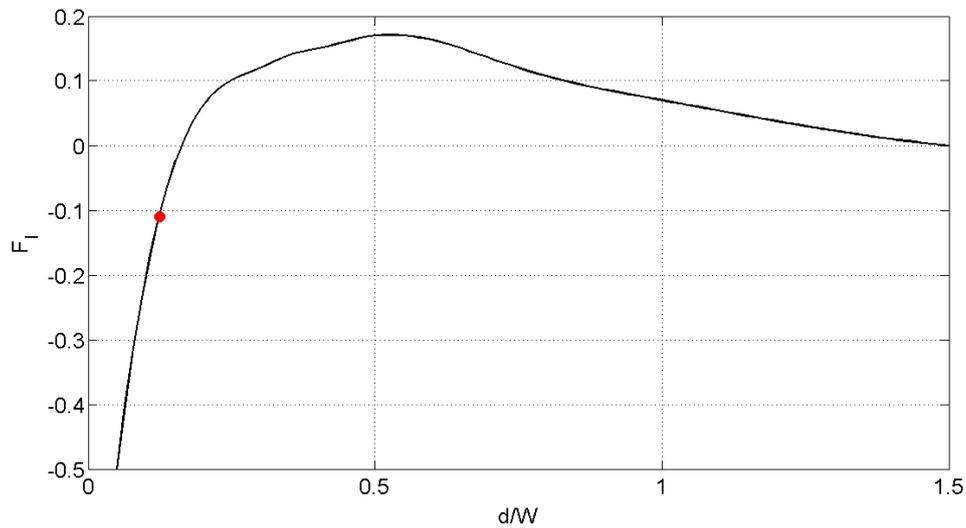
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**Fig 5.** Sample of  $G_f$  calculated from  $K_{Ic}$  (top) and relative Probabilistic distribution of one sample of  $G_f$ : it can be observed that its behaviour follows a lognormal distribution, behaviour consistent with the assumption that non-Gaussian distributions well describe the physical trend of brittle materials such as concrete. [3-5].



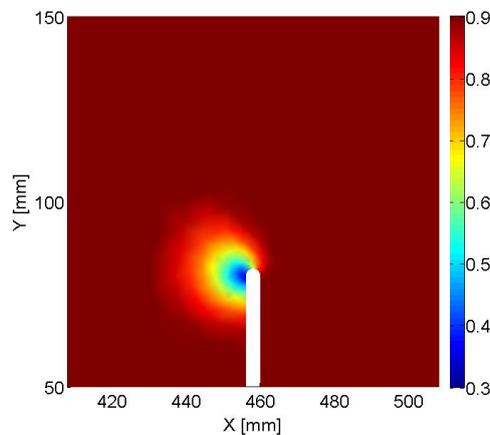
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**Fig 6.** Geometry and load of the SENS beam.



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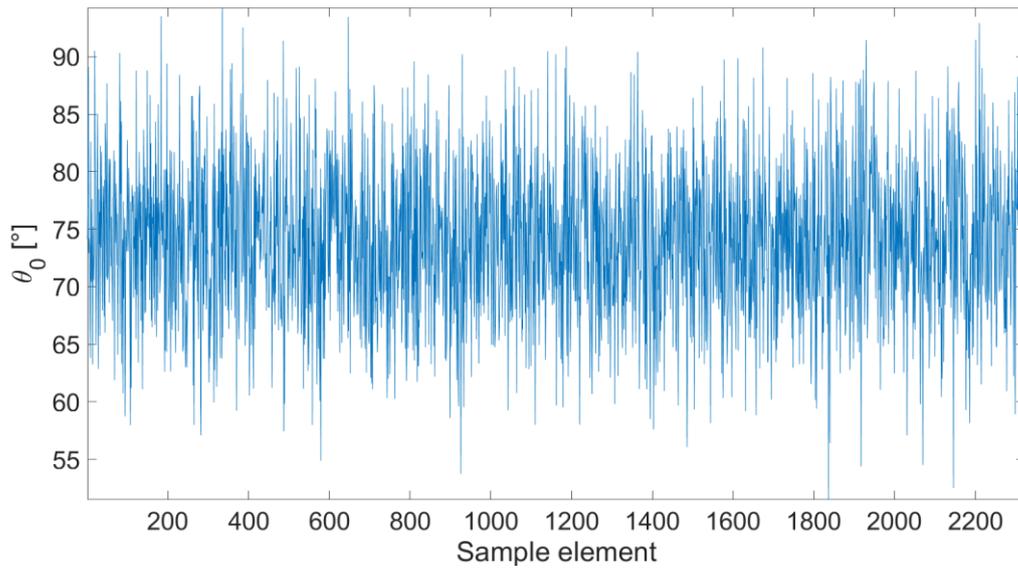
**Fig 7.** Geometric function  $F_I$  trend as function of  $d/W$  for  $L/W = 3.0$  and  $a/W = 0.3$ .  $F_I$  has negative values for small values of  $d/W$ , and increases its values for increasing  $d/W$ . For larger values ( $d/W > 1.5$ ) the contribution of mode I component vanishes.



