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# Dose-response-time modelling: Second-generation turnover model with integral feedback control

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#### Abstract

This study presents a dose-response-time (DRT) analysis based on a large preclinical biomarker dataset on the interaction between nicotinic acid (NiAc) and free fatty acids (FFA). Data were collected from studies that examined different rates, routes, and modes of NiAc provocations on the FFA time course. All information regarding the exposure to NiAc was excluded in order to demonstrate the utility of a DRT model. Special emphasis was placed on the selection process of the biophase model. An inhibitory  $I_{\text{max}}$ -model, driven by the biophase amount, acted on the turnover rate of FFA. A second generation NiAc/FFA model, which encompasses integral (slow buildup of tolerance - an extension of the previously used NiAc/FFA turnover models) and moderator (rapid and oscillatory) feedback control, was simultaneously fitted to all time courses in normal rats. The integral feedback control managed to capture an observed 90% adaptation (i.e., almost a full return to baseline) when 10 days constantrate infusion protocols of NiAc were used. The half-life of the adaptation process had a 90% prediction interval between 3.5-12 h in the present population. The pharmacodynamic parameter estimates were highly consistent when compared to an exposure-driven analysis, partly validating the DRT modelling approach and suggesting the potential of DRT analysis in areas where exposure data are not attainable. Finally, new numerical algorithms, which rely on sensitivity equations to robustly and efficiently compute the gradients in the parameter optimization, were successfully used for the mixed-effects approach in the parameter estimation.

Keywords: Biophase models, Turnover, Tolerance, Feedback control, Nicotinic acid (NiAc), Free fatty acids (FFA)

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#### 1. Introduction

The traditional pharmacokinetic-pharmacodynamic (PK-PD) modelling approach is generally based on known plasma kinetics when the PD properties are assessed. Dose-response-time (DRT) data analysis is an alternative to exposure-driven kinetic - dynamic modelling when exposure data are sparse or lacking. This involves studies where the pharmacological response precedes the systemic exposure (e.g. pulmonary drug administration) or when the drug is locally administered (e.g. in ophthalmics). In DRT analyses the pharmacological effect is assumed to contain some kinetic properties whereby a biophase function can be developed and in turn acts as a 'driving' function of the pharmacological effect. The biophase function is assessed using various structures from a biophase model library when the DRT model is fitted to data. This biophase library consists of feasible models derived from the kinetic information in the response-time course in combination with knowledge of the physiology.

DRT data analysis dates back to the 1960's and 1970's when Smolen [53, 54, 55] and Levy [39] introduced the concept. Smolen used response data to quantify the bioavailability and biokinetic behaviour of a mydriatic drug after oral and ophthalmic administration whilst Levy derived a relation between the pharmacological effect and elimination rate of a mydriatic drug. Since the work of Smolen, DRT data analysis has been proven to be applicable to novel systems where the kinetics and/or dynamics behave non-linearly, when there are time-delays in the response data, and when the system contains feedback mechanisms [24]. The technique has successfully been applied in models of the muscle relaxant drug vecuronium [14, 22, 21, 64], antinociceptive drugs [1, 26, 24], ophthalmic drugs [24, 41], antidepressants [28], psycho-motor stimulants [26], drugs to treat chronic obstructive pulmonary disease (COPD) [65], and osteoporosis [46]. For a review and theoretical guide to DRT analysis see Gabrielsson et al. [24, 26]. DRT models go under the name of K-PD (K for kinetic) models in some analyses [28, 29, 35, 46, 65]. However, in the latter case the biophase turnover rate, rather than the biophase amount, is driving the response.

NiAc has long been used as a therapeutic agent to treat dyslipidemia. The drug effectively suppresses the level of triglycerides and low-density lipoprotein cholesterols in plasma whilst elevating the level of high-density lipoprotein cholesterol [16]. NiAc inhibits hydrolysis in adipose tissue by activating the G-coupled receptor GPR109A, which in turn inhibits the adenylyl cyclase, leading to reduced levels of cyclic adenosine monophosphate (cAMP). The cAMP activates the enzyme protein kinase A which phosphorylates hormone-sensitive lipase that in turn hydrolyses triglycerides into FFA (Fig. 1) [44].

We sought to further demonstrate the utility of DRT data analysis. To do so, we analysed a rich preclinical data set containing several individuals (a total of 95 rats and response-time courses) and provocations (constant rate infusions at three dosage levels, step-wise increasing infusion at two dosage levels, and oral administration at three dosage levels) of the NiAc - FFA interaction. Available exposure data for NiAc were intentionally excluded in order to use a DRT approach. The developed DRT model was compared and validated by means of

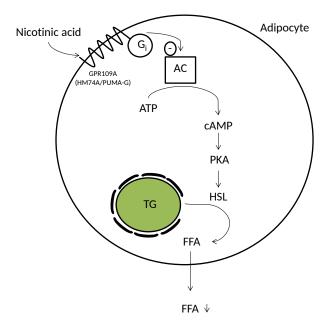


Figure 1: Mechanism of NiAc-induced inhibition of lipolysis. NiAc activates the G-coupled receptor GPR109A, which in turn inhibits the adenylyl cyclase, reducing the production of cyclic adenosine monophosphate (cAMP) from adenosine triphosphate. cAMP activates protein kinase A, which phosphorylates hormone-sensitive lipase, thereby regulating the hydrolysis of triglycerides into FFA. Thus, NiAc binding will inhibit lipolysis leading to reduced levels of FFA. Adapted from Offermanns 2006 [44].

exposure-driven kinetic/dynamic results, where the pharmacokinetic properties of NiAc had been thoroughly characterized [3].

The applied pharmacodynamic model is an extended and significantly improved version of a previously utilised feedback model [2, 4, 6, 25, 59]. This second-generation feedback model uses an integral feedback control mechanism to capture the slowly developing tolerance. This model is affected by a biophase model that drives the inhibitory drug-mechanism function. The biophase model was selected using an iterative modelling approach where the biophase model was systemically refined in order to better capture the dynamic behaviour seen in the data. This study presents an approach to the development of the biophase model structure simultaneously with the pharmacodynamic model. In light of the aforementioned, DRT analyses do not fully replace exposure-driven analyses, particularly in safety assessment.

