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# EXISTENCE AND SMOOTHNESS OF THE STABLE FOLIATION FOR SECTIONAL HYPERBOLIC ATTRACTORS 

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#### Abstract

We prove the existence of a contracting invariant topological foliation in a full neighborhood for partially hyperbolic attractors. Under certain bunching conditions it can then be shown that this stable foliation is smooth. Specialising to sectional hyperbolic attractors, we give a verifiable condition for bunching. In particular, we show that the stable foliation for the classical Lorenz equation (and nearby vector fields) is better than $C^{1}$ which is crucial for recent results on exponential decay of correlations. In fact the foliation is at least $C^{1.278}$.


## 1. Introduction

The goal of this paper is to establish existence and smoothness of the stable foliation for sectional hyperbolic flows. In particular, we treat the case of the classical Lorenz equations [13]

$$
\begin{aligned}
& \dot{x}_{1}=10\left(x_{2}-x_{1}\right) \\
& \dot{x}_{2}=28 x_{1}-x_{2}-x_{1} x_{3} \\
& \dot{x}_{3}=x_{1} x_{2}-\frac{8}{3} x_{3}
\end{aligned}
$$

showing that the stable foliation for the flow is at least $C^{1.278}$. This regularity $\left(C^{1+\varepsilon}\right.$ for some $\varepsilon>0$ ) is a crucial component of the analysis in [2,3] where we prove exponential decay of correlations for the Lorenz attractor. An immediate consequence of our result is that the stable foliation for the associated Poincaré map is also at least $C^{1.278}$. The results are robust in the sense that we obtain smoothness of the stable foliations and exponential decay of correlations for smooth vector fields that are sufficiently $C^{1}$-close to the classical one.

As far as we know, this is the first complete proof that the stable foliation for the classical Lorenz equations (or even for the Poincaré map) exists and is better than Hölder continuous. By [14] and [19], the classical Lorenz attractor is a singular hyperbolic attractor. A consequence is the existence of smooth stable leaves through each point of the attractor. However, a priori it does not follow that these leaves form a topological foliation in a full neighborhood of the attractor; nor is there any information about smoothness of such a foliation. These issues are somewhat controversial, with various false claims in the literature.

[^0]Careful analyses (see for example [11, 16, 17]) require additional conditions to establish smoothness and do not apply to the classical Lorenz attractor.

Recently [3] gave a verifiable criterion for smoothness of the stable foliation that is easily seen to hold for the classical Lorenz attractor. However, the argument in [3] presupposes that the stable leaves topologically foliate a full neighborhood of the attractor - a fact that is folklore but for which apparently there is no proof available in the literature.

In this paper, we consider general partially hyperbolic attractors and give a complete proof of the existence of a topological foliation $\left\{W_{x}^{s}\right\}$ in a neighborhood of such attractors. The individual leaves $W_{x}^{s}$ are smoothly embedded stable manifolds. In general, the leaves need not vary smoothly, but under a bunching condition [9] the foliation is smooth. The argument in [3] now applies, and we obtain existence and smoothness of the stable foliation for the classical Lorenz attractor. Our results hold for the flow, and hence also for the Poincaré map. This resolves an issue in [19, Section 2.4] where it is claimed that the stable foliation for the Poincaré map is smooth but no details are provided.

In addition, we extend the verifiable criterion of [3] to the sectional hyperbolic situation, and we give a lower bound for the smoothness for the classical Lorenz attractor. The condition is verifiable in the sense that it depends only on the linearised vector field and the location of the attractor and its equilibria.

In Section 2, we recall the notion of partially hyperbolic and sectional hyperbolic attractors. Section 3 contains general facts about cone fields for partially hyperbolic attractors, as well as the crucial step that the stable bundle extends continuously to a contracting invariant bundle over a neighborhood of the attractor. Section 4 contains general results about the stable foliation of partially hyperbolic attractors. In particular, the stable leaves define a topological foliation of a neighborhood of the attractor and is smooth under a bunching condition. In Section 5, we specialise to sectional hyperbolic attractors. Following [3], we give a verifiable condition for smoothness of the stable foliation and apply this to the classical Lorenz attractor.

## 2. SECtional hyperbolic attractors

In this section, we define what is understood as a sectional hyperbolic attractor; see e.g. [4] for an extended presentation of this theory,

Let $M$ be a compact Riemannian manifold and $\mathfrak{X}^{r}(M), r \geq 1$, be the set of $C^{r}$ vector fields defined on $M$. Let $X_{t}$ denote the flow generated by $G \in \mathfrak{X}^{r}(M)$. Given a compact invariant set $\Lambda$ for $G \in \mathfrak{X}^{r}(M)$, we say that $\Lambda$ is isolated if there exists an open set $U \supset \Lambda$ such that

$$
\Lambda=\bigcap_{t \in \mathbb{R}} X_{t}(U)
$$

If $U$ above can be chosen such that $X_{t}(U) \subset U$ for $t>0$, then we say that $\Lambda$ is an attracting set.

Given $x \in M$, we define $\omega_{G}(x)$ as the set of accumulation points of the set $\left\{X_{t} x ; t \geq 0\right\}$ and define $\alpha_{G}(x)=\omega_{-G}(x)$. A subset $\Lambda \subset M$ is transitive if it has a full dense orbit, that is, there is $x \in \Lambda$ such that $\omega_{G}(x)=\Lambda=\alpha_{G}(x)$.

Definition 2.1. An attractor is a transitive attracting set, and a repeller is an attractor for the reversed vector field $-G$.

Definition 2.2. Let $\Lambda$ be a compact invariant set for $G \in \mathfrak{X}^{r}(M)$. We say that $\Lambda$ is partially hyperbolic if the tangent bundle over $\Lambda$ can be written as a continuous $D X_{t}$-invariant sum

$$
T_{\Lambda} M=E^{s} \oplus E^{c u},
$$

where $d_{s}=\operatorname{dim} E^{s} \geq 1$ and $d_{c u}=\operatorname{dim} E^{c u} \geq 2$, and there exist constants $C>0, \lambda \in(0,1)$ such that for every $t>0$ and every $x \in \Lambda$, we have

- uniform contraction along $E^{s}$ :

$$
\begin{equation*}
\left\|D X_{t} \mid E_{x}^{s}\right\| \leq C \lambda^{t} \tag{2.1}
\end{equation*}
$$

- domination of the splitting:

$$
\begin{equation*}
\left\|D X_{t}\left|E_{x}^{s}\|\cdot\| D X_{-t}\right| E_{X_{t} x}^{c u}\right\| \leq C \lambda^{t} \tag{2.2}
\end{equation*}
$$

We refer to $E^{s}$ as the stable bundle and to $E^{c u}$ as the center-unstable bundle.
Remark 2.3. By [8, Theorem 1], we may suppose without loss that $\|\cdot\|$ is an adapted metric so that $C=1$.

Definition 2.4. The center-unstable bundle $E^{c u}$ is volume expanding if there exists $K, \theta>0$ such that $\left|\operatorname{det}\left(D X_{t}(x) \mid E_{x}^{c u}\right)\right| \geq K e^{\theta t}$ for all $x \in \Lambda$ and $t \geq 0$. More generally, $E^{c u}$ is sectional expanding if for every two-dimensional subspace $P_{x} \subset E_{x}^{c u}$,

$$
\left|\operatorname{det}\left(D X_{t}(x) \mid P_{x}\right)\right| \geq K e^{\theta t} \quad \text { for all } x \in \Lambda, t \geq 0
$$

If $\sigma \in M$ and $G(\sigma)=0$, then $\sigma$ is called an equilibrium. An invariant set is nontrivial if it is neither a periodic orbit nor an equilibrium.

Definition 2.5. Let $\Lambda$ be a compact nontrivial invariant set for $G \in \mathfrak{X}^{r}(M)$. We say that $\Lambda$ is a sectional hyperbolic set if all the equilibria in $\Lambda$ are hyperbolic, and $\Lambda$ is partially hyperbolic with sectional expanding center-unstable bundle. A sectional hyperbolic set which is also an attractor is called a sectional hyperbolic attractor.

In the special case when $E^{c u}$ is volume expanding, $\Lambda$ is called a singular hyperbolic set/attractor.

An isolated set $\Lambda=\Lambda_{G}$ for a $C^{1}$ vector field $G$ is robustly transitive if there is an open set $U \supset \Lambda$ such that $\Lambda_{\tilde{G}}=\bigcap_{t \in \mathbb{R}} \tilde{X}_{t}(U)$ is transitive and nontrivial for any vector field $\tilde{G}$ $C^{1}$-close to $G$.

Definition 2.6. An equilibrium $\sigma$ for a 3 -dimensional vector field $G$ is Lorenz-like if the eigenvalues $\lambda_{j}, 1 \leq j \leq 3$, of $D G(\sigma)$ are real and satisfy $\lambda_{1}<\lambda_{2}<0<-\lambda_{2}<\lambda_{3}$.

For 3-dimensional vector fields, Morales, Pacifico, and Pujals proved in [14] that any robustly transitive invariant set $\Lambda$ containing an equilibrium is a singular hyperbolic attractor or repeller. Moreover, every equilibrium in $\Lambda$ is Lorenz-like for $G$ or $-G$, and $\Lambda$ is proper, i.e., $\Lambda \neq M$.

Tucker [19] gave a computer-assisted proof that the classical Lorenz attractor [13] is a robustly transitive invariant set containing an equilibrium. It then follows from [14] that the classical Lorenz attractor is singular hyperbolic.

## 3. Cone fields and the stable bundle for partially hyperbolic attractors

In this section, we analyse stable and center-unstable cone fields in a neighborhood of a partially hyperbolic attractor $\Lambda$, and we show that the stable bundle $E^{s}$ extends to a continuous $D X_{t}$-invariant contracting bundle over a neighborhood of $\Lambda$.

Throughout, $\Lambda$ is a partially hyperbolic attractor for a vector field $G \in \mathfrak{X}^{r}(M), r \geq 1$, with invariant splitting $T_{\Lambda} M=E^{s} \oplus E^{c u}$ and contraction rate $\lambda \in(0,1)$. Sectional expansion is not assumed. Write $d=\operatorname{dim} M=d_{s}+d_{c u}$.
3.1. Cone fields in a neighborhood of $\Lambda$. Let $U_{0} \subset M$ be a forward invariant neighborhood of $\Lambda$ such that $\bigcap_{t \geq 0} X_{t}\left(U_{0}\right)=\Lambda$. Choose a continuous (not necessarily invariant) extension $T_{U_{0}} M=E^{s} \oplus E^{c \bar{u}}$ of the splitting $T_{\Lambda} M=E^{s} \oplus E^{c u}$. Given $x \in U_{0}$ and $a>0$ we define the cone fields

$$
\begin{aligned}
\mathcal{C}_{x}^{s}(a) & =\left\{v=v^{s}+v^{c u} \in E_{x}^{s} \oplus E_{x}^{c u}:\left\|v^{c u}\right\| \leq a\left\|v^{s}\right\|\right\}, \\
\mathcal{C}_{x}^{c u}(a) & =\left\{v=v^{s}+v^{c u} \in E_{x}^{s} \oplus E_{x}^{c u}:\left\|v^{s}\right\| \leq a\left\|v^{c u}\right\|\right\} .
\end{aligned}
$$

Proposition 3.1. Fix $T$ so that $\lambda^{T}=1 / 150$. For any $a \in\left(0, \frac{1}{4}\right]$ there exists a positively invariant neighborhood $U_{0}$ of $\Lambda$, such that for all $x \in U_{0}$ the following hold:
(a) backward invariance of stable cones and forward invariance of center-unstable cones:

$$
\begin{align*}
& D X_{-t}\left(\mathcal{C}_{X_{t} x}^{s}(b)\right) \subset \mathcal{C}_{x}^{s}(b),  \tag{3.1}\\
& D X_{t}\left(\mathcal{C}_{x}^{c u}(b)\right) \subset \mathcal{C}_{X_{t} x}^{c u}(b), \tag{3.2}
\end{align*}
$$

for all $b \geq a, t \geq T$.
(b) backward expansion of stable cones and domination: there exist constants $c>0$, $\tilde{\lambda} \in(0,1)$, such that for all $t>0$,

$$
\begin{align*}
& \left\|D X_{-t}\left(X_{t} x\right) v\right\| \geq c \tilde{\lambda}^{-t}\|v\| \quad \text { for all } v \in \mathcal{C}_{X_{t} x}^{s}(a),  \tag{3.3}\\
& \frac{\left\|D X_{t}(x) v\right\|}{\|v\|} \geq c \tilde{\lambda}^{-t} \frac{\left\|D X_{t}(x) u\right\|}{\|u\|} \text { for all nonzero } v \in \mathcal{C}_{x}^{c u}(a), u \in D X_{-t}\left(\mathcal{C}_{X_{t} x}^{s}(a)\right) . \tag{3.4}
\end{align*}
$$

Proof. If $v$ lies in $T_{x} M$ where $x \in U_{0}$, then we write $v=v^{s}+v^{c u} \in E_{x}^{s} \oplus E_{x}^{c u}$. If $v \in \mathcal{C}_{x}^{*}(a)$, then $(1-a)\left\|v^{*}\right\| \leq\|v\| \leq(1+a)\left\|v^{*}\right\|$ where throughout $* \in\{s, c u\}$.

