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Rapid imaging of pulsed terahertz radiation with spatial light modulators and neural networks

Rayko Ivanov Stantchev^{1,†}, Kaidi Li^{1,†}, and Emma Pickwell-MacPherson^{1,2,*}

ABSTRACT

We report the first use of a convolutional neural network for terahertz (THz) imaging combined with a single-pixel camera to achieve high quality hyperspectral THz imaging 10 times faster than the current commercial systems, with faster potential only limited by noise. Imaging with a spatial light modulator (SLM) relies on projecting a set of spatial patterns onto an object and recording the transmission with a single-pixel detector, and an optical delay unit (ODU) is used to obtain the terahertz time-of-flight information. A key breakthrough in this work is to synchronize the equipment to not need any time to instruct the ODU to move whilst projecting the patterns.

Keywords: Terahertz imaging, single-pixel detectors, spatial light modulation, time-domain spectroscopy, neural networks

Terahertz (THz) time-domain spectroscopy (TDS) has generated a great body of research¹. TDS systems measure the amplitude and phase information of a THz wave thereby allowing easy calculation of the THz complex refractive index, giving insight into the charge-carrier dynamics of semiconductors² and crystal quality of perovskites³ for example. Furthermore, the time-of-flight information can be used to create a 3D image showing the subsurface layers of optically opaque materials⁴. The non-ionizing THz photon energies also hold potential for cancer diagnosis⁵. Despite these capabilities, imaging with time-resolved THz spectrometers is not widely used outside of laboratory settings.

Current commercial THz-TDS imaging systems work by raster scanning either the object or the emitter-detector pair, resulting in a slow acquisition of around 20-30 data pixels per second due to mechanical movement. This slow imaging rate is unappealing to the semiconductor industry and renders hospital use unpractical. Raster scanning mechanisms are typically employed as detector arrays that can measure the amplitude and phase of a THz wave are not readily available. Although using microbolometer arrays in conjunction with digital holography can achieve coherent imaging at a single frequency^{6,7}, they lack the sub-picosecond temporal resolution that THz-TDS offers. Using an optical camera to map the THz fields in an electro-optic crystal⁸ is a viable alternative, this however requires a regeneratively-amplified Ti:Sapphire laser which severely reduces the pulse repetition rate (slower acquisition) and increases the system size and cost.

Using a single-pixel detector and a spatial light modulator has recently become an alternative imaging method to overcome the drawbacks of the aforementioned approaches⁹. Such single-pixel cameras are typically slower than ones based on detector-arrays, but they are more robust and accessible for frequencies outside the visible-light regime. This makes them highly suited for THz imaging. Single-pixel THz cameras do exist^{10, 11}, and they have been used for inspection of circuits hidden behind semiconductors¹² for example as well as for near-field THz imaging of solid state systems^{13–16} and biological samples as well¹⁷. There have also been studies showing 2D tomographic imaging¹⁸ and potential for standoff applications¹⁹. Previously, we showed that a THz video can be obtained and displayed in real-time with a single-pixel THz

camera²⁰. However, hitherto there has not been a single study on how to best use a SLM for time-resolved THz imaging.

Here, we consider and optimize the synchronization between a spatial THz modulator and an optical delay unit (ODU), commonly used in THz-TDSs to acquire time-of-flight information. We show how to eradicate the time needed to instruct the ODU to move whilst simultaneously projecting our masks. This removes a dead waiting time that would otherwise impede any further reductions in acquisition time, with the fundamental limit imposed by the SLM switch-rate only. We demonstrate temporal undersampling procedures reducing measurement times by 70% and a neural network is built to improve the quality of our THz data allowing five times faster acquisition rates to be used. Ultimately, in under 3 seconds we obtain high quality THz images with 32×32 data pixels over a 10ps time-window with 100 time frames. This is ten times faster than the state-of-the-art.