#### 2. Materials and methods

#### 60 2.1. Background and data sources

The pre-clinical data set consisted of FFA response-time series of 95 male Sprague-Dawley rats under NiAc provocation. These data have previously been described by Ahlström et al. [3, 5, 7, 4, 6, 33] and Tapani et al. [59]. A thorough description of the animals and surgical procedure, experimental design, and analytical assay can be found in Ahlström et al. [4].

All experiments were designed and conducted at AstraZeneca, Mölndal Sweden, and approved by the Ethics Committee for Animal Experiments, Gothenburg, Sweden (EA 100868).

# 2.2. Selection process of biophase models

The DRT data analysis is based on the assumption that the pharmacological response contains some kind of kinetic information and is driven by NiAc in a hypothetical biophase compartment. The fit of the pharmacodynamic model (given in Sec. 2.4) to the data informs about the soundness of choice of the driving biophase function. Depending on the route of administration, the input is either approximated to be directly into the biophase (intravenous dosing) or absorbed into the biophase (oral dosing). The biophase model structures were modified through a series of steps where data from different routes and rates of administration were sequentially assessed (see Table 1). In a pairwise accept-reject procedure, two models were qualitatively and quantitatively compared and the one considered to be the better model, in terms of goodness-of-fit, was selected and further challenged by more complex data (see Table 1). The goodness-of-fit was based on the likelihood function value and by graphical inspection of the function plots.

Step I. The first biophase model that was evaluated consisted of a zero-order input into and first-order elimination from the biophase (Fig. 2b). To capture the disposition characteristics, the model was evaluated using response-time data derived from different constant-rate intravenous infusion experiments.

Step II. The next biophase model to be evaluated consisted of zero-order input and Michaelis-Menten elimination from the biophase (Fig 2c). This model was evaluated using the same data as in step I.

The model that best described (in terms of goodness-of-fit) the dynamics, using the response-time data derived from different constant-rate intravenous infusion experiments, was kept for the later stages of the biophase evolution. In this case, the models used in step I and II had close to similar objective function values and were indistinguishable by graphical inspection of the function fits. However, in accordance with the principle of Occam's razor, and by applying the Akaike Information Criterion [8], the zero-order input and first-order elimination model was chosen.

Step III. When a model for the biophase elimination model was set, responsetime data derived from experiments for different oral dosages were included in order to address the biophase absorption. The first biophase absorption model that was evaluated consisted of first-order input and elimination from the biophase (Fig. 2d).

Step IV. The final absorption model that was evaluated consisted of Michaelis-Menten input and first-order elimination (Fig 2e). This model was evaluated using the same data as in step III.

The model in step IV had a higher likelihood function value and a substantially better fit when inspecting the function plots than the model in step III, and was therefore selected.

## 2.3. The final biophase model

The biophase was modelled as

$$\frac{\mathrm{d}A_{\mathrm{b}}}{\mathrm{d}t} = Inf - k \cdot A_{\mathrm{b}},\tag{1}$$

for intravenous administration of NiAc, with initial condition

$$A_{\mathbf{b}}(0) = 0 \tag{2}$$

where  $A_{\rm b}$  denotes the biophase drug amount, k the biophase elimination rate constant, and Inf the infusion rate to the biophase. The infusion rate was modelled as a step function with either constant rate during the infusion period, or stepwise decreasing infusion rates, to mimic the infusion regimens used in the experiments.

Orally administered NiAc was assumed to be eliminated from the gut according to a Michaelis-Menten type of saturable process

$$\frac{\mathrm{d}A_{\mathrm{g}}}{\mathrm{d}t} = -\frac{V_{\mathrm{max,g}} \cdot A_{\mathrm{g}}}{K_{\mathrm{m,g}} + A_{\mathrm{g}}} \tag{3}$$

with initial condition

$$A_{\mathbf{g}}(0) = D \tag{4}$$

where  $A_{\rm g}$  denotes the amount of drug in the gut,  $V_{\rm max,g}$  the maximal elimination rate from the gut,  $K_{\rm m,g}$  the Michaelis-Menten constant (representing the amount in the gut at half maximal rate), and D the oral drug dose. The drug amount that is eliminated from the gastro-intestinal tract is absorbed into the biophase, giving the biophase equation

$$\frac{\mathrm{d}A_{\mathrm{b}}}{\mathrm{d}t} = \frac{V_{\mathrm{max,g}} \cdot A_{\mathrm{g}}}{K_{\mathrm{m,g}} + A_{\mathrm{g}}} - k \cdot A_{\mathrm{b}}$$
 (5)

with initial condition

$$A_{\mathbf{b}}(0) = 0 \tag{6}$$

where  $A_{\rm b}$  denotes the biohase drug amount and k the biophase elimination rate constant.

## 2.4. Structure of the FFA feedback model

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The fundamental dynamics of FFA are described in terms of a turnover equation

$$\frac{\mathrm{d}R}{\mathrm{d}t} = \widetilde{k}_{\mathrm{in}} - \widetilde{k}_{\mathrm{out}} \cdot R \tag{7}$$

where R denotes the FFA level, and  $\widetilde{k}_{\rm in}$  and  $\widetilde{k}_{\rm out}$  are functions describing the lumped effects of NiAc, and insulin and other hormones, on the turnover and fractional turnover of FFA, respectively. The NiAc-induced action on FFA is described by means of an inhibitory drug mechanism function given by

$$I(A_{\rm b}) = 1 - \frac{I_{\rm max} \cdot A_{\rm b}^{\gamma}}{ID_{50}^{\gamma} + A_{\rm b}^{\gamma}} \tag{8}$$

where  $A_{\rm b}$  denotes the biophase drug amount,  $I_{\rm max}$  the efficacy,  $ID_{50}$  the potency, and  $\gamma$  the Hill exponent.

The FFA level in the model is affected by a chain of moderator compartments  $M_1, \ldots, M_8$ . These moderator compartments represent a conglomerate of insulin, and other hormonal, regulators of the FFA disposition. Insulin, for example, acts as a dual regulator on the FFA level via rapid inhibition of the lipolysis and slow re-esterification of FFA to triglycerides [23, 50, 58]. This is captured by the dynamics of the first  $M_1$  and the last  $M_8$  moderator compartment, respectively. The moderators are described by the following set of equations

$$\frac{dM_1}{dt} = k_{\text{tol}} \cdot (R - M_1)$$

$$\frac{dM_2}{dt} = k_{\text{tol}} \cdot (M_1 - M_2)$$

$$\vdots$$

$$\frac{dM_8}{dt} = k_{\text{tol}} \cdot (M_7 - M_8)$$
(9)

where R denotes the FFA level and  $k_{\rm tol}$  the fractional turnover rate of the moderators. Consequently, all moderator compartments have the same transit time of  $1/k_{\rm tol}$ . The moderators are initially assumed to be in equilibrium with the response, thus

$$M_1(0) = \dots = M_8(0) = R_0$$
 (10)

where  $R_0$  is the FFA baseline level. The number of moderator compartments selected was previously discussed by Ahlström et al. [7].