For $x \in \Lambda$, it follows from invariance of the splitting $E^{s} \oplus E^{c u}$ that $\left(D X_{t}(x) v\right)^{*}=$ $D X_{t}(x) v^{*}$ for all $v \in T_{x} M$ and $t \in \mathbb{R}$.

We fix the neighborhood $U_{0}$ as follows. For each $x \in \Lambda$, we choose a neighborhood $U_{x} \subset M$ of $x$ such that $U_{x}$ is diffeomorphic to $\mathbb{R}^{d}$ where $d=\operatorname{dim} M$. Then $T_{U_{x}} M$ is identified with $U_{x} \times \mathbb{R}^{d}$. Given $y_{1}, y_{2} \in U_{x}$, a vector $v \in \mathbb{R}^{d}$ corresponds to vectors $v_{y_{j}} \in T_{y_{j}} M$ via this identification. Using the smoothness of the flow, we can choose $U_{x}$ so small that $\left\|D X_{t}\left(y_{1}\right) v_{y_{1}}\right\| \leq 2\left\|D X_{t}\left(y_{2}\right) v_{y_{2}}\right\|$ for all $x \in \Lambda, y_{1}, y_{2} \in U_{x}, v \in \mathbb{R}^{d}, t \in[-T, T]$. Using moreover the continuity of the splitting $E^{s} \oplus E^{c u}$, for $a>0$ fixed we can ensure for all $b \geq a / 8, t \in[-T, T]$, that if $D X_{t}\left(y_{1}\right) v_{y_{1}} \in \mathcal{C}_{X_{t} y_{1}}^{*}(b)$, then $D X_{t}\left(y_{2}\right) v_{y_{2}} \in \mathcal{C}_{X_{t} y_{2}}^{*}(2 b)$.

We now fix $U_{0}$ to be a positively invariant neighborhood of $\Lambda$ contained in $\bigcup_{x \in \Lambda} U_{x}$. By construction, for every $y \in U_{0}$, there exists $x \in \Lambda$ such that
(i) $D X_{t}(x) v_{x} \in \mathcal{C}_{X_{t} x}^{*}(b)$ implies that $D X_{t}(y) v_{y} \in \mathcal{C}_{X_{t} y}^{*}(2 b)$,
(ii) $D X_{t}(y) v_{y} \in \mathcal{C}_{X_{t} y}^{*}(b)$ implies that $D X_{t}(x) v_{x} \in \mathcal{C}_{X_{t} x}^{*}(2 b)$, and
(iii) $\frac{1}{2}\left\|D X_{t}(x) v_{x}\right\| \leq\left\|D X_{t}(y) v_{y}\right\| \leq 2\left\|D X_{t}(x) v_{x}\right\|$,
for all $v \in \mathbb{R}^{d}, b \geq a / 8, t \in[-T, T]$.
We now proceed with the proof of part (a). By (2.2),

$$
\begin{aligned}
\left\|\left(D X_{t}(x) v\right)^{s}\right\| & =\left\|D X_{t}(x) v^{s}\right\| \leq\left\|D X_{t}\left|E_{x}^{s}\| \| v^{s}\left\|\leq \lambda^{t}\right\| D X_{-t}\right| E_{X_{t} x}^{c u}\right\|^{-1}\left\|v^{s}\right\| \\
& =\lambda^{t}\left\|\left(D X_{t} \mid E_{x}^{c u}\right)^{-1}\right\|^{-1}\left\|v^{s}\right\| \leq \lambda^{t}\left\|\left(D X_{t}(x) v\right)^{c u}\right\|\left\|v^{c u}\right\|^{-1}\left\|v^{s}\right\|,
\end{aligned}
$$

for all $x \in \Lambda, v \in T_{x} M, t \geq 0$. In particular, $D X_{t}\left(\mathcal{C}_{x}^{c u}(b)\right) \subset \mathcal{C}_{X_{t} x}^{c u}\left(b \lambda^{t}\right)$ for all $x \in \Lambda, b>0$, $t \geq 0$.

Now let $y \in U_{0}, b \geq a, v \in \mathcal{C}_{y}^{c u}(b)$. We can pass to a nearby point $x \in \Lambda$ with corresponding vector $v_{x} \in \mathcal{C}_{x}^{c u}(2 b)$ by (ii). Then $D X_{t}(x) v_{x} \in \mathcal{C}_{X_{t} x}^{c u}\left(2 b \lambda^{t}\right)$ for all $t \geq 0$. In particular, since $\lambda^{T}=1 / 150 \leq 1 / 16$,

$$
D X_{T}(x) v_{x} \in \mathcal{C}_{X_{T} x}^{c u}(b / 8) \quad \text { and } \quad D X_{t}(x) v_{x} \in \mathcal{C}_{X_{t} x}^{c u}(2 b) \text { for all } t \geq 0 .
$$

By (i),

$$
\begin{equation*}
D X_{T}\left(\mathcal{C}_{y}^{c u}(b)\right) \subset \mathcal{C}_{X_{T} y}^{c u}(b / 4) \subset \mathcal{C}_{X_{T} y}^{c u}(b) \quad \text { and } \quad D X_{r}\left(\mathcal{C}_{y}^{c u}(b)\right) \subset \mathcal{C}_{X_{r y}}^{c u}(4 b) \tag{3.5}
\end{equation*}
$$

for all $r \in[0, T], y \in U_{0}$.
By positive invariance of $U_{0}$, it follows inductively from (3.5) that $D X_{k T}\left(\mathcal{C}_{y}^{c u}(b)\right) \subset$ $\mathcal{C}_{X_{k T} y}^{c u}(b / 4) \subset \mathcal{C}_{X_{k T} y}^{c u}(b)$ for all $y \in U_{0}, k \in \mathbb{N}$.

For general $t \geq T$, write $t=k T+r$ where $k \geq 1$ and $r \in[0, T)$. Again using positive invariance of $U_{0}$ together with (3.5),

$$
D X_{t}\left(\mathcal{C}_{y}^{c u}(b)\right)=D X_{k T} \cdot D X_{r}\left(\mathcal{C}_{y}^{c u}(b)\right) \subset D X_{k T}\left(\mathcal{C}_{X_{r} y}^{c u}(4 b)\right) \subset \mathcal{C}_{X_{t}}^{c u}(b)
$$

This completes the proof of (3.2).
The proof of (3.1) is similar, so we only sketch the details. Using (2.2) as before, we obtain that $D X_{-t}\left(\mathcal{C}_{X_{t} x}^{s}(b)\right) \subset \mathcal{C}_{x}^{s}\left(b \lambda^{t}\right)$ for all $x \in \Lambda, b>0, t \geq 0$. Let $y \in U_{0}, b \geq a$, $v \in \mathcal{C}_{X_{t} y}^{s}(b)$ where $t \geq 0$, and pass to a nearby point $x_{t} \in \Lambda$ such that $v_{X_{t} x_{t}} \in \mathcal{C}_{X_{t} x_{t}}^{s}(2 b)$. (The only difference here is the dependence of $x_{t}$ on $t$.) As before, we obtain that

$$
D X_{-T}\left(X_{T} x_{T}\right) v_{X_{T} x_{t}} \in \mathcal{C}_{x_{T}}^{s}(b / 8) \quad \text { and } \quad D X_{-t}\left(X_{t} x_{t}\right) v_{X_{t} x_{t}} \in \mathcal{C}_{x_{t}}^{s}(2 b) \text { for all } t \geq 0
$$

from which it follows that

$$
D X_{-T}\left(\mathcal{C}_{X_{T} y}^{s}(b)\right) \subset \mathcal{C}_{y}^{s}(b / 4) \subset \mathcal{C}_{y}^{s}(b) \quad \text { and } \quad D X_{-r}\left(\mathcal{C}_{X_{r} y}^{s}(b)\right) \subset \mathcal{C}_{y}^{s}(4 b)
$$

for all $r \in[0, T], y \in U_{0}$. The last formulas are the direct analogy to those in (3.5), and the remainder of the proof of (3.1) is identical to the proof of (3.2).

Next we turn to part (b). The choices of $T$ and $U_{0}$ are unchanged. Recall that $a \in$ $\left(0, \frac{1}{4}\right]$ is fixed. First we prove (3.3). Suppose that $x \in \Lambda$ and $v \in \mathcal{C}_{X_{T} x}^{s}(2 a)$. By (3.1), $D X_{-T}\left(X_{T} x\right) v \in \mathcal{C}_{x}^{s}(2 a)$, so using (2.1),

$$
\begin{aligned}
\left\|D X_{-T}\left(X_{T} x\right) v\right\| & \geq(1-2 a)\left\|\left(D X_{-T}\left(X_{T} x\right) v\right)^{s}\right\|=(1-2 a)\left\|\left(D X_{T}(x)\right)^{-1} v^{s}\right\| \\
& \geq(1-2 a) \lambda^{-T}\left\|v^{s}\right\| \geq(1+2 a)^{-1}(1-2 a) \lambda^{-T}\|v\| \geq 50\|v\| \geq 8\|v\| .
\end{aligned}
$$

Now let $y \in U_{0}, v \in \mathcal{C}_{X_{T} y}^{s}(a)$. As in part (a), we can pass to a nearby point $x \in \Lambda$ with corresponding vector $v_{x} \in \mathcal{C}_{X_{T} x}^{s}(2 a)$ and so $\left\|D X_{-T}\left(X_{T} x\right) v_{x}\right\| \geq 8\left\|v_{x}\right\|$. Using (iii) together with positive invariance of $U_{0}$, we have that $\left\|D X_{-T}\left(X_{T} y\right) v\right\| \geq 2\|v\|$ for all $v \in \mathcal{C}_{X_{T} y}^{s}(a)$.