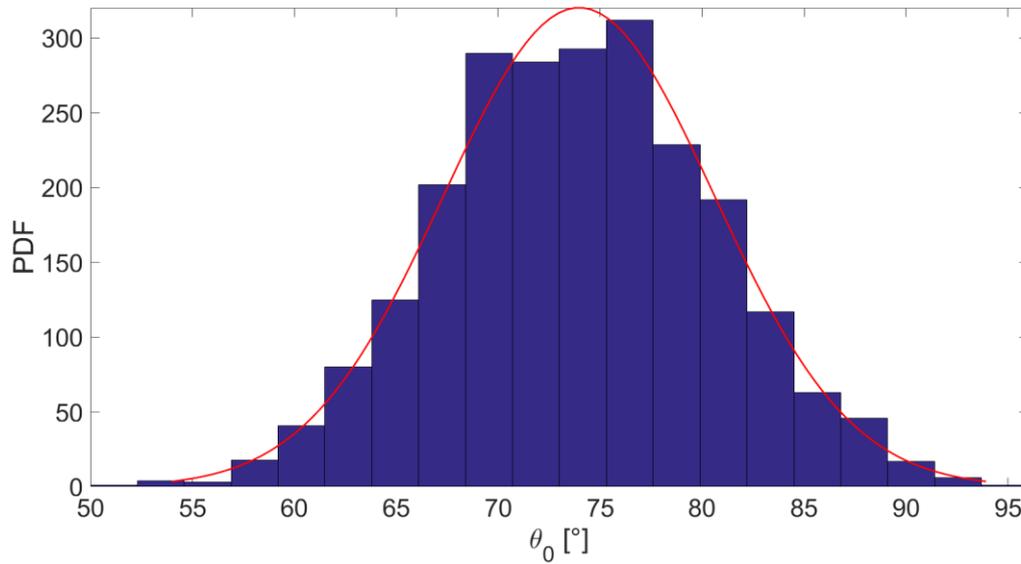
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**Fig 8.** Local area in proximity of the crack tip of the four point SENS beam: the effect of the damage influences also for this example the direction of crack initiation. Nodes closed to the crack tip have a lower value of damage and therefore a higher influence for the determination of the crack initiation angle.

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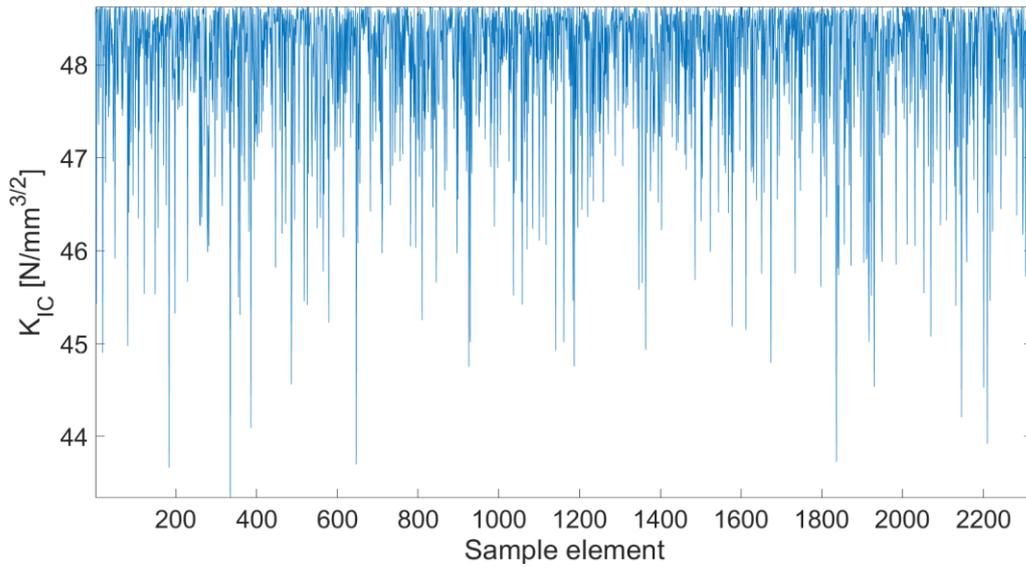