Figure 1 illustrates the experimental setup. A femtosecond fibre laser powers a photoconductive emitter to generate a beam of THz pulses, which then propagate through an object onto a spatial THz-light modulator and are finally detected by a photoconductive detector. An optical delay line controls the temporal position at which we are sampling the THz-field. The system is a MENLO K15 fibre based THz-TDS with an 80MHz pulse repetition rate where the (100fs, 1500nm) pulses power a pair of photoconductive antennas that use low temperature grown GaAs with subpicosecond carrier lifetimes as the semiconductor, and we use a NI USB-6351 DAQ card with a 250kHz acquisition rate to readout the detected signal. For our spatial THz modulator we photoexcite silicon with a spatially patterned 450 nm continuous-wave laser²⁰. Note the silicon used here has carrier lifetimes of $65\mu s$ as opposed to $250\mu s$ in our previous work²⁰ to achieve quicker switch-rates. Thus our physical masks are effectively binary, having values of [1, 0] for the masks and values of [1, -1] for the differential masks (signal from the positive mask minus the signal from the complimentary inverse mask).

Obtaining an image with a spatial light modulator (SLM) works by projecting a set of masking patterns onto an object and using a single-element detector to record the resulting transmission (or reflection) of an object for each pattern. Since the recorded signals are correlations between the object and the masking patterns, computers can reconstruct an image

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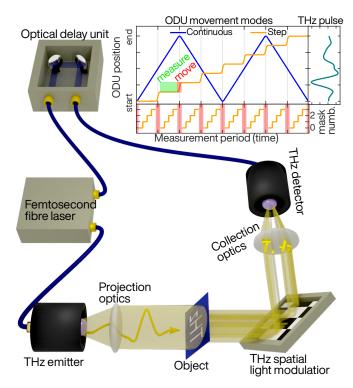


Figure 1. Illustration of experimental setup: A femtosecond fibre laser (100fs, 1550nm) sends a pulse to a photoconductive THz emitter. The train of THz pulses pass through an object, then a spatial THz modulator (see ref.²⁰ for details) and finally all the light is measured with a photoconductive detector. There is an optical delay unit (ODU) between the THz receiver and fibre laser that changes the arrival times of detection and THz pulses, thus allowing the measurement of the THz-field strength at different temporal-points. Inset: Depiction of the two ODU movement modes. The bottom graph depicts how the masks are displayed on the SLM during each measurement stage of the step-mode, with the red areas showing the time waited for the ODU to move.

of the object via matrix inversion or other minimization algorithms⁹. Therefore, a simple way of obtaining a THz image that contains temporal data, ie. a 3D image with one temporal and two spatial dimensions, which can be used in hyperspectral THz analysis^{1,2} is the following: project the set of masking patterns needed to recover a 2D-image, then move the delay line to the next temporal-point and project the set of masking patterns again. Repeat this until we can obtain an individual 2D-image at each temporal-point of interest. We call this ODU movement mode step-mode and it is illustrated in vellow in the inset of figure 1. Whilst very simple and easy to setup, this mode suffers from one major drawback. Namely, instructing the ODU when to move and waiting for it to arrive at the next temporal-point adds dead time where we are not measuring. An alternative movement mode is for the ODU to continuously oscillate backwards and forward in a triangle-wave manner between the start and end temporal-points whilst we simultaneously project our set of masking patterns a number of times. This ODU movement mode we call continuous-mode and it is illustrated by the blue line in the inset of figure 1.

Step-mode has a simple reconstruction algorithm for our 3D-

images; since we project our mask set at the some temporalpoint and move only after finishing the projection, we can easily recover a 2D-image at this and every other temporalpoint. However, in continuous-mode the masks are projected at different temporal-points hence the challenge is to recover a 2D-image at time t when some masks where projected at t and others at $t + \delta t$. If δt is infinitesimally small then we have no problem. However, we encounter a problem once δt is large enough for us to consider t and $t + \delta t$ to be different temporalpoints on the THz waveform, ie. they have distinct values on the detector. This is related to the temporal resolution of the detector, which is 100fs as set by the optical pulses from our MENLO K15 system that uses a low-temperature grown GaAs photoconductive detector with subpicosecond lifetimes. However, in practice we can observe a difference between two temporal points spaced by 50fs at the maximum and minimum of the gradient of the THz-pulse, hence we expect to have image reconstruction problems if $\delta t > 50$ fs. In our experiment this δt value is set by the rate at which we change our spatial masks and the oscillation frequency of our ODU.