By positive invariance of $U_{0}$ and (3.1), it follows inductively that

$$
\begin{equation*}
\left\|D X_{-k T}\left(X_{k T} y\right) v\right\| \geq 2^{k}\|v\| \quad \text { for } y \in U_{0}, v \in \mathcal{C}_{X_{k T} y}^{s}(a), k \geq 0 \tag{3.6}
\end{equation*}
$$

Finally, we consider the case of general $t=k T+r$ where $k \in \mathbb{N}, r \in[0, T)$. Let $v \in \mathcal{C}_{X_{t} y}^{s}(a)$. Then $D X_{-t}\left(X_{t} y\right) v=D X_{-r}\left(X_{r} y\right) D X_{-k T}\left(X_{t} y\right) v$ so it follows from positive invariance and (3.6) that

$$
\left\|D X_{-t}\left(X_{t} y\right) v\right\| \geq c\left\|D X_{-k T}\left(X_{k T}\left(X_{r} y\right)\right) v\right\| \geq c 2^{k}\|v\|,
$$

where $c=\inf _{r \in[0, T]} \inf _{y \in U_{0}} \inf _{v \in T_{y} M, v \neq 0}\left\|D X_{-r}(y) v\right\| /\|v\|>0$. This completes the proof of (3.3).

To prove (3.4), we start from (2.2) so for $x \in \Lambda, u, v \in T_{x} M$,

$$
\frac{\left\|D X_{T}(x) u^{s}\right\|}{\left\|u^{s}\right\|} \leq\left\|D X_{T} \mid E_{x}^{s}\right\| \leq \lambda^{T}\left\|\left(D X_{T} \mid E_{x}^{c u}\right)^{-1}\right\|^{-1} \leq \lambda^{T} \frac{\left\|D X_{T}(x) v^{c u}\right\|}{\left\|v^{c u}\right\|} .
$$

Let $u \in D X_{-T}\left(\mathcal{C}_{X_{T} x}^{s}(2 a)\right), v \in \mathcal{C}_{x}^{c u}(2 a)$. By (3.1) and (3.2),

$$
\frac{\left\|D X_{T}(x) v^{c u}\right\|}{\left\|v^{c u}\right\|} \leq \frac{(1+2 a)\left\|D X_{T}(x) v\right\|}{(1-2 a)\|v\|}, \quad \text { and } \quad \frac{\left\|D X_{T}(x) u\right\|}{\|u\|} \leq \frac{(1+2 a)\left\|D X_{T}(x) u^{s}\right\|}{(1-2 a)\left\|u^{s}\right\|},
$$

and so

$$
\frac{\left\|D X_{T}(x) u\right\|}{\|u\|} \leq 9 \lambda^{T} \frac{\left\|D X_{T}(x) v\right\|}{\|v\|} \leq \frac{3}{50} \frac{\left\|D X_{T}(x) v\right\|}{\|v\|}
$$

for all $v \in \mathcal{C}_{x}^{c u}(2 a), u \in D X_{-T}\left(\mathcal{C}_{X_{T} x}^{s}(2 a)\right)$. Using (iii), it follows that

$$
\frac{\left\|D X_{T}(y) u\right\|}{\|u\|} \leq \frac{24}{25} \frac{\left\|D X_{T}(y) v\right\|}{\|v\|}
$$

for all $v \in \mathcal{C}_{y}^{c u}(a), u \in D X_{-T}\left(\mathcal{C}_{X_{T} y}^{s}(a)\right)$. For general $t \geq 0$, we write $t=k T+r, k \geq 0$, $r \in[0, T)$ and proceed as in the proof of (3.3).
3.2. Stable bundle over a neighborhood of $\Lambda$. Whereas the original splitting $T_{\Lambda} M=$ $E^{s} \oplus E^{c u}$ is $D X_{t}$-invariant, in general the extension $E^{c u}$ of the center-unstable bundle cannot be assumed to be invariant. However the extension $E^{s}$ of the stable bundle may be chosen to be $D X_{t}$-invariant:

Proposition 3.2. The continuous bundle $E^{s}$ over $U_{0}$ can be chosen to be $D X_{t}$-invariant and uniformly contracting: $\left\|D X_{t} \mid E_{x}^{s}\right\| \leq c^{-1} \tilde{\lambda}^{t}$ for all $t \geq 0, x \in U_{0}$, where $c>0$, $\tilde{\lambda} \in(0,1)$ are the constants in Proposition 3.1.

Proof. We begin with the original choice of continuous splitting $T_{U_{0}} M=E^{s} \oplus E^{c u}$. Let $a \in\left(0, \frac{1}{4}\right]$ and choose $T$ and $U_{0}$ as in Proposition 3.1. For $x \in U_{0}$, define

$$
F_{x}=\bigcap_{t \geq 0} D X_{-t}\left(\mathcal{C}_{X_{t} x}^{s}(a)\right) .
$$

We show that $\left\{F_{x}\right\}$ is the desired stable bundle. That is, we show that for all $t \geq 0$,
(i) $x \mapsto F_{x}$ is a continuous map from $U_{0}$ to the Grassmannian bundle $\mathcal{G}=\left\{\mathcal{G}_{x}, x \in U_{0}\right\}$ where $\mathcal{G}_{x}$ is the space of $d_{s}$-dimensional subspaces of $T_{x} M$,
(ii) $F_{x}=E_{x}^{s}$ for $x \in \Lambda$,
(iii) $\left\{F_{x}, x \in U_{0}\right\}$ is $D X_{t}$-invariant and uniformly contracting.

Now $\left\{D X_{-t}\left(\mathcal{C}_{X_{t} x}^{s}(a)\right), t \geq 0\right\}$ is a nested family of closed cones, and by (3.1) the cones are contained in $\mathcal{C}_{x}^{s}(a)$ for $t \geq T$. In particular, $F_{x} \subset \mathcal{C}_{x}^{s}(a)$.

We can also regard $\left\{D X_{-t}\left(\mathcal{C}_{X_{t x}}^{s}(a)\right), t \geq 0\right\}$ as a nested family of closed subsets of $\mathcal{G}_{x}$, so $F_{x}$ is a closed subset of $\mathcal{G}_{x}$. By compactness of $\mathcal{G}_{x}$, the elements $D X_{-t} E_{X_{t} x}^{s} \in \mathcal{G}_{x}$ have a convergent subsequence $D X_{-t_{n}} E_{X_{t_{n} x} x}^{s}$ with limit $\tilde{F}_{x} \in \mathcal{G}_{x}$. Since $D X_{-t} E_{X_{t x}}^{s} \in$ $D X_{-t}\left(\mathcal{C}_{X_{t} x}^{s}(a)\right)$ and $F_{x}$ is closed, it follows that $\tilde{F}_{x} \in F_{x}$.

To summarise, we have shown that there exists a $d_{s}$-dimensional subspace $\tilde{F}_{x}$ such that $\tilde{F}_{x} \subset F_{x}$ and $\tilde{F}_{x}=\lim _{n \rightarrow \infty} D X_{-t_{n}} E_{X_{t_{n} x} x}^{s}$ (in $\mathcal{G}_{x}$ ). Without loss we may suppose that $t_{n} \geq T$ for all $n$.

Next we show that $F_{x}=\tilde{F}_{x}$. Choose vectors $u_{n} \in E_{X_{t_{n} x}}^{s}$ such that $\left\|D X_{-t_{n}}\left(X_{t_{n}} x\right) u_{n}\right\|=1$. Suppose for contradiction that $F_{x} \neq \tilde{F}_{x}$. Then $F_{x}$ is a nontrivial cone containing $\tilde{F}_{x}$, and so there exists $v \in E_{x}^{c u}$ nonzero such that $w_{n}=D X_{-t_{n}}\left(X_{t_{n}} x\right) u_{n}+v \in F_{x}$ for $n$ sufficiently large. It follows from the definition of $F_{x}$ that $D X_{t_{n}}(x) w_{n}=u_{n}+D X_{t_{n}}(x) v \in \mathcal{C}_{X_{t_{n}} x}^{s}(a)$. Hence

$$
\begin{equation*}
\left\|\left(D X_{t_{n}}(x) v\right)^{c u}\right\| \leq a\left\|u_{n}+\left(D X_{t_{n}}(x) v\right)^{s}\right\| . \tag{3.7}
\end{equation*}
$$

Since $v \in E_{x}^{c u}$, it follows from (3.2) that $D X_{t_{n}}(x) v \in \mathcal{C}_{x}^{c u}(a)$ and hence $\left\|\left(D X_{t_{n}}(x) v\right)^{s}\right\| \leq$ $a\left\|\left(D X_{t_{n}}(x) v\right)^{c u}\right\|$ and $\left\|D X_{t_{n}}(x) v\right\| \leq(1+a)\left\|\left(D X_{t_{n}}(x) v\right)^{c u}\right\|$. Substituting into (3.7) yields $\left(1-a^{2}\right)\left\|\left(D X_{t_{n}}(x) v\right)^{c u}\right\| \leq a\left\|u_{n}\right\|$ and then

$$
\left\|D X_{t_{n}}(x) v\right\| \leq(1+a)\left(1-a^{2}\right)^{-1} a\left\|u_{n}\right\| .
$$

On the other hand, $u_{n} \in E_{X_{t_{n}} x}^{s}, v \in E_{x}^{c u}$, so by (3.4),

$$
\frac{\left\|D X_{t_{n}}(x) v\right\|}{\|v\|} \geq c \tilde{\lambda}^{-t_{n}} \frac{\left\|u_{n}\right\|}{\left\|D X_{-t_{n}}\left(X_{t_{n}} x\right) u_{n}\right\|}=c \tilde{\lambda}^{-t_{n}}\left\|u_{n}\right\| .
$$

Letting $n \rightarrow \infty$ yields the desired contradiction, and so $F_{x}$ and $\tilde{F}_{x}$ coincide. In particular, $F_{x} \in \mathcal{G}_{x}$ for all $x \in U_{0}$.

To prove continuity of the map $x \mapsto F_{x}$, fix $x \in U_{0}$ and let $\mathcal{U} \subset \mathcal{G}$ be a neighborhood of $F_{x}$. There exists $t_{0} \geq 0$ such that $\bigcap_{t \leq t_{0}} D X_{-t}\left(\mathcal{C}_{X_{t x}}^{s}(a)\right) \subset \mathcal{U}$. By smoothness of the flow, $F_{y} \subset \bigcap_{t \leq t_{0}} D X_{-t}\left(\mathcal{C}_{X_{t} y}^{s}(a)\right) \subset \mathcal{U}$ for $y$ sufficiently close to $x$. This completes the proof of (i).

It is immediate from invariance of the bundle $E^{s} \mid \Lambda$ that $E_{x}^{s} \subset F_{x}$ for all $x \in \Lambda$. Hence $E_{x}^{s}=F_{x}$ for all $x \in \Lambda$ establishing (ii).

For $r \geq 0$,

$$
\begin{aligned}
D X_{r} F_{x} & =\bigcap_{t \geq 0} D X_{r-t}\left(\mathcal{C}_{X_{t-r}\left(X_{r} x\right)}^{s}(a)\right)=\bigcap_{t \geq r} D X_{r-t}\left(\mathcal{C}_{X_{t-r}\left(X_{r} x\right)}^{s}(a)\right) \\
& =\bigcap_{t \geq 0} D X_{-t}\left(\mathcal{C}_{X_{t}\left(X_{r} x\right)}^{s}(a)\right)=F_{X_{r} x},
\end{aligned}
$$

so the bundle $\left\{F_{x}\right\}$ is $D X_{t}$-invariant. Finally, if $v \in F_{x}, t \geq 0$, then $D X_{t}(x) v \in \mathcal{C}_{X_{t x}}^{s}(a)$ so by (3.3), $\|v\| \geq c \tilde{\lambda}^{-t}\left\|D X_{t}(x) v\right\|$. Hence $\left\|D X_{t} \mid F_{x}\right\| \leq c^{-1} \tilde{\lambda}^{t}$ so (iii) holds.

From now on, we suppose that the continuous extension $T_{U_{0}} M=E^{s} \oplus E^{c u}$ of $T_{\Lambda} M=$ $E^{s} \oplus E^{c u}$ is chosen so that $E^{s}$ is invariant and uniformly contracted.