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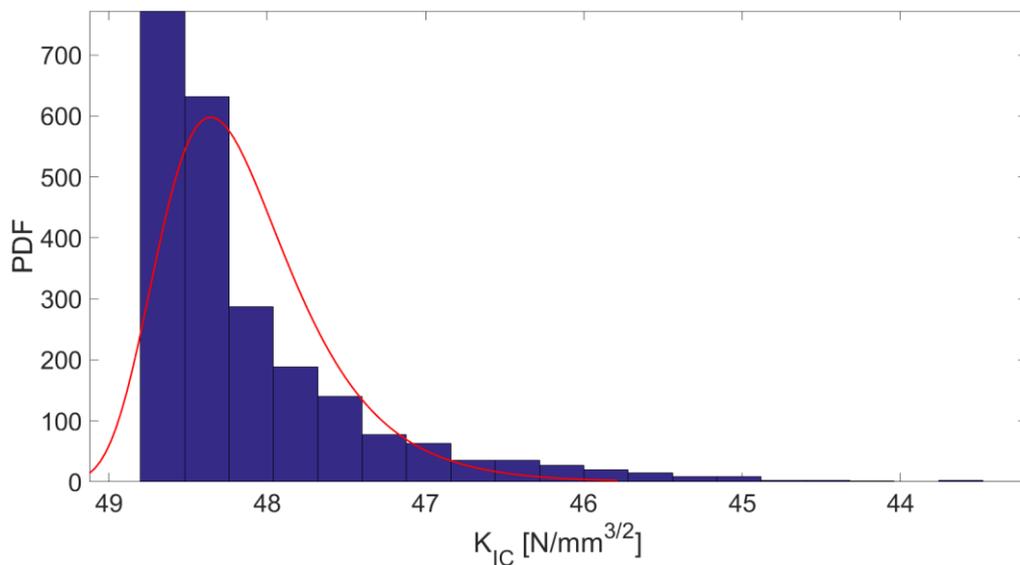


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**Fig 9.** Sample for 2300 values of  $\theta_0$  (top) and PDF with Gaussian nature (bottom). The method shown in Eq. (10) is used to generate each sample.