The simplest scenario is for the ODU to perform half a cycle during the measurement period and the spatial masks to be changed such that the temporal-distance between the first and last mask, of the mask set needed to recover a 2D-image. is less than 50fs. Another simple scenario is to change the SLM pattern every time the ODU has completed half a cycle, ie. record the THz-pulse for mask one then change to mask two. Whilst this circumvents the problem with δt , these two scenarios suffer from one major drawback. Namely, temporalundersampling is impossible and we want to minimize the total measurement time. As per the Fourier analysis of signals, sampling at temporal-intervals shorter than our detector response will give us no new information other than smoother looking data. Our THz detector has a temporal-resolution of 100fs due to the width of the pulses powering it, hence for temporal undersampling we need to have fewer sampling points than the total temporal-distance divided by 100fs, a quantity we call N. For us, this means that we need to project the whole 2D-mask set fewer times than this number and obtain a set of 2D of images to construct our 3D-THz image without causing significant degradation.

Step-mode has an easy undersampling implementation²¹. THz-pulses are sparse in that the energy is temporally concentrated around a single point and there are large intervals with near-zero values. Therefore, we only need to concentrate taking 2D-images where most of the energy is and ignore other areas. This is can be accomplished via two-stage adaptive sampling; first we measure a coarsely distributed sampling, every 1ps for example, then secondly add more sampling points around where we have measured largest THz amplitudes as we believe most of the THz-pulse energy to be located around here. Reference²¹ shows this can reduce the number of measurement points needed by half and still get a very good results when performing spectroscopic THz analysis.

Continuous-mode does have an equivalent adaptive sampling technique, which would be to reduce the ODU movement speed where the pulse is located. Unfortunately, our ODU can only oscillate in a triangle-wave manner, as shown in the inset of fig. 1, hence we can not experimentally analyze this idea and only discuss it in supplementary section 1. The simplest way of discussing undersampling in the continuous-mode is to think of the projection of patterns as taking the form of a stepped saw-wave and considering the frequency of this saw-wave, f_s , and the frequency of ODU triangle-wave, f_t . Our task is to find the optimum ratio between these frequencies f_s/f_t with the constraint that we want f_s or f_t to perform fewer

cycles than N or N/2 respectively during our measurement period. It is important that f_s and f_t are not multiples of each other. The reason for this can be seen in the inset of fig. 1 where $f_s = 4f_t$. If we look at the first and fifth time mask 0 is projected, we find that both projections were at the starting point of the ODU movement range. This means that during the second triangle-wave cycle we did not obtain new temporal information but only better averaging for mask 0, and consequently every other mask. Therefore, it is best if f_s and f_t are both prime numbers and this is discussed in detail in supplementary section 1. Note, our hardware lacks the precision to thoroughly study when f_t is large, thus this is only discussed in the supplementary information. We define the temporal sampling ratio, T_r , as the number of cycles f_s has performed during the whole measurement divided by N. The temporal undersampling requirement means that $\delta t > 100$ fs, hence we can expect reconstruction problems for the 2D-images especially around the maxima and minima of the THz-pulse gradient.

Figure 2a shows a THz-pulse and the detected values from binary Hadamard masks with values of [1, 0], centered around 4.25ps as taken with the ODU in continuous-mode. The inset shows the [1, 0] mask measurements compared against the measurements from the differential [1, -1] masks taken at the same temporal-positions with coefficient number along the x-axis. Figures 2b-p show 2D THz-images at different temporal-times as recovered from [1, 0] and [1, -1] Hadamard masks in the top and middle rows, respectively, with the ODU moving in the continuous-mode with $T_r = 0.6$. The ground truth images (bottom row) were taken using the same [1, -1] Hadamard masks but the ODU was moving in step-mode with $T_r = 1$. We choose step-mode for the ground truth because we want to be certain that the continuous imaging mode does not introduce any temporal errors or artifacts. For all the 32×32 images we measured the 256 coefficients with the lowest sequency as defined by the 2D Hadamard transform (see supplementary section 3 for details) since Hadamard masks are easy to implement with our THz-SLM²⁰. This spatial undersampling is performed for the ground truths as well since spatial undersampling of images has been extensively studied⁹ and this work concerns itself with how the temporal-nature of THz-TDS measurements affects single-pixel imaging.