Remark 3.3. In the definition of partial hyperbolicity, we assumed uniform contraction along $E^{s}$ and dominated splitting. However the uniform contraction assumption (2.1) was used only to ensure that the extended stable bundle is uniformly contracting.

For attracting sets satisfying just the dominated splitting assumption (2.2), it still follows from the arguments above that the bundle $E^{s}$ over $\Lambda$ extends to a continuous invariant bundle over a neighborhood of $\Lambda$.

Remark 3.4. Let $r \geq 1$. A compact invariant set for a $C^{r}$ diffeomorphism $f: M \rightarrow M$ is partially hyperbolic if there is a continuous $D f$-invariant splitting $T_{\Lambda} M=E^{s} \oplus E^{c u}$ where $\operatorname{dim} E^{s} \geq 1$ and $\operatorname{dim} E^{c u} \geq 1$, and there exist constants $C>0, \lambda \in(0,1)$ such that for every $n \geq 1$ and every $x \in \Lambda$, we have

$$
\left\|D f^{n}\left|E_{x}^{s}\left\|\leq C \lambda^{n} ; \quad\right\| D f^{n}\right| E_{x}^{s}\right\| \cdot\left\|D f^{-n} \mid E_{f^{n} x}^{c u}\right\| \leq C \lambda^{n}
$$

It is easily seen that the results in this section go through for partially hyperbolic attractors for diffeomorphisms, with $f$ playing the role of $X_{1}$ and $X_{T}$ replaced by a high enough iterate of $f$.

## 4. The stable foliation for partially hyperbolic attractors

In this section, we discuss the existence and regularity properties of the stable foliation associated with a partially hyperbolic attractor $\Lambda$ satisfying the conditions in Definition 2.2. Sectional expansion is not assumed. Again we focus on partially hyperbolic attractors for flows, but the situation for diffeomorphisms is the same (cf. Remark 3.4).

In Subsection 4.1, we prove that the stable bundle $E^{s}$ integrates to a contracting invariant topological foliation of a neighborhood of $\Lambda$ with smooth leaves. In Subsection 4.2, we obtain smoothness of the foliation under a suitable bunching condition.

Remark 4.1. The results in this section follow entirely from standard arguments. However the proof that the extended stable bundle $E^{s}$ in Section 3.2 integrates to a topological foliation is complicated by the noninvariance of the complementary bundle $E^{c u}$. Since we have been unable to find a formulation in the literature that does not assume invariance of both $E^{s}$ and $E^{c u}$, we present below the details of the standard arguments suitably modified.
4.1. Stable foliation in a neighborhood of $\Lambda$. Let $\mathbb{D}^{k}$ denote the $k$-dimensional open unit disk and let $\operatorname{Emb}^{r}\left(\mathbb{D}^{k}, M\right)$ denote the set of $C^{r}$ embeddings $\phi: \mathbb{D}^{k} \rightarrow M$ endowed with the $C^{r}$ distance.

Theorem 4.2. There exists a positively invariant neighborhood $U_{0}$ of $\Lambda$, and a constant $\nu \in(0,1)$, such that the following are true.
(a) For every point $x \in U_{0}$ there is a $C^{r}$ embedded $d_{s}$-dimensional disk $W_{x}^{s} \subset M$, with $x \in W_{x}^{s}$, such that
(1) $T_{x} W_{x}^{s}=E_{x}^{s}$.
(2) $X_{t}\left(W_{x}^{s}\right) \subset W_{X_{t x}}^{s}$ for all $t \geq 0$.
(3) $d\left(X_{t} x, X_{t} y\right) \leq \nu^{t} d(x, y)$ for all $y \in W_{x}^{s}, t \geq 0$.
(b) The disks $W_{x}^{s}$ depend continuously on $x$ in the $C^{0}$ topology: there is a continuous map $\gamma: U_{0} \rightarrow \operatorname{Emb}^{0}\left(\mathbb{D}^{d_{s}}, M\right)$ such that $\gamma(x)(0)=x$ and $\gamma(x)\left(\mathbb{D}^{d_{s}}\right)=W_{x}^{s}$.
(c) The family of disks $\left\{W_{x}^{s}: x \in U_{0}\right\}$ defines a topological foliation of $U_{0}$.

To prove Theorem 4.2, we begin by following the exposition in [12, Section 6.4(b)].
Let $T>0, c>0, \tilde{\lambda} \in(0,1)$ be the constants in Propositions 3.1 and 3.2. Increase $T>0$ if necessary so that $\hat{\lambda}=c^{-1} \tilde{\lambda}^{T} \in(0,1)$. Define the diffeomorphism $f=X_{T}: U_{0} \rightarrow U_{0}$.

For each $x \in U_{0}$, we consider the exponential map $\exp _{x}: T_{x} M \rightarrow M$. This transforms a small enough neighborhood of 0 diffeomorphically onto a neighborhood of $x$, and $D \exp _{x}(0)=I$.

Choose orthonormal bases on $\mathbb{R}^{d_{s}}, \mathbb{R}^{d_{c u}}$. Also for each $x \in U_{0}$, choose orthonormal bases on $E_{x}^{s}$ and $E_{x}^{c u}$. Let $P_{x}^{s}: \mathbb{R}^{d_{s}} \rightarrow E_{x}^{s}, P_{x}^{c u}: \mathbb{R}^{d_{c u}} \rightarrow E_{x}^{c u}$ be the corresponding isometric isomorphisms. The splitting $E^{s} \oplus E^{c u}$ is continuous so we can arrange that $x \mapsto P_{x}^{s}$ and $x \mapsto P_{x}^{c u}$ are continuous families of isomorphisms.

Define $P_{x, n}=P_{f^{n} x}^{s}+D f^{n}(x) P_{x}^{c u}: \mathbb{R}^{d} \rightarrow T_{f^{n} x} M$. Note that $x \mapsto P_{x, n}$ is a continuous family of isomorphisms for each $n$. In general $P_{x, n}$ is not an isometric isomorphism since $D f^{n} E_{x}^{c u}$ is not necessarily orthogonal to $E_{f^{n} x}^{s}$. However, it follows from (3.2) that $D f^{n} E_{x}^{c u} \subset \mathcal{C}_{f^{n} x}^{c u}(a)$ for some $a \in\left(0, \frac{1}{4}\right]$, and so the angle between the subspaces $E_{f^{n} x}^{s}$ and $D f^{n} E_{x}^{c u}$ is bounded away from zero. Hence there is a constant $C_{1} \geq 1$ such that $C_{1}^{-1} \leq\left\|P_{x, n}\right\| \leq C_{1}$ for all $x \in U_{0}, n \geq 0$.

Next, $Q_{x, n}=\exp _{f^{n} x} \circ P_{x, n}: \mathbb{R}^{d} \rightarrow M$ maps a neighborhood of 0 in $\mathbb{R}^{d}$ diffeomorphically onto a neighborhood of $f^{n} x$. Again, $x \mapsto Q_{x, n}$ is a continuous family of diffeomorphisms for each $n$.

Let $D_{\rho} \subset \mathbb{R}^{d}$ denote the $\rho$-neighborhood of 0 . Using boundedness of $\left\|P_{n}\right\|$ and compactness of $\Lambda$, and shrinking $U_{0}$ if necessary, we can choose $\rho>0$ so that $Q_{x, n}: D_{\rho} \rightarrow M$ is a diffeomorphism onto its range for all $n$. Moreover, there is a constant $C_{2} \geq 1$ such that

$$
C_{2}^{-1}\|p\| \leq d\left(f^{n} x, Q_{x, n}(p)\right) \leq C_{2}\|p\| \text { for all } x \in U_{0}, n \geq 0, p \in D_{\rho} .
$$

Now define the family of maps $f_{x, n}=Q_{x, n+1}^{-1} \circ f \circ Q_{x, n}: D_{\rho} \rightarrow \mathbb{R}^{d}$. By construction, $D f_{x, n}(0)$ is identified with $D f\left(f^{n} x\right)$. Also, the maps $f_{x, n}$ are uniformly $C^{r}$ close to $D f_{x, n}(0)$ on $D_{\rho}$. Hence for any $\delta>0$ there exists $\rho>0$ and a family of (surjective) $C^{r}$ diffeomorphisms $g_{x, n}: \mathbb{R}^{d} \rightarrow \mathbb{R}^{d}, n \geq 0$, such that $\left\|g_{x, n}-D f_{x, n}(0)\right\|_{C^{1}}<\delta$ and $g_{x, n}=f_{x, n}$ on $D_{\rho}$. (See for example [12, Lemma 6.2.7].)

Proposition 4.3. For all $n \geq 0$,

$$
\left\|D g_{x, n}(0)\left|\mathbb{R}^{d_{s}}\|\leq \hat{\lambda}, \quad\| D g_{x, n}(0)\right| \mathbb{R}^{d_{s}}\right\| \cdot\left\|D g_{x, n}(0)^{-1} \mid \mathbb{R}^{d_{c u}}\right\| \leq \hat{\lambda}
$$

Proof. Choose $a$ as in Proposition 3.1. By construction, $D g_{x, n}(0)=D f_{x, n}(0)$ is identified with $D f\left(f^{n} x\right)$ and moreover,

$$
\begin{aligned}
& \left\|D g_{x, n}(0)\left|\mathbb{R}^{d_{s}}\|=\| D f\right| E_{f^{n} x}^{s}\right\|=\left\|D X_{T} \mid D X_{-T} E_{X_{T} f_{x} x}^{s}\right\|, \\
& \left\|D g_{x, n}(0)^{-1}\left|\mathbb{R}^{d_{c u}}\|=\| D f^{-1}\right| D f^{n+1} E_{x}^{c u}\right\| \leq\left\|D X_{-T} \mid D X_{T}\left(\mathcal{C}_{f^{n} x}^{c u}(a)\right)\right\|,
\end{aligned}
$$

where we have used invariance of $E^{s}$ and forward invariance of $\mathcal{C}^{c u}(a)$. The second estimate follows from (3.4). The first estimate is immediate from Proposition 3.2.

We require a slightly modified version of the Hadamard-Perron Invariant Manifold Theorem from [12, Theorem 6.2.8, pp 242-257]:

Lemma 4.4. Let $r \geq 1$. Fix $\lambda_{\text {min }}>0, \sigma \in(0,1)$. Then there exists $\gamma, \delta>0$ arbitrarily small so that the following holds:

For each $n$ let $g_{n}: \mathbb{R}^{d} \rightarrow \mathbb{R}^{d}$ be a $C^{r}$ diffeomorphism such that

$$
\begin{equation*}
g_{n}(u, v)=\left(A_{n} u+\alpha_{n}(u, v), B_{n} v+\beta_{n}(u, v)\right), \quad(u, v) \in \mathbb{R}^{d_{s}} \oplus \mathbb{R}^{d_{c u}} \tag{4.1}
\end{equation*}
$$

for linear maps $A_{n}: \mathbb{R}^{d_{s}} \rightarrow \mathbb{R}^{d_{s}}, B_{n}: \mathbb{R}^{d_{c u}} \rightarrow \mathbb{R}^{d_{c u}}$ and $C^{r}$ maps $\alpha_{n}: \mathbb{R}^{d} \rightarrow \mathbb{R}^{d_{s}}, \beta_{n}: \mathbb{R}^{d} \rightarrow$ $\mathbb{R}^{d_{c u}}$ with $\alpha_{n}(0,0)=0, \beta_{m}(0,0)=0$ and $\left\|\alpha_{n}\right\|_{C^{1}}<\delta,\left\|\beta_{n}\right\|_{C^{1}}<\delta$.