Long-term exposure to NiAc has proven to induce insulin resistance in adipocytes [20, 47]. This is believed to be a consequence of down-regulated gene expressions

of the insulin and  $\beta$ -adrenergic pathways in adipose tissue [32]. Insulin resistance ultimately leads to full systemic adaptation with a FFA level that returns to its baseline within a few days [37, 45]. This slow and complete adaptation is captured by an integral feedback controller, with output u(t), that slowly forces deviating FFA levels back towards their baseline  $R_0$  despite persistent perturbations such as constant rate infusion of NiAc. The integral controller is given by

$$u(t) = K_{\rm i} \int_{0}^{t} \left( 1 - \frac{R(\tau)}{R_0} \right) d\tau \tag{11}$$

where  $K_i$  denotes the integral gain parameter (here-after referred to as the adaptation rate). The integral controller may also be expressed as a rate equation

$$\frac{\mathrm{d}u}{\mathrm{d}t} = K_{\mathrm{i}} \cdot \left(1 - \frac{R(t)}{R_0}\right) \tag{12}$$

with initial condition

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$$u(0) = 0. (13)$$

The expanded turnover equation of FFA under NiAc provocation is given by

$$\frac{\mathrm{d}R}{\mathrm{d}t} = k_{\mathrm{in}} \cdot (1 + u(t)) \cdot \frac{1}{\left(\frac{M_1}{R_0}\right)^p} \cdot I(A_{\mathrm{b}})$$

$$- k_{\mathrm{out}} \cdot \left(\frac{M_8}{R_0}\right) \cdot R \tag{14}$$

with initial condition

$$R(0) = R_0 \tag{15}$$

where R denotes the FFA level,  $k_{\rm in}$  the basal turnover rate,  $k_{\rm out}$  the basal fractional turnover rate,  $R_0$  the baseline of response, u(t) the integral controller, p the amplification factor, and  $M_1$  and  $M_8$  the first and last moderator, respectively. The moderators are normalized in the turnover Eq. 14 with the baseline FFA value  $R_0$ . The levels of the moderators follow the level of the FFA according to Eq. 9. In turn, the first moderator  $M_1$  modifies the turnover rate  $k_{\rm in}$ , amplified with the exponent p, whilst the last moderator  $M_8$  modifies the fractional turnover rate  $k_{\text{out}}$ . These feedback mechanisms represent the fast inhibition of lipolysis and the slower re-esterification of FFA to triglycerides, triggered by insulin and other hormones, that strive to dampen fluctuations in the FFA level. Furthermore, when the FFA level drops below the baseline level, the integral controller, given by Eq. 11, will accumulate and provide a positive contribution to the turnover rate  $k_{\rm in}$  of FFA. Similarly, when the FFA level increases and rises above the baseline level, the integral controller will accumulate and provide a negative contribution to the turnover rate. The full pharmacodynamic model structure is depicted in Fig 3.

#### 2.5. Initial parameter estimates

At time zero, before administration of NiAc, the system is in steady-state, with the moderators set at  $R_0$ . Consequently, the turnover equation (Eq. 14) pre-NiAc administration is given by

$$\frac{\mathrm{d}R}{\mathrm{d}t} = k_{\mathrm{in}} - k_{\mathrm{out}} \cdot R_0 = 0. \tag{16}$$

A simple rearrangement gives the relation

$$R_0 = \frac{k_{\rm in}}{k_{\rm out}} \tag{17}$$

and hence the system may be simplified with one of the parameters  $R_0$ ,  $k_{\rm in}$ , or  $k_{\rm out}$  removed in the parameter estimation. In this study,  $k_{\rm in}$  was estimated as a secondary parameter from the product of  $R_0$  and  $k_{\rm out}$ . The initial estimate of the FFA baseline level  $R_0$  was taken as the mean response at time zero.

Since the minimum FFA level is close to zero, initially for high NiAc dosages, we conclude that NiAc has a high efficacy and that  $I_{\rm max}$  is close to 1. Furthermore, for high NiAc infusion rates, the inhibitory drug-mechanism function becomes saturated whilst the moderators are initially in steady-state with the response. Using this, and the initiate estimate of  $I_{\rm max}$  Eq. 14 can be approximated as

$$\frac{\mathrm{d}R}{\mathrm{d}t} \approx -k_{\mathrm{out}} \cdot R \tag{18}$$

or

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$$R(t) \cong R_0 e^{-k_{\text{out}}t}. (19)$$

By means of this relation,  $k_{\rm out}$  can be estimated from the initial down-swing of the response on a semi-logarithmic scale.

The Hill exponent  $\gamma$  and the amplification factor p were initially set to 1 since little was known about the respective parameter values. The remaining parameters were estimated from simulations of the system.

# 2.6. Modelling random effects and residual variability

The extent of the data set allowed for mixed-effects to be included in the model, i.e., specific parameter values were allowed to vary within the population. To identify which parameters had a significant spread in the population, individual parameter fitting was applied. The five parameters with highest variability, in terms of coefficient of variation, were then selected as individual parameters; the rest were considered as population parameters. The parameters chosen to vary in the population were k,  $K_{\rm i}$ ,  $R_{\rm 0}$ ,  $k_{\rm out}$ , and  $k_{\rm tol}$ . These parameters were assumed to be uncorrelated (to simplify the model) and log-normally distributed (to keep the parameters positive).

The individual parameter estimates are referred to as Empirical Bayes Estimates (EBE's) and their individual fits and the model assumptions were quantified by their corresponding  $\eta$ -shrinkage [51, 13].

#### 2.7. Parameter estimation

The parameter estimation of the DRT model in this study was performed using a mixed-effects modelling framework implemented in Mathematica, developed at the Fraunhofer-Chalmers Research Centre for Industrial Mathematics (Gothenburg, Sweden) [9]. This framework is designed to estimate parameters in non-linear mixed effects models where the underlying dynamical system is either described by a set of ordinary or stochastic differential equations. The framework relies on the first-order conditional estimation (FOCE) [38], with or without interactions, to estimate the individual likelihoods of the population likelihood function. The argument that maximises the population likelihood function is found using the Broyden–Fletcher–Goldfarb–Shanno algorithm [43] where the gradient of the objective function is calculated using the so-called sensitivity equations.