The signals from the [1, 0] mask in fig. 2a are a complete set of the 256 coefficients we use to reconstruct a 2D image with all of them measured in the temporal interval of 4 and 4.5ps. It can be seen that the masks around 4ps have lower amplitudes than those around 4.5ps, in line with the slope of the THz-pulse. Comparing the signals from the [1, -1] and [1, 0] masks in the inset, it can be seen that most of the [1, -1] signals have very little energy as expected from Hadamard transforms of images. By contrast, the [1, 0] signals have large curve-shaped artefacts caused by the THz-pulse gradient. Since the signals for the [1, -1] masks were obtained by projecting a mask followed by its inverse and taking the difference, this procedure has effectively subtracted out the THz-pulse gradient and removed the errors it causes. In figs. 2b-p we can see that the images from [1, 0] masks (top row) have severe artefacts where as the [1, -1] images (middle row) do not when compared to the ground truth images (bottom row). It should be noted that a different measurement matrix would result in different image artefacts. Framing the problem as a minimization problem of the form y = Ax is infeasible as even our modest $32 \times 32 \times 100$ images would be a computationally heavy problem. Therefore, we choose a 3D image reconstruction procedure that uses interpolation to temporally align all the measurements, with the details shown in supplementary section 4.

Using a differential measurement of a [1, 0] mask and its

inverse to obtain a [1, -1] sampling matrix usually doubles the number of measurements needed. However, single-pixel Fourier imaging can obtain the equivalent [1, -1] matrix via a three-shift method increasing the number of measurements by 3/2²². For this reason, we demonstrate the implementation of Fourier masks with our THz-SLM in supplementary section 3 and use them in the following parts of this work. Noise in the measurement and artifacts from implementing temporal undersampling will heavily influence the acquisition rate, provided we are not near the limits of our equipment. In our previous work we showed that our modulator can reach up-to 20kHz switch rate²⁰ however our signal-to-noise was not sufficiently high to acquire images of viewable quality at that switch rate as the data needed to be averaged 16 times. Therefore, noise limits our acquisition speeds and not equipment or any physical phenomena, thus to improve image quality when imaging at

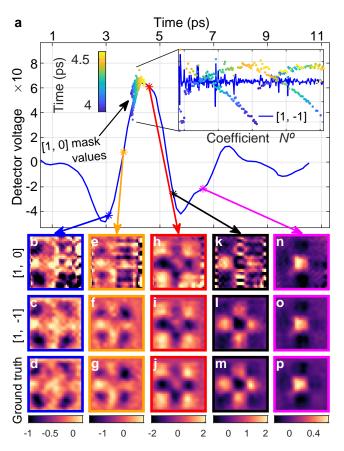


Figure 2. a: Detected signals from [1, 0] Hadamard masks centered around 4.2ps shown alongside a THz pulse (blue line) for comparison. Inset: the same [1, 0] mask signals plotted against their Hadamard coefficient number along the *x*-axis. The solid blue line shows the same coefficients as measured by [1, -1] masks. Note the [1, 0] were shifted by subtracting the mean of the ensemble. **b-p:** 32×32 THz-images at individual temporal-points along the columns and the top, middle and bottom rows being images taken with [1, -1] and [1, 0] masks and ground truth respectively. The image temporal times are shown by arrows coming from **a**. Field of view is 1×1cm with acquisition times being 17.1, 34.2, and 47.2s for a single 3D-image in the [1, 0], [1, -1] and ground truth images respectively. Note the ground truth is an average of 18 measurements.

high SLM switch-rates we explore image denoising algorithms in supplementary info S5. We find that a neural network is able to post process our raw images in real-time as well as having the largest reduction in noise and artifacts from the measurement. The second best improvement in image quality was by Wiener filtering which was also able to display the denoised images in real-time. Other methods studied were total variational minimization and wavelet denoising, both of which had similar improvements in image quality although neither were able to process the images fast enough for real-time display. Thus our results from supplementary info S5 indicate that for real-time display applications deep learning methods should be used if training data is available otherwise Wiener filtering will give a very good result. Data and processing scripts can be downloaded, see the data availability statement.