Define $\lambda_{n}=\left\|A_{n}\right\|$, $\mu_{n}=\left\|B_{n}^{-1}\right\|^{-1}$ and suppose that $\lambda_{n} \geq \lambda_{\min }$ and $\lambda_{n} / \mu_{n} \leq \sigma$. Set $\lambda_{n}^{\prime}=(1+\gamma)\left(\lambda_{n}+\delta(1+\gamma)\right), \mu_{n}^{\prime}=\frac{\mu_{n}}{1+\gamma}-\delta$ and suppose that $\lambda_{n}^{\prime}<\nu_{n}<\mu_{n}^{\prime}$ for all $n \in \mathbb{Z}$.

Then there exists a unique family of $d_{s}$-dimensional $C^{1}$ manifolds $Z_{n}=\left\{\left(x, \varphi_{n}(x)\right): x \in\right.$ $\left.\mathbb{R}^{d_{s}}\right\}$, where $\varphi_{n}: \mathbb{R}^{d_{s}} \rightarrow \mathbb{R}^{d_{c u}}$ satisfies $\varphi_{n}(0,0)=0, D \varphi_{n}(0,0)=0$, and $\left\|D \varphi_{n}\right\|_{C^{0}}<\gamma$ for all $n \in \mathbb{Z}$, and the following properties hold for all $n \in \mathbb{Z}$ :
(1) $g_{n}\left(Z_{n}\right)=Z_{n+1}$,
(2) $\left\|g_{n}(q)\right\| \leq \lambda_{n}^{\prime}\|q\|$ for $q \in Z_{n}$,
(3) If $\left\|g_{n+k-1} \circ \cdots \circ g_{n}(q)\right\| \leq C \nu_{n+k-1} \ldots \nu_{n}\|q\|$ for all $k \geq 0$ and some $C>0$, then $q \in Z_{n}$.
If $\sup _{n} \lambda_{n}<1$, then the manifolds $Z_{n}$ are $C^{r}$.
Proof. The only difference from [12, Theorem 6.2.8, pp 242-257] is that the rates $\lambda_{n}, \mu_{n}$ may depend on $n$. However, the ratios $\lambda_{n} / \mu_{n}$ are controlled uniformly, and it is easy to check that the proof in pp 242-257 of [12] is valid in this slightly more general setting with no change in the arguments.

Remark 4.5. The constraints on $\gamma$ and $\delta$ can be made explicit:

$$
\gamma<\min \left\{1, \sigma^{-1 / 2}-1\right\}, \quad \delta<\lambda_{\min } \min \left\{\frac{\sigma^{-1}-1}{\gamma+\gamma^{-1}+2}, \frac{\sigma^{-1}-(1+\gamma)^{2}}{(2+\gamma)(1+\gamma)}\right\} .
$$

Remark 4.6. In Lemma 4.4, there exists also a unique family of $d_{c u}$-dimensional $C^{1}$ manifolds $\tilde{Z}_{n}=\left\{\left(x, \psi_{n}(x)\right): x \in \mathbb{R}^{d_{c u}}\right\}$ satisfying analogous properties to the family $Z_{n}$. This leads to a family of center-unstable manifolds $\left\{W_{x}^{c u}, x \in \Lambda\right\}$ each of which is tangent at $x$ to $E_{x}^{c u}$. These manifolds do not play a role in this paper. (Unlike the case for stable manifolds, there is no useful notion of $W_{x}^{c u}$ for $x \notin \Lambda$.)

Next, we verify the hypotheses of Lemma 4.4. Fix $x \in U_{0}$. The sequence of diffeomorphisms $g_{x, n}: \mathbb{R}^{d} \rightarrow \mathbb{R}^{d}$ is defined for $n \geq 0$. For $n<0$, we set $g_{x, n}=g_{x, 0}$. The diffeomorphisms $g_{x, n}$ have the structure in (4.1). Take $\sigma=\hat{\lambda} \in(0,1)$ and $\lambda_{\text {min }}=\inf _{x \in U_{0}} \| D X_{T} \mid$ $E_{x}^{s} \|>0$. By Proposition 4.3, the linear maps $A_{n}, B_{n}$ satisfy the constraints $\lambda_{\text {min }} \leq \lambda_{n} \leq \sigma$ and $\lambda_{n} / \mu_{n} \leq \sigma$. Choose $\gamma, \delta>0$ so small that $\sup _{n} \lambda_{n}^{\prime}<1$ and $\sup _{n} \lambda_{n}^{\prime} / \mu_{n}^{\prime}<1$. Choose $\nu_{n} \in\left(\lambda_{n}^{\prime}, \mu_{n}^{\prime}\right)$ such that $\nu=\sup _{n} \nu_{n}<1$. Finally, shrink $\rho$ so that $\left\|\alpha_{n}\right\|_{C^{1}}<\delta,\left\|\beta_{n}\right\|_{C^{1}}<\delta$.

We have shown that the hypotheses of Lemma 4.4 are satisfied, with $\nu_{n} \leq \nu<1$ for all $n$. Let $Z_{x, n}$ denote the family of $d_{s}$-dimensional $C^{r}$ manifolds in Lemma 4.4 and define

$$
W_{x}^{s}=Q_{x, 0}\left(Z_{x, 0} \cap D_{\rho}\right) .
$$

Repeating the construction for every $x \in U_{0}$, we obtain a family $\left\{W_{x}^{s}, x \in U_{0}\right\}$ of $d_{s^{-}}$ dimensional $C^{r}$ manifolds covering $U_{0}$. We claim that this is the desired family of stable manifolds.

Lemma 4.7. Let $x, y \in U_{0}$.
(a) If $d(x, y)<C_{2}^{-1} \rho$ and $y \in W_{x}^{s}$ then $d\left(f^{n} x, f^{n} y\right) \leq C_{2}^{2} \nu^{n} d(x, y)$ for all $n \geq 0$.
(b) Let $C>0$. If $d(x, y)<C_{2}^{-1} C^{-1} \rho$ and $d\left(f^{n} x, f^{n} y\right) \leq C \nu^{n} d(x, y)$ for all $n \geq 0$, then $y \in W_{x}^{s}$.
(c) There exists $\varepsilon>0$ such that if $d(x, y)<\varepsilon$ and $y \in W_{x}^{s}$ then $f y \subset W_{f x}^{s}$.

Proof. Let

$$
F_{x, n}=f_{x, n-1} \circ \cdots \circ f_{x, 0}, \quad G_{x, n}=g_{x, n-1} \circ \cdots \circ g_{x, 0} .
$$

Note that if $F_{x, n}(q) \in D_{\rho}$ for all $0 \leq n \leq N_{0}$, or if $G_{x, n}(q) \in D_{\rho}$ for all $0 \leq n \leq N_{0}$, then $F_{x, n}(q)=G_{x, n}(q)$ for all $0 \leq n \leq N_{0}$.
(a) Let $y \in W_{x}^{s}$ with $d(x, y)<C_{2}^{-1} \rho$. Then $q=Q_{x, 0}^{-1}(y) \in Z_{x, 0}$, so by Lemma $4.4(1,2)$,

$$
\left\|G_{x, n}(q)\right\| \leq \nu^{n}\|q\|=\nu^{n}\left\|Q_{x, 0}^{-1}(y)\right\| \leq \nu^{n} C_{2} d(x, y)<\rho,
$$

for all $n \geq 0$. Now $f^{n}=Q_{x, n} \circ F_{x, n} \circ Q_{x, 0}^{-1}$, so

$$
f^{n} y=Q_{x, n} \circ F_{x, n}(q)=Q_{x, n} \circ G_{x, n}(q) .
$$

Hence

$$
d\left(f^{n} x, f^{n} y\right)=d\left(f^{n} x, Q_{x, n} \circ G_{x, n}(q)\right) \leq C_{2}\left\|G_{x, n}(q)\right\| \leq C_{2}^{2} \nu^{n} d(x, y)
$$

(b) Suppose that $d(x, y)<C_{2}^{-1} C^{-1} \rho$ and $d\left(f^{n} x, f^{n} y\right) \leq C \nu^{n} d(x, y)$ for all $n \geq 0$. Let $q=Q_{x, 0}^{-1}(y)$ so $d(x, y) \leq C_{2}\|q\|$. Now $F_{x, n}=Q_{x, n}^{-1} \circ f^{n} \circ Q_{x, 0}$, so

$$
\left\|F_{x, n}(q)\right\|=\left\|Q_{x, n}^{-1} \circ f^{n}(y)\right\| \leq C_{2} d\left(f^{n} x, f^{n} y\right) \leq C_{2} C \nu^{n} d(x, y)<\rho
$$

Hence

$$
\left\|G_{x, n}(q)\right\|=\left\|F_{x, n}(q)\right\| \leq C_{2} C \nu^{n} d(x, y) \leq C_{2}^{2} C \nu^{n}\|q\| .
$$

By Lemma 4.4(3), $q \in Z_{x, 0} \cap D_{\rho}$ and so $y=Q_{x, 0}(q) \subset W_{x}^{s}$.
(c) Let $x^{\prime}=f x, y^{\prime}=f y$ and choose $E \geq 1$ such that $d(x, y) \leq E d\left(x^{\prime}, y^{\prime}\right)$ for all $x, y \in U_{0}$.

Suppose that $y \in W_{x}^{s}$ and $d(x, y)<C_{2}^{-5} E^{-1} \rho$. Then certainly, $d(x, y)<C_{2}^{-1} \rho$, so by part (a),

$$
d\left(f^{n} x^{\prime}, f^{n} y^{\prime}\right)=d\left(f^{n+1} x, f^{n+1} y\right) \leq C_{2}^{2} \nu^{n+1} d(x, y) \leq C_{2}^{2} E \nu^{n} d\left(x^{\prime}, y^{\prime}\right)=C \nu^{n} d\left(x^{\prime}, y^{\prime}\right)
$$

where $C=C_{2}^{2} E$. Also, $d\left(x^{\prime}, y^{\prime}\right) \leq C_{2}^{2} d(x, y)<C_{2}^{-3} E^{-1} \rho=C_{2}^{-1} C^{-1} \rho$, so the result follows from part (b).
Lemma 4.8. The $C^{r}$ embedded disks $W_{x}^{s}$ depend continuously on $x$ in the $C^{0}$ topology: there is a continuous map $\gamma: U_{0} \rightarrow \operatorname{Emb}^{0}\left(\mathbb{D}^{d_{s}}, M\right)$ such that $\gamma(x)(0)=x$ and $\gamma(x)\left(\mathbb{D}^{d_{s}}\right)=W_{x}^{s}$. Moreover, there exists $L \geq 1$ such that $\operatorname{Lip} \gamma(x) \leq L$ for all $x \in U_{0}$, where $\operatorname{Lip} \gamma(x)=$ $\sup _{u \neq u^{\prime}} d\left(\gamma(x)(u), \gamma(x)\left(u^{\prime}\right)\right) /\left\|u-u^{\prime}\right\|$.

Proof. Fix $x \in U_{0}$ and recall that $W_{x}^{s}=Q_{x, 0}\left(Z_{x, 0} \cap D_{\rho}\right)$. For $y$ close to $x$, let $A_{y}=Q_{x, 0}^{-1}\left(W_{y}^{s}\right)$. Let $p_{y}=Q_{x, 0}^{-1}(y)=Q_{x, 0}^{-1} \circ Q_{y, 0}(0) \in A_{y}$. In particular $A_{x}=Z_{x, 0} \cap D_{\rho}$ and $p_{x}=0$. Moreover, $y \mapsto p_{y}$ is continuous.