#### 3. Results

Observed response-time series with corresponding population model fits and 90% Monte Carlo prediction intervals [49] are illustrated in Fig. 4. The FFA concentrations were suppressed in all animals receiving NiAc. A clear adaptation towards the FFA baseline was only seen for the individuals that received a 300 min constant rate infusion of NiAc (Fig. 4d-4f). This functional adaptation was more pronounced the higher the infusion rate. All infusion regimens gave rise to a rebound effect, i.e., the FFA level overshoots the initial baseline, after the infusions were stopped. The rebound effect was more pronounced the higher the infusion rate. This effect was followed by apparent oscillations in the FFA level around the baseline, which were more pronounced with the extended NiAc infusion regimens (longer duration of the infusions and higher NiAc doses). The rats that received an oral dose of NiAc experienced an FFA drop followed by an approximately constant FFA level (Fig. 4i-4k). The higher the dose, the longer the rats stayed at a suppressed and approximately constant FFA level. This was followed by rebound and oscillations. The suppression of FFA, the occurrence of rebound, and the extent of the oscillations were more pronounced the higher the oral dose.

The estimated population biophase amount-time courses are illustrated in Fig. 5. For the constant rate NiAc infusions, the biophase amount quickly reached steady-state (Fig. 5a-5f). The wash-out kinetics were rapid with a half-life of around 2 min. For the highest oral doses, the biophase amount declined in a non-linear fashion post-peak due to absorption-rate limited elimination of NiAc (Fig. 5k).

Observed individual FFA response-time series with individually fitted FFA response levels are illustrated in Fig. 6 for one individual per administration route and rate. The model captured the individual behaviour for all individuals. Specifically, the slow adaptation, in the individuals that received a 300-min infusion of NiAc, was captured by the integral feedback control present in the pharmacodynamic model (Fig. 6d-6f).

The fitted population parameters and inter-individual variations with corresponding relative standard errors for the full system are illustrated in Table 2. The biophase elimination rate constant k and the fractional turnover rate of FFA  $k_{\rm out}$  are of the same order of magnitude, indicating little to no time-delay between biophase kinetics and FFA dynamics. Since the absorption into the biophase is non-linear, we observed typical absorption-rate limited elimination at higher oral doses of NiAc. The estimated  $K_{\rm m,g}$  of about 40 µmol kg<sup>-1</sup> implies that the two higher oral doses (81.2 and 812 µmol kg<sup>-1</sup>) approach and exceed saturation.

The efficacy parameter  $I_{\rm max}$  was estimated as 0.893 < 1; therefore, NiAc cannot completely suppress FFA levels. The estimated biophase potency  $ID_{50}$  shows that the drug-mechanism function (Eq. 8) will be saturated at the highest infusions and for all the oral doses (Fig. 5). The estimated Hill exponent  $\gamma$  indicates a steep NiAc biophase amount - FFA response relationship at equilibrium. The rate constants  $k_{\rm out}$ ,  $k_{\rm tol}$ , and  $K_{\rm i}$  all have different orders of magnitude, and thus act over different time-scales. Half-lives for the three rate constants with 90% non-parametric bootstrap prediction intervals [18] are given in Table 3.

The pivotal systems  $(k_{\text{out}}, k_{\text{tol}}, K_{\text{i}}, p)$  and drug parameters  $(I_{\text{max}}, \gamma)$  were compared to estimates from an exposure-driven analysis, using the same dynamic model. The estimates are given in Table 4.

#### 3.1. Model predictions

By using the predicted population parameters, we explored the long-term effects of NiAc provocation on FFA level for the infusion rate of  $0.17 \,\mu\mathrm{mol\,kg^{-1}\,min^{-1}}$  (Fig. 7), aiming at a therapeutic plasma concentration of NiAc of  $1 \,\mu\mathrm{mol}$  [4]. The model predicted 90% adaptation within approximately 10 days of constant NiAc exposure. The effect of the fast moderator  $(M_1)$  feedback can be seen immediately after the initial drop, where the system rapidly returns towards the baseline. The effect of the slower moderator feedback  $(M_8)$  is seen as a slower terminal return with oscillations in the FFA level. The effect of the integral feedback controller is seen as the slow return to baseline over time.

#### 90 3.2. Structural identifiability

The model structure was proven to be structurally locally identifiable. Identifiability was tested using the Exact Arithmetic Rank (EAR) approach [11, 36, 48]. This approach requires that the functions in the system of differential equations are rational polynomial expressions in the variables and parameters. In this study, the inhibitory drug-mechanism function and the feedback function of the first moderator compartment did not fulfil this requirement since the state variables were raised to the powers of  $\gamma$  and p, respectively (which are real-valued). However, this problem is solved by re-writing the system in rational form by the introduction of auxiliary variables [40]. For example, let

$$B(t) = A_{\rm b}^{\gamma}(t) \tag{20}$$

$$B(0) = B_0 (= A_{\rm b}^{\gamma}(0)). \tag{21}$$

Then we have that

$$\frac{\mathrm{d}B}{\mathrm{d}t} = \gamma \frac{B(t)}{A_{\mathrm{b}}(t)} \cdot \frac{dA_{\mathrm{b}}}{dt},\tag{22}$$

and by introducing the parameter  $\widetilde{ID}_{50}(=ID_{50}^{\gamma})$  the non-rational functions in the inhibitory drug-mechanism function can be written as

$$1 - \frac{I_{\text{max}} \cdot B(t)}{\widetilde{ID}_{50} + B(t)} \tag{23}$$

which is a rational expression of the parameters and the variables.

## 3.3. Shrinkage analysis

Shrinkage analysis was used in order to quantify the individual parameter assumptions (log-normality) and to quantify the model fits [51]. The  $\eta$ -shrinkage of the EBE's are given in Table 2. The standard deviation of the residual additive error and the  $\varepsilon$ -shrinkage for the infusion and oral data are given in Table 5.