The structure similarity index measure (SSIM) is a common quantity when studying the quality of images that are affected by noise and compression. Figure 3 shows how the SSIM of our 3D images behaves when we perform temporal undersampling with the THz data shown in supplementary video 1. The neural network has improved the SSIM by around 0.2 whilst keeping the same trend with regards to T_r . Note, that we get an SSIM around 0.6 when the SLM switch-rate is 5 times slower as shown in supplementary figure 16. This in effect means that the network has removed measurement noise however the artefacts from temporal-undersampling are still present. This is because the measurement noise can be readily identified in the 2D-images where as the artefacts from temporal-undersampling can only be seen in the full 3D-data (made up of 2D-image stacks). Our network processes each individual 2D image by itself only to show that neural networks can be used to improve the quality of 3D THz data. Moreover, building a network that can process data at multiple undersampling ratios is unfeasible as it would be much more efficient to create a network that removes artifacts at a single undersampling amount, for example at $T_r = 0.2$ or lower. Further, the noise artifacts from the continuous and step modes are different and thus are likely to require different networks, likewise if

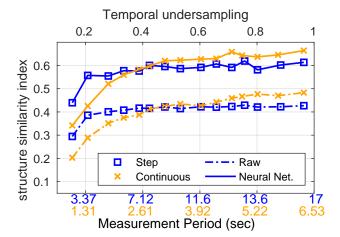


Figure 3. Structure similarity index as a function of temporal undersampling of 3D-THz images, with the dash-dotted (solid) line showing the SSIM of the raw (neural network processed) images. The bottom axis shows the total time the measurement took with top (bottom) numbers being for the step (continuous) ODU mode. SLM switch rate was 5kHz and 294 Fourier-based masks sampled each 2D image.

extracting spectral information 3 or thicknesses from THz pulse delays 4 .

Figure 3 shows that the SSIM of step-mode has a superior performance once the T_r becomes smaller. This is expected as it employs a two-stage adaptive sampling algorithm²¹ that concentrates measurements where the THz-waveform has large amplitudes, whereas in continuous-mode our hardware can not implement the equivalent motion. Therefore, it is inappropriate to do an exact comparison. Nevertheless, we can see that for $T_r > 0.5$ the SSIM for both step and continuous modes is of similar values, indicating that continuous-mode does not introduce any additional errors or temporal artefacts when compared to step-mode, therefore step-mode does not need to be used other than to check if all the equipment was synchronized correctly in continuous-mode. This is significant as continuous-mode offers substantially quicker acquisition rates. In the inset of fig. 1, we can see that the total measurement time for step-mode is going to be the time needed to acquire a single 2D-image and then move the ODU multiplied by the number of temporal-points we want to measure. The time needed to acquire a 2D-image is determined by the number of spatial masks and the SLM switch-rate, and in fig. 3 we use 294 masks switched at a 5kHz rate thus we need 58.8ms to acquire a 2D-image. The time needed by our ODU to move is about 75ms, with 25ms due to software synchronization and 50ms due to acceleration and deceleration of the ODU. This creates a bottleneck in reducing the total acquisition time since reducing the time needed to acquire a 2D-image, by a quicker SLM or by projecting fewer masks, would not result in any meaningful improvement in the overall acquisition rate. This is why the continuous ODU mode is around 3 times quicker than step-mode, for the same T_r , we are using more time waiting for the ODU to move than measuring. The significance of this for future research is that developing quicker THz-SLMs for continuous-mode will give meaningful improvements in the acquisition rate, assuming sufficient signal levels, whereas for step-mode there will be no meaningful improvements.

In terms of the absolute limits of our system, we use a photoconductive antenna detector with subpicosecond carrier lifetimes and the laser system has an 80MHz pulse repetition rate. Due to these short carrier lifetimes, the pulse repetition rate will set the ultimate acquisition rate of fiber based THz-TDS systems such as ours. However, a more realistic limit would be closer to 80kHz because it is likely that 1000 pulses need to be measured for a single mask value to average out laser noise. Additionally, the future antennas used for this type of imaging should be those developed for emitting a beam – whereas the emitter detector pair we used was optimized for focusing the radiation into a spot for raster scanning.