Now $T_{p_{y}} A_{y}=D Q_{x, 0}^{-1}(y) T_{y} W_{y}^{s}=D Q_{x, 0}^{-1}(y) E_{y}^{s}$, so it follows from smoothness of $Q_{x, 0}$ and continuity of $E^{s}$ that $A_{y}$ can be viewed as a graph over $\mathbb{D}^{d_{s}} \subset \mathbb{R}^{d_{s}}$ for $y$ close to $x$. In
particular, $A_{y}=\left\{\left(u, \phi_{y}(u)\right): u \in \mathbb{D}^{d_{s}}\right\}$ where $\phi_{y}: \mathbb{D}^{d_{s}} \rightarrow \mathbb{R}^{d_{c u}}$, see Figure 1. Hence $W_{y}^{s}=\left\{Q_{x, 0}\left(u, \phi_{y}(u)\right): u \in \mathbb{D}^{d_{s}}\right\}$. The family of functions $\phi_{y}$ are $C^{r}$ with uniform Lipschitz constant. Since $p_{y} \in A_{y}$, there exists $u_{y} \in \mathbb{D}^{d_{s}}$ such that $p_{y}=\left(u_{y}, \phi_{y}\left(u_{y}\right)\right)$.


Figure 1. $A_{y}$ as the graph of $\phi_{y}$ near $A_{x}$.
Define the family of embeddings $\gamma: U_{0} \rightarrow \operatorname{Emb}^{r}\left(\mathbb{D}^{d_{s}}, M\right)$ given by

$$
\gamma(y)(u)=Q_{x, 0}\left(u, \phi_{y}(u)\right) .
$$

We claim that $y \mapsto \phi_{y}$ is continuous at $x$ in the $C^{0}$ topology, and hence the embedding $\gamma$ is continuous at $x$ in the $C^{0}$ topology.

It remains to verify the claim. Suppose that $y_{n} \rightarrow x$. By Arzelà-Ascoli, we can pass to a further subsequence such that $\lim _{n \rightarrow \infty} \sup _{u \in \mathbb{D}^{d_{s}}}\left\|\phi_{y_{n}}(u)-\psi(u)\right\|=0$ for some continuous function $\psi: \mathbb{R}^{d_{s}} \rightarrow \mathbb{R}^{d_{c u}}$.

Since $p_{y_{n}} \rightarrow 0$, for $n$ large enough we have that $p_{y_{n}} \in D_{\frac{1}{2} C_{2}^{-5} \rho}$. Now fix $u \in \mathbb{D}^{d_{s}}$ (see Figure 1). Shrinking the disk $\mathbb{D}^{d_{s}}$, we can ensure that $q_{n}=\left(u, \phi_{y_{n}}(u)\right) \in D_{\frac{1}{2} C_{2}^{-5} \rho}$ for $n$ sufficiently large. Hence

$$
d\left(Q_{x, 0}\left(q_{n}\right), y_{n}\right) \leq d\left(Q_{x, 0}\left(q_{n}\right), x\right)+d\left(x, y_{n}\right) \leq C_{2}^{-3} \rho \leq C_{2}^{-1} \rho .
$$

By construction, $Q_{x, 0}\left(q_{n}\right) \in W_{y_{n}}^{s}$, so by Lemma 4.7(a),

$$
d\left(f^{k} \circ Q_{x, 0}\left(q_{n}\right), f^{k} y_{n}\right) \leq C_{2}^{2} \nu^{k} d\left(Q_{x, 0}\left(q_{n}\right), y_{n}\right) \quad \text { for all } k \geq 0
$$

Letting $n \rightarrow \infty$, we obtain that

$$
d\left(f^{k} \circ Q_{x, 0}(u, \psi(u)), f^{k} x\right) \leq C_{2}^{2} \nu^{k} d\left(Q_{x, 0}(u, \psi(u)), x\right) \quad \text { for all } k \geq 0 .
$$

By Lemma 4.7(b), $Q_{x, 0}(u, \psi(u)) \in W_{x}^{s}$ so $(u, \psi(u)) \in A_{x}$. It follows that $\psi(u)=\phi_{x}(u)$. Hence all subsequential limits of $\phi_{y}$ (as $y \rightarrow x$ ) coincide with $\phi_{x} \operatorname{son}^{\lim }{ }_{y \rightarrow x} \phi_{y}=\phi_{x}$ in the $C^{0}$ topology as required.

Lemma 4.9. The family of disks $\left\{W_{x}^{s}: x \in U_{0}\right\}$ defines a topological foliation.
Proof. Let $x \in U_{0}$ and choose an embedded $d_{c u}$-dimensional disk $Y \subset M$ containing $x$ and transverse to $W_{x}^{s}$. By continuity of $E^{s}$, we can shrink $Y$ so that $Y$ is transverse to $W_{y}^{s}$ at $y$ for all $y \in Y$. Let $\psi: \mathbb{D}^{c u} \rightarrow Y$ be a choice of embedding.

Now define $\chi: \mathbb{D}^{s} \times \mathbb{D}^{c u} \rightarrow U_{0}$ by setting $\chi(u, v)=\gamma(\psi(v))(u)$. Note that $\chi$ maps horizontal lines $\{v=$ const. $\}$ homeomorphically onto stable disks; see Figure 2.


Figure 2. Topological foliation chart
By Lemma 4.8, each of these embeddings is Lipschitz with uniform Lipschitz constant $L$. Using this together with the continuity statement in Lemma 4.8,

$$
\begin{aligned}
d\left(\chi(u, v), \chi\left(u_{0}, v_{0}\right)\right) & \leq d\left(\gamma(\psi(v))(u), \gamma(\psi(v))\left(u_{0}\right)\right)+d\left(\gamma(\psi(v))\left(u_{0}\right), \gamma\left(\psi\left(v_{0}\right)\right)\left(u_{0}\right)\right) \\
& \leq L\left\|u-u_{0}\right\|+\left\|\gamma(\psi(v))-\gamma\left(\psi\left(v_{0}\right)\right)\right\|_{C^{0}} \rightarrow 0
\end{aligned}
$$

as $(u, v) \rightarrow\left(u_{0}, v_{0}\right)$, establishing continuity of $\chi$.
Suppose that $\chi\left(u_{1}, v_{1}\right)=\chi\left(u_{2}, v_{2}\right)$ with common value $y \in U_{0}$. Then $y \in W_{x_{1}}^{s} \cap W_{x_{2}}^{s}$ where $x_{j}=\psi\left(v_{j}\right)$. We claim that $x_{1}=x_{2}$ with common value $\hat{x}$. In particular $v_{1}=v_{2}$. But now $\gamma(\hat{x})\left(u_{1}\right)=\gamma(\hat{x})\left(u_{2}\right)$ and so $u_{1}=u_{2}$. It follows that $\chi$ is injective and hence is a homeomorphism onto a neighborhood of $x$ as required.

It remains to prove the claim. Note that $W_{x_{2}}^{s}$ can be viewed as a graph over $W_{x_{1}}^{s}$. Let $A=W_{x_{1}}^{s} \cap W_{x_{2}}^{s}$. We show that $A$ is open and closed in $W_{x_{1}}^{s}$. Since $y \in A$ and $W_{x_{1}}^{s}$ is connected, $A=W_{x_{1}}^{s}$ and in particular, $x_{2}=x_{1}$ as required.

It is clear that $A$ is closed in $W_{x_{1}}^{s}$. To prove that $A$ is open, suppose that $z \in A$. Since $W_{x_{j}}^{s}$ are tangent to $E_{x_{j}}^{s}$ with uniform Lipschitz constant, there exists $C>0$ such that $d\left(x_{1}, x_{2}\right) \leq C d\left(z, x_{j}\right)$. Let $z^{\prime} \in W_{x_{1}}^{s}$ be such that $d\left(z, z^{\prime}\right) \leq(1 / 2 C) d\left(x_{1}, x_{2}\right)$. (This implies that $d\left(x_{1}, x_{2}\right) \leq 2 C d\left(z^{\prime}, x_{2}\right)$.) We must show that $z^{\prime} \in A$. Now

$$
\begin{aligned}
& d\left(f^{n} z^{\prime}, f^{n} x_{2}\right) \leq d\left(f^{n} z^{\prime}, f^{n} x_{1}\right)+d\left(f^{n} x_{1}, f^{n} z\right)+d\left(f^{n} z, f^{n} x_{2}\right) \\
& \leq C_{2}^{2} \nu^{n}\left\{d\left(z^{\prime}, x_{1}\right)+d\left(x_{1}, z\right)+d\left(z, x_{2}\right)\right\} \\
& \leq C_{2}^{2} \nu^{n}\left\{d\left(z^{\prime}, x_{2}\right)+d\left(x_{2}, x_{1}\right)+d\left(x_{1}, x_{2}\right)+d\left(x_{2}, z^{\prime}\right)+d\left(z^{\prime}, z\right)+d\left(z, z^{\prime}\right)+d\left(z^{\prime}, x_{2}\right)\right\} \\
& =C_{2}^{2} \nu^{n}\left\{3 d\left(z^{\prime}, x_{2}\right)+2 d\left(x_{1}, x_{2}\right)+2 d\left(z, z^{\prime}\right)\right\} \leq C_{2}^{2} \nu^{n}\left\{3 d\left(z^{\prime}, x_{2}\right)+4 d\left(x_{1}, x_{2}\right)\right\} \\
& \leq(3+8 C) C_{2}^{2} \nu^{n} d\left(z^{\prime}, x_{2}\right) .
\end{aligned}
$$

We can arrange that $\chi$ takes values in $B_{\varepsilon}(x)$ where $\varepsilon$ is as small as required. By Lemma 4.7(b), $z^{\prime} \in W^{s}\left(x_{2}\right)$ and hence $z^{\prime} \in A$ completing the proof.

Corollary 4.10. There exists $\varepsilon>0$ such that $X_{t}\left(W_{x}^{s} \cap B_{\varepsilon}(x)\right) \subset W_{X_{t} x}^{s}$ for all $t \geq 0$, $x \in U_{0}$.

Proof. Choose $n_{0} \geq 1$ such that $C_{2}^{2} \nu^{n_{0}}<1$. Shrinking $\varepsilon$, it follows from Lemma 4.7(a,c) that $f^{n_{0}}\left(W_{x}^{s} \cap B_{\varepsilon}(x)\right) \subset W_{f^{n_{0}}}^{s} \cap B_{\varepsilon}\left(f^{n_{0}} x\right)$ and inductively that $f^{k n_{0}}\left(W_{x}^{s} \cap B_{\varepsilon}(x)\right) \subset W_{f^{k n_{0}}}^{s} \cap$ $B_{\varepsilon}\left(f^{k n_{0}} x\right)$ for all $k \geq 0$.

Next choose $C \geq 1$ such that $d\left(X_{r} x, X_{r} y\right) \leq C d(x, y)$ for all $x, y \in U_{0}, r \in\left[-n_{0} T, n_{0} T\right]$. Suppose that $y \in W_{x}^{s}$ and let $x^{\prime}=X_{r} x, y^{\prime}=X_{r} y$. By Lemma 4.7(a), for $y$ sufficiently close to $x$,

$$
d\left(f^{n} x^{\prime}, f^{n} y^{\prime}\right)=d\left(X_{r} f^{n} x, X_{r} f^{n} y\right) \leq C d\left(f^{n} x, f^{n} y\right) \leq C C_{2}^{2} \nu^{n} d(x, y) \leq C^{2} C_{2}^{2} \nu^{n} d\left(x^{\prime}, y^{\prime}\right)
$$

for all $n \geq 0$. By Lemma $4.7(\mathrm{~b}), X_{r} y \in W_{X_{r} x}^{s}$ for $y$ sufficiently close to $x$. Hence there exists $\varepsilon>0$ such that $X_{r}\left(W_{x}^{s} \cap B_{\varepsilon}(x)\right) \subset W_{X_{r} x}^{s}$ for all $r \in\left[0, n_{0} T\right], x \in U_{0}$.