#### 310 4. Discussion

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DRT data analysis has previously proved to be an alternative approach to exposure-driven modelling when exposure data are sparse or absent [14, 22, 21, 24, 26, 35, 41, 64, 65]. The technique has been applied in studies of novel systems where the pharmacodynamic response behaves non-linearly, where time-lags are present, and when functional adaptation is manifested [24]. These examples demonstrate the potential of DRT modelling in characterizing mechanisms of action of complex pharmacological systems. The present study extends the utility of a non-linear biophase model, permitting the description of more complex absorption kinetics. The non-invasiveness of DRT analysis promotes its use when excessive sampling is prohibited (small animals, paedriatic populations) [60].

## 4.1. DRT modelling

DRT data analysis typically requires response-time series with higher resolution than traditional traditional exposure-driven studies. This is because kinetic information in response-time data are sought for the biophase turnover.

In contrast to exposure-driven pharmacodynamic modelling, the biophase kinetics and the pharmacodynamic properties of a DRT model must be estimated simultaneously. This may in some instances lead to difficulties in separating confounding factors originating from either the concentration-time or the response-time course or both. If, for example, drug absorption and disposition is highly non-linear this may confound the interpretation of nonlinear pharmacoynamics. Therefore, a priori knowledge about the mechanism(s) of action is necessary for construction of an adequate biophase model.

#### 4.2. Strategy when selecting the biophase model

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The structure of the biophase model is preferably derived through a series of steps where data from different administration routes are sequentially implemented and the biophase is structure refined if necessary. In this way, different properties, for example elimination rate and absorption rate, can be addressed separately.

In this study, the intravenous data were initially analysed in order to address the biophase disposition. Both a linear first-order and a Michaelis-Menten elimination model were successfully fitted to the data. The two models had approximately the same objective function values and fitted the data equally well when the function plots were inspected graphically. However, when the AIC was applied, the simpler model was preferred, and therefore selected. The similarity between the linear first-order and Michaelis-Menten elimination models was due to the high estimate of the Michaelis-Menten constant, in comparison to the biophase amounts, rendering an approximately linear elimination rate at all dose levels.

When the disposition model was set, oral data were included and the absorption process into the biophase was assessed. Both a first-order and nonlinear Michaelis-Menten absorption model were fitted to the data. The first-order absorption model failed to capture the full dynamic behaviour of the data in that it systematically over-predicted the response-time course for the highest oral dose (812 µmol kg<sup>-1</sup>). This problem was resolved by the Michaelis-Menten absorption model that also captured the absorption-rate limited elimination.

#### 4.3. The NiAc/FFA DRT model

The model captures the general trends of the populations and the Monte Carlo prediction intervals span most of the individuals.

The population fits in Fig. 4 indicate that the population medians differ slightly from the individual behaviours for the infusion of  $0.033\,\mu\mathrm{mol\,kg^{-1}\,min^{-1}}$  (Fig. 4a), which is predicted to be higher than the individual outcomes, and the oral dose of  $81.2\,\mu\mathrm{mol\,kg^{-1}}$  (Fig. 4i), which is predicted to be lower than the individual outcomes. This difference is believed to be an artefact of inter-occasional variability since these populations have lower (for the infusion of  $0.033\,\mu\mathrm{mol\,kg^{-1}\,min^{-1}}$ ), respectively higher (for the oral dose of  $81.2\,\mu\mathrm{mol\,kg^{-1}}$ ), baseline values than the estimated population baseline. A potential way to avoid this issue is to model the inter-occasional variations.

The eight moderator compartments were chosen to model the slow and fast action of insulin and other hormones. A more eloquent way would be to optimize the number of compartments as a system parameter or use another time-delay relation, such as the actual insulin concentration-time course. This is a matter for future model refinement.

The integral feedback control, moderator feedback, and the turnover of FFA are shown to act over different time-scales (Table 3). Turnover of FFA occurs within minutes, the feedback triggered by insulin and other hormones operates within 30 minutes, while the slow buildup of NiAc tolerance occurs within a

couple of hours.

The model predicts full system adaptation for long-term constant rate infusions with the therapeutic infusion rate of  $0.17\,\mu\mathrm{mol\,kg^{-1}\,min^{-1}}$  (Fig. 7). This illustrates the effect of the integral feedback control, which forces the response back to baseline over time. Homeostatic behaviour has been proven experimentally in studies of long-term NiAc provocation [45]. However, 90% of adaptation typically occurs within 24 h at therapeutic concentrations of NiAc. A better estimate for the adaptation  $K_i$  is expected when longitudinal data are generated and added to the analysis.

In general, there is high consistency between our derived system parameter estimates and the ones from exposure-driven analysis. The slight deviations are still within reasonable biological limits given the parameter uncertainty (Table 4). This comparison strengthens the use of DRT analysis as a complementary technique in studies where limited exposure data are available.

The proposed biophase model is *per se* a substantial simplification in comparison to the original multi-compartment plasma kinetics (exposure) model that has been applied by others (Iwaki et al. [34], Ahlström et al. [7] and Tapani et al. [59]). Therefore, dose predictions, impact of different dosing regimens, or assessment of safety margins will probably require an exposure-driven approach.

This study has demonstrated the utility of DRT modelling by developing biophase-driven pharmacodynamic models. The biophase structure was challenged by means of different rates, routes, and modes of administration, on top of the pharamcodynamic complexities.

We envision that DRT data analysis will have great significance on pharmacological responses (biomarkers) used in the future assessment of dynamics. DRT analysis has proven to be an acceptable alternative to exposure-driven PD modelling in situations where plasma concentrations are sparse or missing, or if extreme differences are seen for the initial and terminal disposition phases in plasma (such as with oligonucleotides, where rate and extent of exposure vary significantly between tissues [15, 31]).

## 4.4. Control theory

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In this study, techniques from systems and control theory were utilized to describe feedback mechanisms and systemic adaptation. By applying integral feedback control the system demonstrated full adaptation under constant long-term NiAc pressure (see Fig. 7). In fact, integral feedback control is a prerequisite for perfect adaptation in systems that experience constant disturbance [10, 56].

The control theory feature of the pharmacodynamic model provides a significant improvement in comparison to previously published NiAc/FFA models [7, 59], and will make the model better suited for chronic regimens.

Many biological systems, experiencing adaptation when put under external disturbance, have been successfully modelled by means of control theory techniques, including metabolic networks [30], synthetic biology [17], the osmoregulation in yeast [27, 42], and bacterial chemotaxis [12, 66]. El-Samad et al.

showed how integral feedback control could, for example, be derived from enzymatic relations when the goal is to address the control of plasma calcium levels [19]. Control theory techniques have been used sparsely within PK-PD modelling and mostly in dose control [52, 57, 61, 63, 62]. Control theory techniques have a clear potential in modelling intrinsic control and feedback systems.