It should be noted that we originally tried to use the CIFAR-10 image dataset to simulate our experiment and train the neural network. However, this gave sub-optimal results due to the following: first, visible light images have very different physical resolution to our THz radiation, leading the network to create fictitious objects. Second, these images are intensity based and are scaled between 0 and 1 whereas our THz images have positive and negative values, hence the network struggles to preserve the energy in each THz image making spectroscopic analysis impossible. Thirdly, the noise in our THz system is difficult to model; any noise in the femtosecond fibre laser manifests itself as source and detector noise simultaneously in a non-linear manner and this is in addition to electrical noise. We can not measure the laser noise simultaneously to our THz signals and thus we can only make guesses into our THz system's noise. Thus without an accurate noise model the resulting network would sometimes

enhance features which were actually due to experimental noise. This is why we had to build our own dataset suitable for our THz-TDS imaging system. A further note is that since THz radiation has potential uses in cancer diagnosis⁵, clinical trials will be performed and the raw data from these trials will be sufficient to build a database of THz images that could be used as training data for neural networks. This would spare THz researchers from the effort of building a database for training, although for applications like semiconductor/electronics quality control solving the aforementioned problems and using an existing image database might prove to be a more efficient solution.

This work optimizes single-pixel THz cameras for timedomain measurements. We completely remove the time usually needed to instruct the ODU to move forward, which means only the system noise and THz-SLM switch rate limit the acquisition rate. We demonstrate that the THz-waveform gradients need to be subtracted out from the measurement, which we do by using a differential mask measurement (although using a second detector should achieve the same result). We use a neural network to improve our images and show it is possible acquire a 32 × 32 THz image over an 10ps temporal-interval, with 100 frames in under 3 seconds, about ten times faster than commercial raster-scanning based THz-TDS imaging systems. The most interesting aspect of this work is that there is no inherently expensive equipment involved and the potential of achieving faster acquisition is restricted by noise and not equipment capabilities. Given the large range of possible applications of single-pixel THz cameras 12, 13, 15-19, future work will need to focus on optical designs for more specific applications such as skin imaging or semiconductor quality control.

Data Availability

All the training data and scripts (MATLAB for raw data processing and Python for network training) needed to reproduce the results of this work can be found on https://doi.org/10.6084/m9.figshare.14236766.

Supporting information

Supplementary material is available free of charge via the internet at http://pubs.acs.org. List of materials:

- S1 Adaptive sampling distribution in continuous ODU mode
- S2 ODU speed and SLM switch rate relationship
- S3 Single-pixel imaging
- S4 Raw signals and processing
- S5 Convolutional neural network

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Author contributions

R.I.S, K.D. and E.P-M conceived the idea. R.I.S. created the experimental setup and programmed all equipment. K.D. designed the neural network. R.I.S and K.D. performed the experiments and data analysis. R.I.S. wrote the manuscript and all others providing editorial input.

The authors declare no competing interests

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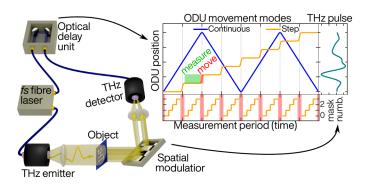
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Synopsis:

Illustration of the single-pixel THz camera with time-domain measurement capabilities. A femtosecond laser powers a THz emitter and a THz detector, with an optical delay unit between the detector and laser. The THz beam passes through an object onto a spatial THz-light modulator and everything is collected by the THz detector. The optical delay unit can move in two motions, *step-mode* and *continuous-mode* with the synchronization with respect to the masks projected on the spatial modulator shown in the inset. In this work we show that continuous-mode has 3 times faster acquisition rate. The breakthrough in this work is that in our continuous-mode configuration we have removed all communication lag between the optical delay line and spatial light modulator. This overcomes a significant bottleneck in single pixel imaging and now developing quicker THz modulators will give meaningful improvements in the acquisition rate for continuous-mode imaging, assuming sufficient signal levels, whereas for step-mode there would be no meaningful improvements with faster modulation due to this communication lag.

Below is a rasterized PNG version



Below is the vectorized PDF version incase the PNG file has wrong resolution