The result for general $t$ follows by writing $t=k n_{0} T+r$ where $k \geq 0, r \in\left[0, n_{0} T\right)$.
Recall that $f=X_{T}$. Choose $C$ such that $\sup _{r \in[0, T]} d\left(X_{r} x, X_{r} y\right) \leq C d(x, y)$ for all $x, y \in U$. Write $t=n T+r, n \geq 0, r \in[0, T)$. By Lemma 4.7(a), if $d(x, y)<C_{2}^{-1} \rho$ and $y \in W_{x}^{s}$, then

$$
d\left(X_{t} x, X_{t} y\right)=d\left(X_{n T+r} x, X_{n T+r} y\right) \leq C_{2}^{2} C \nu^{n} d(x, y) \leq C^{\prime} \tilde{\nu}^{t} d(x, y)
$$

where $C^{\prime}=C_{2}^{2} C \nu^{-1}$ and $\tilde{\nu}=\nu^{1 / T}$.
Passing to an adapted metric, we can arrange that there are constants $\varepsilon>0, \nu \in(0,1)$ such that if $d(x, y)<\varepsilon$ and $y \in W_{x}^{s}$, then $d\left(X_{t} x, X_{t} y\right) \leq \nu^{t} d(x, y)$ for all $t \geq 0$. From now on, we write $W_{x}^{s}$ instead of $W_{x}^{s} \cap B_{\varepsilon}(x)$. With this notation, Corollary 4.10 states that $X_{t}\left(W_{x}^{s}\right) \subset W_{X_{t} x}^{s}$ for all $x \in U_{0}, t \geq 0$.

This completes the proof of Theorem 4.2.
4.2. Regularity of the stable foliation. In this subsection, we prove results on the regularity of the stable foliation $\left\{W_{x}^{s}\right\}$ in a neighborhood of $\Lambda$ under an appropriate bunching condition. We follow [10, Theorem 6.5], adapting and applying the results of [9] in our setting.

We continue to suppose that $X_{t}$ is the flow generated by a $C^{r}$ vector field $G$ where $r \geq 1$. Let $q \in[0, r]$. We suppose that there exists $t>0$ such that the following bunching condition holds:

$$
\begin{equation*}
\left\|D X_{t}\left|E_{x}^{s}\|\cdot\| D X_{-t}\right| E_{X_{t} x}^{c u}\right\| \cdot\left\|D X_{t} \mid E_{x}^{c u}\right\|^{q}<1 \quad \text { for all } x \in \Lambda . \tag{4.2}
\end{equation*}
$$

Let $T_{U_{0}} M=E^{s} \oplus E^{c u}$ be a continuous extension of the underlying splitting with $E^{s}$ invariant as in Proposition 3.2. Choose $t$ as in (4.2) and let $f=X_{t}$. Increasing $t$ and shrinking $U_{0}$ if necessary, we can ensure that

$$
\begin{equation*}
\left\|D f\left|E_{x}^{s}\|\cdot\| D f^{-1}\right| E_{f x}^{c u}\right\| \leq\left\|D f\left|E_{x}^{s}\|\cdot\| D f^{-1}\right| E_{f x}^{c u}\right\| \cdot\left\|D f \mid T_{x} M\right\|^{q}<1 \tag{4.3}
\end{equation*}
$$

for all $x \in U_{0}$.
Let $T_{U_{0}} M=F^{s} \oplus F^{c u}$ be a $C^{r}$ approximation of the splitting $T_{U_{0}} M=E^{s} \oplus E^{c u}$. For each $x \in U_{0}$, let $L\left(F_{x}^{s}, F_{x}^{c u}\right)$ denote the space of linear maps from $F_{x}^{s}$ to $F_{x}^{c u}$, and let $\mathbb{D}_{x}$ denote the unit disk in $L\left(F_{x}^{s}, F_{x}^{c u}\right)$. Define the corresponding disk bundle $\mathcal{D}_{0}=\left\{\mathbb{D}_{x}, x \in U_{0}\right\}$.

Let $U_{1}=f\left(U_{0}\right) \subset U_{0}$ and set $\mathcal{D}_{1}=\left\{\mathbb{D}_{x}, x \in U_{1}\right\}$. Let $h=\left.f^{-1}\right|_{U_{1}}: U_{1} \rightarrow U_{0}$. Since $h\left(U_{1}\right)=U_{0} \supset U_{1}$, the $C^{r}$ diffeomorphism $h$ is overflowing in the sense of [9, p. 30].

Represent $D h(x): T_{x} M \rightarrow T_{h x} M$ using the splitting $F^{s} \oplus F^{c u}$ by writing

$$
\operatorname{Dh}(x)=\left(\begin{array}{ll}
A_{x} & B_{x} \\
C_{x} & D_{x}
\end{array}\right): F_{x}^{s} \times F_{x}^{c u} \rightarrow F_{h x}^{s} \times F_{h x}^{c u}, \quad x \in U_{1} .
$$

We define the graph transform $\Gamma: \mathcal{D}_{1} \rightarrow \mathcal{D}_{0}$,

$$
\Gamma_{x}(\ell)=\left(C_{x}+D_{x} \ell\right)\left(A_{x}+B_{x} \ell\right)^{-1}, \quad \ell \in \mathbb{D}_{x}, x \in U_{1} .
$$

Lemma 4.11. The neighborhood $U_{0}$ of $\Lambda$ and the $C^{r}$ splitting $F^{s} \oplus F^{c u}$ can be chosen so that $\Gamma: \mathcal{D}_{1} \rightarrow \mathcal{D}_{0}$ is well-defined and $\operatorname{Lip}\left(\Gamma_{x}\right) \cdot\left\|D h^{-1} \mid T_{h x} M\right\|^{q}<1$ for all $x \in U_{1}$.

Proof. By (4.3), we can choose $\lambda_{x} \in(0,1)$ such that

$$
\left\|D f\left|E_{x}^{s}\|\cdot\| D f^{-1}\right| E_{f x}^{c u}\right\|<\lambda_{x} \quad \text { and } \quad \lambda_{x}\left\|D f \mid T_{x} M\right\|^{q}<1 \quad \text { for all } x \in U_{0} .
$$

Since $f$ is $C^{1}$ and $\overline{U_{0}}$ is compact, there exists $\delta \in(0,1)$ such that $\left(\lambda_{h x}+2 \delta\right)(1-\delta)^{-2}<1$ and

$$
\begin{equation*}
\left(\lambda_{h x}+2 \delta\right)(1-\delta)^{-2}\left\|D h^{-1} \mid T_{h x} M\right\|^{q}<1 \quad \text { for all } x \in U_{1} . \tag{4.4}
\end{equation*}
$$

Since $F^{s}$ is close to the $D f$-invariant contracting bundle $E^{s}$, we can arrange that $\left\|C_{x}\right\| \leq 1$ and $\left\|A_{x}^{-1}\right\| \leq 1$ for all $x \in U_{1}$. Also, $F^{c u}$ is close to $E^{c u}$ which is invariant when restricted to $\Lambda$ so we can arrange that $\left\|B_{x}\right\|<\delta$. Moreover, $A_{x}^{-1}$ is close to $D f \mid E_{h x}^{s}$ and $D_{x}$ is close to $D f^{-1} \mid E_{x}^{c u}$ so we can ensure that $\left\|A_{x}^{-1}\right\|\left\|D_{x}\right\| \leq \lambda_{h x}$ for all $x \in U_{1}$.

Let $\ell, \ell^{\prime} \in \mathbb{D}_{x}$. Note that $\left\|A_{x}^{-1} B_{x} \ell\right\| \leq \delta$, so $\left\|\left(I+A_{x}^{-1} B_{x} \ell\right)^{-1}\right\| \leq(1-\delta)^{-1}$. Similarly, $\left\|\left(I+A_{x}^{-1} B_{x} \ell^{\prime}\right)^{-1}\right\| \leq(1-\delta)^{-1}$. It follows that

$$
\begin{aligned}
&\left\|\left(A_{x}+B_{x} \ell\right)^{-1}-\left(A_{x}+B_{x} \ell^{\prime}\right)^{-1}\right\|=\left\|\left(A_{x}+B_{x} \ell\right)^{-1}\left(B_{x}\left(\ell^{\prime}-\ell\right)\right)\left(A_{x}+B_{x} \ell^{\prime}\right)^{-1}\right\| \\
& \leq\left\|A_{x}^{-1}\right\|^{2} \delta(1-\delta)^{-2}\left\|\ell^{\prime}-\ell\right\| \leq\left\|A_{x}^{-1}\right\| \delta(1-\delta)^{-2}\left\|\ell^{\prime}-\ell\right\|
\end{aligned}
$$

Hence

$$
\begin{aligned}
& \left\|\Gamma_{x}(\ell)-\Gamma_{x}\left(\ell^{\prime}\right)\right\| \leq\left\|D_{x}\left(\ell-\ell^{\prime}\right)\right\|\left\|\left(A_{x}+B_{x} \ell\right)^{-1}\right\| \\
& \quad+\left\|\left(C_{x}+D_{x} \ell^{\prime}\right)\right\|\left\|\left(A_{x}+B_{x} \ell\right)^{-1}-\left(A_{x}+B_{x} \ell^{\prime}\right)^{-1}\right\| \\
& \quad \leq\left\|A_{x}\right\|^{-1}\left\|D_{x}\right\|(1-\delta)^{-1}\left\|\ell-\ell^{\prime}\right\|+\left(1+\left\|D_{x}\right\|\right)\left\|A_{x}^{-1}\right\| \delta(1-\delta)^{-2}\left\|\ell-\ell^{\prime}\right\| \\
& \leq \lambda_{h x}(1-\delta)^{-1}\left\|\ell-\ell^{\prime}\right\|+2 \delta(1-\delta)^{-2}\left\|\ell-\ell^{\prime}\right\|,
\end{aligned}
$$

and so $\operatorname{Lip}\left(\Gamma_{x}\right) \leq\left(\lambda_{h x}+2 \delta\right)(1-\delta)^{-2}$ for all $x \in U_{1}$. In particular, $\operatorname{Lip}\left(\Gamma_{x}\right)<1$ so $\Gamma_{x}\left(\mathbb{D}_{x}\right) \subset \mathbb{D}_{h x}$, and hence $\Gamma$ is well-defined. The result follows from this estimate combined with (4.4).

Theorem 4.12. Let $q \in[0,[r]]$. If condition (4.2) holds for some $t>0$, then the bundle $E^{s}$ is $C^{q}$ over $U_{1}$. That is, the map $x \mapsto E_{x}^{s}$ is a $C^{q}$ map from $U_{1}$ to $\mathcal{D}_{1}$.

Proof. Recall that we can regard $E_{x}^{s}$ as the graph of an element $\omega \in L\left(F_{x}^{s}, F_{x}^{c u}\right)$ with $\|\omega\|$ as close to zero as desired. In particular, $\|\omega\| \leq 1$, and hence $E^{s}$ is identified with a continuous $D f$-invariant section of $\mathcal{D}_{1}$.

Note that $D h(x) \operatorname{graph}(\ell)=\operatorname{graph}\left(\Gamma_{x}(\ell)\right)$ for $\ell \in \mathbb{D}_{x}$. Since $h=d f^{-1}$, it follows that $E^{s}: U_{1} \rightarrow \mathcal{D}_{1}$ is a continuous $\Gamma$-invariant section.

By Lemma 4.11, the graph transform $\Gamma: \mathcal{D}_{1} \rightarrow \mathcal{D}_{0}$ defines a fiber contraction over the overflowing diffeomorphism $h: U_{1} \rightarrow U_{0}$, and this fiber contraction is $q$-sharp in the terminology of [9]. When $q$ is an integer, we have verified the hypotheses of the " $C^{r}$ section theorem" [9, Theorem 3.5] (with $q$ playing the role of $r$, and vector bundles replaced by
disk bundles as in [9, Remark, p. 36]). It follows from [9, Theorem 3.5] that $E^{s}: U_{1} \rightarrow \mathcal{D}_{1}$ is the unique continuous $\Gamma$-invariant section and moreover that this section is $C^{q}$.