#### 4.5. Inter-individual and intra-individual variability

When the model was fitted for each individual separately (i.e., without a mixed-effects approach) the parameter estimates of  $R_0$ , k,  $k_{out}$ ,  $k_{tol}$ , and  $K_i$ had large coefficients of variation, indicating that the data contained enough information to estimate the corresponding  $\eta$ 's of these parameters (i.e. the individual parameters) in a mixed-effects approach. However, no parametric model (e.g., normal or log-normal) was successfully matched to the distributions of the EBE's. Regardless, a log-normal distribution was chosen to model the EBE's spread due the positive range of the log-normal distribution, a generic feature expected in the parameters. Use of a log-normal model led to high levels of shrinkage in some of the EBE's. Whilst  $R_0$  and k had low  $\eta$ -shrinkages, indicating that the log-normal assumption on the parameter distributions was reasonable, the remaining three parameters  $(k_{\text{out}}, k_{\text{tol}}, \text{ and } K_i)$  had high  $\eta$ shrinkages of 40 - 60%, indicating that the log-normal distribution does not describe these parameters in a satisfactory way. Thus, one should be careful not to over-interpret the values of the EBE's. This includes EBE vs EBE plots or EBE vs covariate plots, which are not reliable under high levels of shrinkage. For that reason, analyses of these kinds are omitted in this study. However, the estimated random effects are still useful when describing the data and when extrapolating to, for example, other dosing regimens.

Both of the models used for the infusion and oral data gave reasonably low  $\varepsilon$ -shrinkages of less than 10% indicating that the models describe the data in a satisfactory manner without being over-fitted.

### 4.6. New numerical algorithms

The new numerical algorithms used rely on sensitivity equations to calculate the gradients in the optimization routine. This improves precision and accuracy extensively in comparison to finite difference approximations, increasing the chance of convergence in the parameter estimation for computer-intensive models [9].

#### 5. Conclusions

A DRT model was successfully fitted to all time courses available of the NiAcinduced changes in FFA in normal rats, showing the versatility of this approach. A nonlinear biophase model was used to describe saturable absorption. Using moderator compartments, and systems and control theory, we captured different feedback mechanisms. The systems and control theory techniques was successfully applied to describe complete system adaptation under constant long-term exposure to NiAc. This provides a significant improvement of the previously used NiAc/FFA models and will be suited in chronic regimens. Consistency in pharmacodynamic parameters between biophase- and kinetic-driven studies indicates potentially wider use of DRT data analysis. New numerical approaches were successfully applied to robustly and efficiently compute the gradients in the nonlinear mixed-effects framework.

DRT analysis is generally a poorly explored area that has great potential and could be considered more frequently in future pharmacological studies when drug exposure data are scarce or even lacking.

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## Appendix A

The following is an excerpt from the modelling code used, implemented in Mathematica. An executable version of this code, with corresponding data sets used for this study, is available from the authors upon request.

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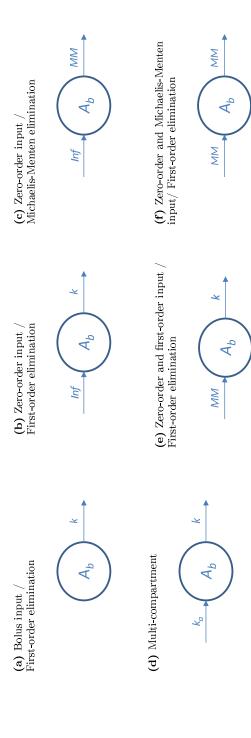


Figure 2: Examples drawn from a library biophase functions used here and in literature [21, 26, 64]. (a) bolus input and first-order elimination. (b) zero-order input and first-order elimination. (c) zero-order input and first-order elimination. (c) zero-order input and first-order elimination. (d) multi-compartment model. (e) zero-order elimination. and first-order input, and first-order elimination. (f) zero-order and Michaelis-Menten input, and first-order elimination.  $A_b$ , Inf, k, k, and MM represent, respectively, the biophase amount, the constant rate infusion input, the first-order elimination rate constant, the first-order absorption rate constant, and the Michaelis-Menten absorption/elimination process

**Table 1:** Evolution of the biophase model structure. Steps I - IV, description of the biophase function, the data used for the regression and the pair-wise accept/reject procedures when addressing the biophase disposition and absorption

Step	Model	Description	Data for regression
н	$A_{b}$	$\left\{ egin{aligned} { m Zero-order input} \ { m First-order elimination} \end{aligned}  ight.$	Intravenous
п	Inf Ab MM	$\left\{ egin{aligned} { m Zero-order input} \ { m Michaelis-Menten elimination} \end{aligned}  ight.$	Intravenous
	Pair-wise accept-reject I The zero-order input and first-	Pair-wise accept-reject procedure between the models in step I and step II.  The zero-order input and first-order elimination model was considered the better model.	and step II. the better model.
Ħ	$k_{a}$ $A_{b}$ $k_{a}$	$\left\{ egin{aligned} { m Zero-order input (IV^a)} \ { m First-order input (PO^b)} \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \$	Intravenous and oral
N	Inf $A_b$ $k$	$\begin{cases} \text{Zero-order input (IV}^{a}) \\ \text{Michaelis-Menten input (PO}^{b}) \\ \\ \text{First-order elimination} \end{cases}$	Intravenous and oral

The Michaelis-Menten input and first-order elimination model was considered the better model. Pair-wise accept-reject procedure between the models in step III and step IV.