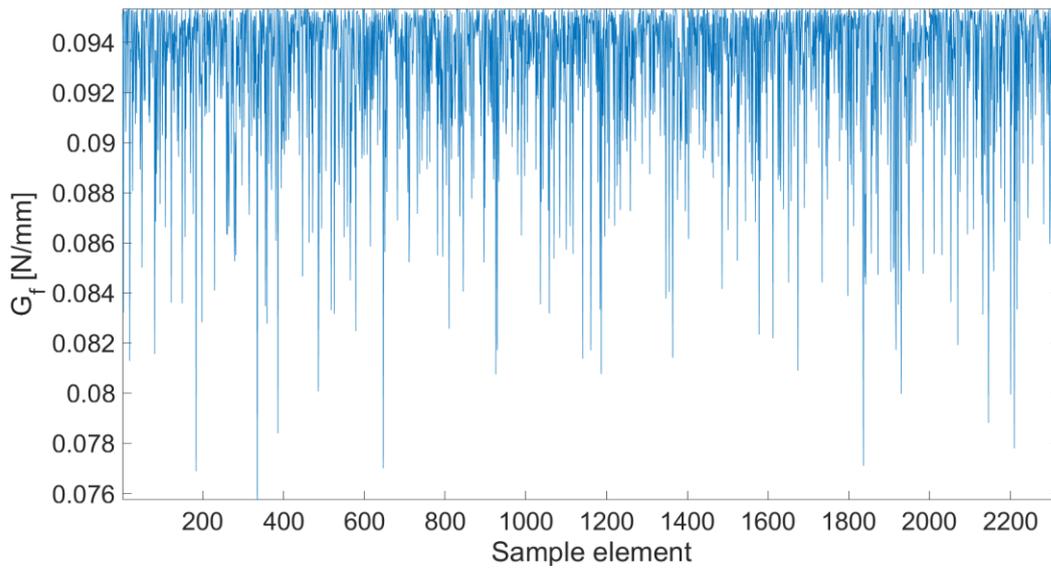


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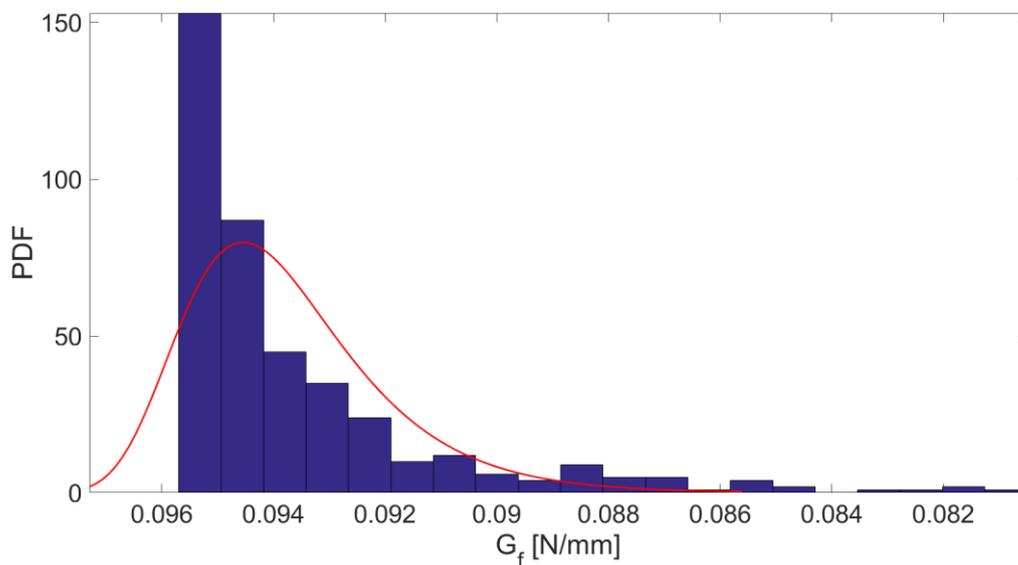


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**Fig 10.** Sample of  $K_{Ic}$  generated from the sample of crack initiation angle (top) and relative PDF (bottom): the PDF follows also in this case a non-Gaussian distribution [3-5].



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**Fig 11.** Sample of  $G_f$  calculated from  $K_{Ic}$  (top) and relative Probabilistic distribution of one sample of  $G_f$ : Also in this example its behaviour follows a non-Gaussian trend, behaviour consistent with the assumption that non-Gaussian distributions well describe the physical trend of brittle materials such as concrete. [3-5].

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669 **Tables**

670 **Table 1.** Mean values for  $\theta_0$  estimated in proximity of the crack tip for different threshold values of  $\bar{s}$

$\bar{s}$	0.4	0.5	0.6	0.7	0.8	Mean value $\theta_0$	Standard deviation	Crack initiation angle, [41]	Crack initiation angle, Eq (20)
$\theta_0$	45°	65.3°	60.3°	56.9°	58°	<b>57.1°</b>	7.5°	<b>53.1°</b>	<b>52.7°</b>

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673 **Table 2.** Values for  $\theta_0$  estimated in proximity of the crack tip for different threshold values of  $\bar{s}$

$\bar{s}$	0.4	0.5	0.6	0.7	0.8	Mean value	Standard deviation	Crack initiation angle, Eq (20)
$\theta_0$	89.7°	79.6°	72.6°	74.9°	63.6°	<b>74.1°</b>	10.8°	<b>72.2°</b>

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