This completes the proof in the case that $q$ is an integer. The general case follows from [9, Remark 2, p. 38].

Remark 4.13. (a) It is immediate from domination (2.2) that condition (4.2) holds with $q=0$. By smoothness of the flow and compactness of $\Lambda$, condition (4.2) holds for some $q>0$ and hence the stable bundle $E^{s}$ is at least Hölder over $U_{1}$.
(b) When $q \geq 1$ in Theorem 4.12, it follows by Frobenius's Theorem (see for example [1, pp. 93-95]) that the family of stable manifolds $\left\{W_{x}^{s}\right\}$ obtained in Theorem 4.2 forms a $C^{q}$ foliation of $U_{1}$ in the sense that the foliation charts are $C^{q}$. Moreover the holonomy maps along the stable leaves are $C^{q}$ smooth. (See [15, Section 6] for more details.) For $q \in(0,1)$, it remains true that the holonomy maps are $C^{q}$ [15].

## 5. Strong dissipativity

From now on, our results are specialised to flows. In this section, we define strong dissipativity for sectional hyperbolic attractors. This is a verifiable condition for smoothness of stable foliations, extending [3] who proved strong dissipativity and hence smoothness of the stable foliation for the classical Lorenz attractor. We recover the result of [3] and moreover obtain an estimate for the smoothness.

Recall that $d_{s}=\operatorname{dim} E_{x}^{s}$. Given $A=\left\{a_{i j}\right\} \in \mathbb{R}^{d \times d}$, let $\|A\|_{2}=\left(\sum_{i j} a_{i j}^{2}\right)^{1 / 2}$.
Definition 5.1. Let $q>1 / d_{s}$. A partially hyperbolic attractor $\Lambda$ is $q$-strongly dissipative if
(a) For every equilibrium $\sigma \in \Lambda$ (if any), the eigenvalues $\lambda_{j}$ of $D G(\sigma)$, ordered so that $\Re \lambda_{1} \leq \Re \lambda_{2} \leq \cdots \leq \Re \lambda_{d}$, satisfy $\Re\left(\lambda_{1}-\lambda_{d_{s}+1}+q \lambda_{d}\right)<0$.
(b) $\sup _{x \in \Lambda}\left\{\operatorname{div} G(x)+\left(d_{s} q-1\right)\|(D G)(x)\|_{2}\right\}<0$.

Theorem 5.2. Let $\Lambda$ be a sectional hyperbolic attractor. Suppose that $\Lambda$ is $q$-strongly dissipative for some $q \in\left(1 / d_{s},[r]\right]$. Then there exists a neighborhood $U_{0}$ of $\Lambda$ such that the stable manifolds $\left\{W_{x}^{s}, x \in U_{0}\right\}$ define a $C^{q}$ foliation of $U_{0}$.

Proof. For each $t \in \mathbb{R}$, we define $\eta_{t}: \Lambda \rightarrow \mathbb{R}$,

$$
\eta_{t}(x)=\log \left\{\left\|D X_{t}\left|E_{x}^{s}\|\cdot\| D X_{-t}\right| E_{X_{t} x}^{c u}\right\| \cdot\left\|D X_{t} \mid E_{x}^{c u}\right\|^{q}\right\} .
$$

Note that $\left\{\eta_{t}, t \in \mathbb{R}\right\}$ is a continuous family of continuous functions each of which is subadditive, that is, $\eta_{s+t}(x) \leq \eta_{s}(x)+\eta_{t}\left(X_{s} x\right)$.

Let $\mathcal{M}$ denote the set of flow-invariant ergodic probability measures on $\Lambda$. We claim that for each $m \in \mathcal{M}$, the limit $\lim _{t \rightarrow \infty} t^{-1} \eta_{t}(x)$ exists and is negative for $m$-almost every $x \in \Lambda$. It then follows from [5, Proposition 3.4] that there exists constants $C, \beta>0$ such that $\exp \eta_{t}(x) \leq C e^{-\beta t}$ for all $t>0, x \in \Lambda$. In particular, for $t$ sufficiently large, $\exp \eta_{t}(x)<1$ for all $x \in \Lambda$. Hence condition (4.2) is satisfied for such $t$ and the result follows from Theorem 4.12 and Remark 4.13.

It remains to verify the claim. For each $m \in \mathcal{M}$, we label the Lyapunov exponents

$$
\chi_{1}(m) \leq \chi_{2}(m) \leq \cdots \leq \chi_{d}(m) .
$$

Since $\Lambda$ is partially hyperbolic, the Lyapunov exponents $\chi_{j}(m), j=1, \ldots, d_{s}$ are associated with $E^{s}$ and are negative, while the remaining exponents are associated with $E^{c u}$.

For $m$-a.e. $x \in \Lambda$ we have

$$
\begin{aligned}
& \lim _{t \rightarrow \infty} t^{-1} \log \left\|D X_{t}\left|E_{x}^{s}\left\|=\chi_{1}(m), \quad \lim _{t \rightarrow \infty} t^{-1} \log \right\| D X_{-t}\right| E_{X_{t} x}^{c u}\right\|=-\chi_{d_{s}+1}(m) \\
& \lim _{t \rightarrow \infty} t^{-1} \log \left\|D X_{t}\left|E_{x}^{c u}\left\|=\lim _{t \rightarrow \infty} t^{-1} \log \right\| D X_{t}\right| T_{x} M\right\|=\chi_{d}(m)
\end{aligned}
$$

Hence, $m$-almost everywhere,

$$
\lim _{t \rightarrow \infty} t^{-1} \eta_{t}(x)=\chi_{1}(m)-\chi_{d_{s}+1}(m)+q \chi_{d}(m)
$$

If $m$ is a Dirac delta at an equilibrium $\sigma \in \Lambda$, then $\chi_{j}(m)=\Re \lambda_{j}$ for $j=1, \ldots, d$, where $\lambda_{j}$ are the eigenvalues of $D G(\sigma)$. Hence, it is immediate from Definition 5.1(a) that $\lim _{t \rightarrow \infty} t^{-1} \eta_{t}(\sigma)<0$.

If $m$ is not supported on an equilibrium, then there is a zero Lyapunov exponent in the flow direction. Sectional expansion ensures that $\chi_{d_{s}+1}(m)=0$ and $\chi_{j}(m)>0$ for $j=d_{s}+2, \ldots, d$. Hence, $m$-almost everywhere,

$$
\begin{aligned}
\lim _{t \rightarrow \infty} t^{-1} \eta_{t}(x) & =\chi_{1}(m)+q \chi_{d}(m) \leq d_{s}^{-1} \sum_{j=1}^{d_{s}} \chi_{j}(m)+q \chi_{d}(m) \\
& =d_{s}^{-1}\left(\sum_{j=1}^{d_{s}} \chi_{j}(m)+d_{s} q \chi_{d}(m)\right) \leq d_{s}^{-1}\left(\sum_{j=1}^{d} \chi_{j}(m)+\left(d_{s} q-1\right) \chi_{d}(m)\right) \\
& =d_{s}^{-1} \lim _{t \rightarrow \infty} t^{-1}\left(\log \left|\operatorname{det} D X_{t}(x)\right|+\left(d_{s} q-1\right) \log \left\|D X_{t}(x)\right\|\right) \\
& \leq d_{s}^{-1} \lim _{t \rightarrow \infty} t^{-1} \int_{0}^{t}\left(\operatorname{div} D G\left(X_{s} x\right)+\left(d_{s} q-1\right)\left\|D G\left(X_{s} x\right)\right\|_{2}\right) d s \\
& \leq d_{s}^{-1} \sup _{x \in \Lambda}\left\{\operatorname{div} D G(x)+\left(d_{s} q-1\right)\|D G(x)\|_{2}\right\} .
\end{aligned}
$$

By Definition 5.1(b), we again have that $\lim _{t \rightarrow \infty} t^{-1} \eta_{t}(x)<0$ for $m$-almost every $x \in \Lambda$. This completes the proof of the claim.
Remark 5.3. If $\sup _{\Lambda} \operatorname{div} G<0$, then condition (b) holds for $q=d_{s}^{-1}+\varepsilon$ for $\varepsilon$ sufficiently small. When $\operatorname{dim} M=3$, we have $d_{s}=1$ and hence we recover the result in [3, Lemma 2.2]. For the classical Lorenz equations [13], we have

$$
\operatorname{div} G \equiv-\frac{41}{3}, \quad \lambda_{1} \approx-22.83, \quad \lambda_{2}=-\frac{8}{3}, \quad \lambda_{3} \approx 11.83
$$

so the Lorenz attractor is $(1+\varepsilon)$-strongly dissipative for $\varepsilon>0$ sufficiently small. Hence, the stable foliation is $C^{1+\varepsilon}$ for the classical Lorenz attractor.

In fact, we have:
Corollary 5.4. The stable foliation for the classical Lorenz attractor is at least $C^{1.278}$.
Proof. By definition, $q$-strong dissipativity holds for any $q<\min \left\{q_{1}, q_{2}\right\}$ where

$$
q_{1}=\frac{\lambda_{2}-\lambda_{1}}{\lambda_{3}} \approx 1.704, \quad q_{2}=1-\frac{\operatorname{div} G}{\sup \|D G\|_{2}}=1+\frac{41}{3} \frac{1}{\sup \|D G\|_{2}} .
$$

Now

$$
\|D G(x)\|_{2}^{2}=201+\frac{64}{9}+2 x_{1}^{2}+x_{2}^{2}+\left(x_{3}-28\right)^{2} \leq 208.12+V,
$$

where

$$
V=2 x_{1}^{2}+x_{2}^{2}+\left(x_{3}-28\right)^{2} .
$$

We claim that $V \leq 2197$. Then $q \geq 1.278$ as required.
In verifying the claim, we use the standard notation $\sigma=10, b=\frac{8}{3}, r=28$ for the parameters in the Lorenz equations. Various authors $[6,7,18]$ have established the estimate

$$
\begin{equation*}
x_{2}^{2}+\left(x_{3}-r\right)^{2} \leq R^{2}, \quad R^{2}=\frac{b^{2} r^{2}}{4(b-1)}=\frac{12544}{15} \leq 836.27 . \tag{5.1}
\end{equation*}
$$

It follows that

$$
\begin{equation*}
x_{2}^{2}+x_{3}^{2} \leq(r+R)^{2} \leq 3239.7 . \tag{5.2}
\end{equation*}
$$

Next, by [18, Example 5] (see also [7]), $a x_{1}^{2} \leq\left(x_{2}^{2}+x_{3}^{2}\right)$ where $a>0$ is the largest root of

$$
(10 a-28)^{2}+a(20-\lambda)(2-\lambda), \quad \lambda=11 .
$$

This yields $a \geq 4.7644$, so using (5.2), $x_{1}^{2} \leq a^{-1}\left(x_{2}^{2}+x_{3}^{2}\right) \leq 680$. Combined with (5.1),

$$
V=2 x_{1}^{2}+x_{2}^{2}+\left(x_{3}-28\right)^{2} \leq 1360+837=2197,
$$

proving the claim.
Remark 5.5. It might seem that we could use [6, equation (22)] to get a better estimate on $x_{3}$ and hence $V$. Unfortunately this equation implies

$$
\left(x_{3}-\frac{1}{2}(r+\sigma)\right)^{2} \leq \frac{1}{4}(r+\sigma)^{2},
$$

so $x_{3} \leq r+\sigma=38$ which is clearly incorrect.

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