 $<sup>^{</sup>m a}$ Intravenous

bOral

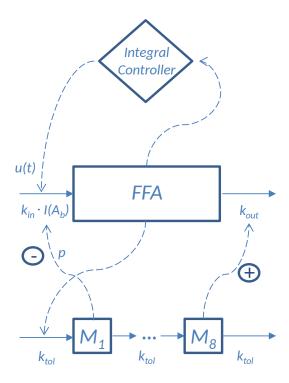


Figure 3: Schematic structure of the pharmacodynamics of the DRT feedback model. The pharmacodynamic model structure consists of a turnover equation coupled with a chain of moderator compartments, with slow and rapid feedback, as well as a slow integral control feedback. Here  $k_{\rm in}$  denotes the turnover rate of FFA,  $k_{\rm out}$  the fractional turnover rate of FFA,  $k_{\rm tol}$  the turnover rate of the moderators, p the amplification factor,  $I(A_{\rm b})$  the drugmechanism function, and  $M_1$  and  $M_8$  the first and last moderator, respectively. Solid lines represent fluxes whilst the dashed lines represent flow of information (i.e., how the different entities affect one another)

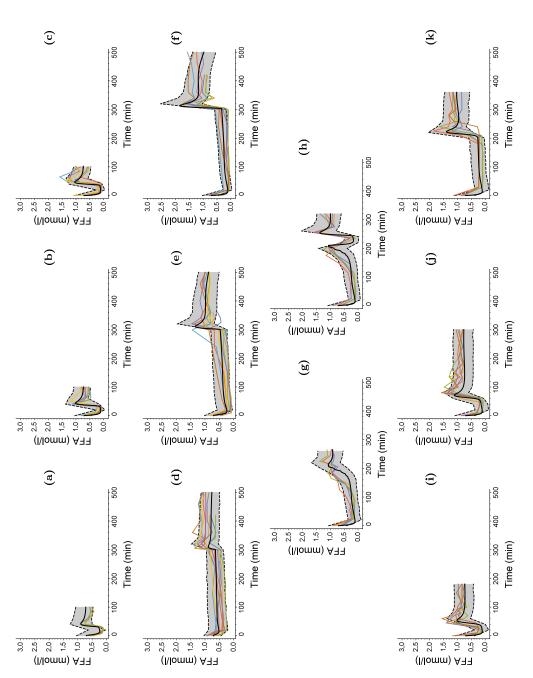
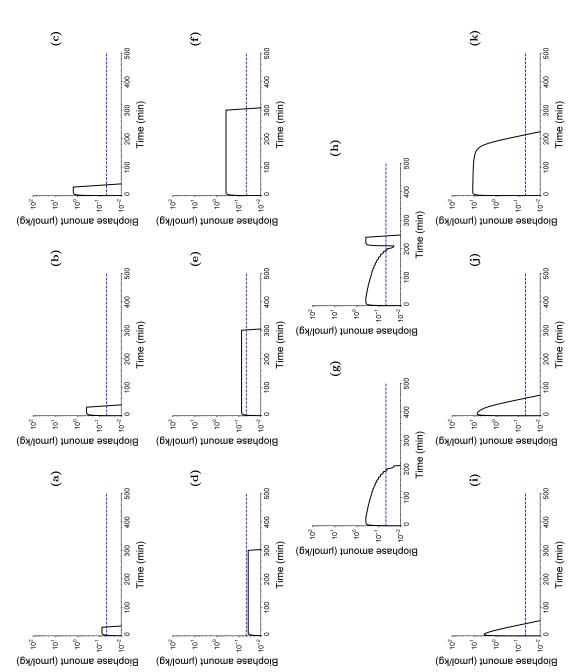


Figure 4: Population model fits to the FFA response levels, with 90% Monte Carlo prediction intervals. The black lines represent the estimated population median, the lower black dashed lines and the upper black dashed lines represent the 5%-quantile and the 95%-quantile of the Monte Carlo prediction interval, respectively. The coloured lines are the measured individual FFA response levels. (a-c) represent 30 min constant rate infusion of 0.033, 0.17, and 0.67 µmol kg<sup>-1</sup> min<sup>-1</sup>, respectively; (d-f) represent 300 min constant rate infusion of 0.017, 0.033, and 0.17 µmol kg<sup>-1</sup> min<sup>-1</sup>, respectively; (g) represents a 30 min constant rate infusion of 0.17 µmol kg<sup>-1</sup> min<sup>-1</sup> followed by a stepwise decrease in infusion rate to zero every 10 min for 180 min; and (h) represents a 30 min constant rate infusion of 0.17 µmol kg<sup>-1</sup> min<sup>-1</sup> followed by a stepwise decrease in infusion rate to zero every 10 min for 180 min followed by another 30 min constant rate infusion of 0.17 µmol kg<sup>-1</sup> min<sup>-1</sup>. (i-k) represent oral dosing of 24.4, 81.2, and 812 µmol kg<sup>-1</sup>, respectively



drug amount and the blue dashed lines represent the predicted  $ID_{50}$  estimate. (a-c) represent 30 min constant rate infusion of 0.033, 0.17, and 0.67 µmol kg<sup>-1</sup> min<sup>-1</sup>, respectively; (d-f) represent 300 min constant rate infusion of 0.017, 0.033, and 0.17 µmol kg<sup>-1</sup> min<sup>-1</sup>, respectively; (g) represents a 30 min constant rate infusion of 0.17 µmol kg<sup>-1</sup> min<sup>-1</sup> followed by a stepwise decrease in infusion rate to zero every 10 min for 180 min; (h) represents a 30 min constant rate infusion of 0.17 µmol kg<sup>-1</sup> min<sup>-1</sup> followed by a stepwise decrease in infusion rate to zero every 10 min for 180 min and followed by another 30 min constant rate infusion of 0.17 µmol kg<sup>-1</sup> min<sup>-1</sup>. (i-k) represent oral dosing of 24.4, 81.2, and 812 µmol kg<sup>-1</sup>, Figure 5: Population model predictions of the biophase drug amount on a semi-logarithmic scale. The black lines represent the estimated biophase respectively

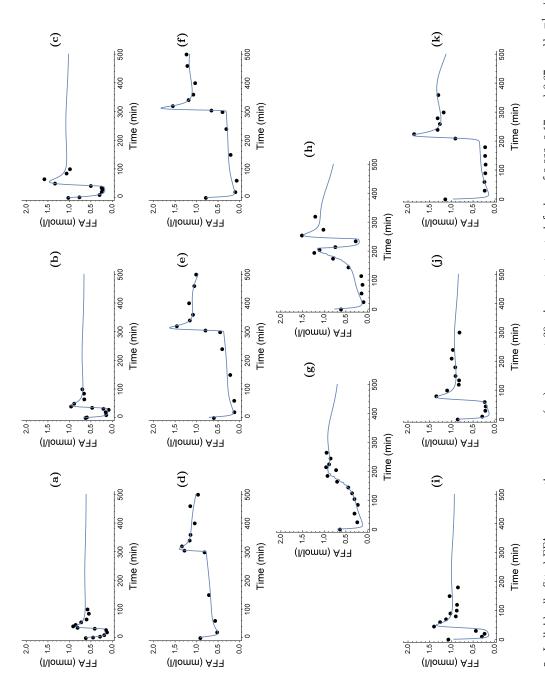


Figure 6: Individually fitted FFA response-time courses. (a-c) represent 30 min constant rate infusion of 0.033, 0.17, and 0.67 µmol kg<sup>-1</sup> min<sup>-1</sup>, respectively; (d-f) represent 300 min constant rate infusion of 0.017, 0.033, and 0.17 µmol kg<sup>-1</sup> min<sup>-1</sup>, respectively; (g) represents a 30 min constant rate infusion of 0.17 µmol kg<sup>-1</sup> min<sup>-1</sup> followed by a stepwise decrease in infusion rate to zero every 10 min for 180 min; (h) represents a 30-min constant rate infusion of 0.17 µmol kg<sup>-1</sup> min<sup>-1</sup> followed by a stepwise decrease in infusion rate to zero every 10 min for 180 min and followed by another 30 min constant rate infusion of 0.17 µmol kg<sup>-1</sup> min<sup>-1</sup> and (i-k) represent oral dosing of 24.4, 81.2, and 812 µmol kg<sup>-1</sup>, respectively

**Table 2:** DRT model parameter estimates and inter-individual variations, expressed in CV%, with corresponding relative standard errors (RSE%), and  $\eta$ -shrinkages

Parameter	Definition	Estimate	ΛΠ	η-shrinkage
$V_{\text{max,g}} \text{ (µmolkg}^{-1} \text{min}^{-1}\text{)}$	Max. elimination rate from gut	5.37(0.97)	1	ı
$K_{ m m,g}~({ m umolkg^{-1}})$	Amount in gut at half $V_{ m max,g}$	37.1(3.4)	ı	I
$k \; (\widetilde{\min}^{-1})$	Biophase elimination rate	0.446(5.8)	45.1(23)	21%
$R_0 \; (\mathrm{mmol}  \mathrm{l}^{-1})$	Baseline FFA conc.	0.705(2.3)	21.1(37)	4.2%
$k_{ m out}~({ m min}^{-1})$	Fractional turnover rate	0.306(8.1)	42.4(47)	46%
$k_{ m tol}~({ m min}^{-1})$	Turnover rate of moderator	0.0242(5.2)	24.4(98)	52%
$K_{ m i}~({ m min}^{-1})$	Adaptation rate	0.00174(25)	90.6(23)	28%
d	Amplification factor	0.819(4.7)	ı	Î
$I_{ m max}$	Efficacy	0.881(2.8)	ı	I
$ID_{50} \; ({ m \mu mol  kg^{-1}})$	Potency	0.0456(6.8)	1	I
~	Hill exponent	2.96(8.6)	1	I

Table 3: Estimated system rate constants and their corresponding half-lives (in minutes) with 90% non-parametric bootstrap prediction intervals

Parameter	Estimate	Half-life	$90\% \text{ PI}^a$
$k_{\rm out} \ ({\rm min}^{-1})$	0.31	2.3	[1.3, 4.0]
$k_{\rm tol} \ (\rm min^{-1})$	0.024	$^{29}$	[15, 51]
$K_{\rm i}~({\rm min}^{-1})$	0.0017	400	[210, 710]

 $<sup>^</sup>a90\%$  non-parametric bootstrap prediction interval

**Table 4:** Comparison between the dynamic parameter estimates from the DRT study and an exposure-driven study. The parameter estimates are given with corresponding relative standard errors (RSE%)

Parameter	DRT analysis	Exposure-response anal.
$k_{\rm out} \ ({\rm min}^{-1})$	0.306(8.1)	0.244(7.3)
$k_{\rm tol} \ (\rm min^{-1})$	0.0242(5.2)	0.0222(2.7)
$K_{\rm i}~({\rm min}^{-1})$	0.00174(25)	0.00160(18)
p	0.819(4.7)	0.859(3.7)
$I_{ m max}$	0.881(2.8)	0.907(0.63)
$\gamma$	2.96(8.6)	2.36(9.2)

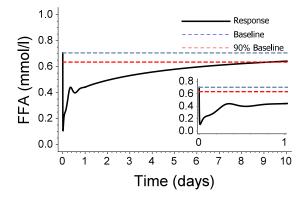


Figure 7: The long-term model-predicted effect of NiAc provocation on FFA level in normal rats with an infusion rate of  $0.17 \, \mu \text{mol kg}^{-1} \, \text{min}^{-1}$  (aiming at a therapeutic NiAc concentration of  $1 \, \mu \text{mol}$  [4]) during 10 days. The inserted figure shows in more detail the dynamics during the first day of NiAc infusion

Table 5: Model residual additive errors with corresponding relative standard errors (RSE%) and  $\varepsilon$ -shrinkage for infusion and oral data, respectively

Data	Residual add. error $\sigma$	$\varepsilon ext{-shrinkage}$
Infusion	0.0982(14)	9.5%
Oral	0.149(5.0)	7.7%

```
Construct a data list of data from all models. In this case, with only one administration route, the list
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             \{ SList, sStartValue \}, \{ randomParams, \Omega, \omega StartValue \}, t, fullParameterList ];
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    parameterStartValue = \{\{aVmax, 5\}, \{aKm, 30\}, \{\theta1, 2\}, \{kb, 0.3\}, \{Ki, 0.001\},
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      \{orallc\} /. Thread[absInput \rightarrow absInputFunctions], out\} /. randomEffects;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           wstartValue = \{\{w11, 0.1\}, \{w22, 0.1\}, \{w33, 0.1\}, \{w44, 0.1\}, \{w55, 0.1\}\};
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   {Join[prepDataOralDose24, prepDataOralDose81, prepDataOralDose812]};
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                [ID50, 0.05], {kout, 0.30], {R0, 0.70}, {\forallet}, {\forallet}, {\forallet}, {\forallet});
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         FitPopulationModel[data, models, listOfInputs, parameterStartValue,
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   prepDataDose5Time30, prepDataDose20Time30, prepDataDose5Time300,
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               infData = {Join[prepDataDoseOTime0,prepDataDose1Time30,
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                {0, 0, w33, 0, 0}, {0, 0, w44, 0}, {0, 0, 0, w55}};
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      prepDataDose10Time300, prepDataDose51Time300]};
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   stepData = {Join[prepDataDose20, prepDataDose25]};
                                                                                                                                                                                                                                                                                                                                                                                              model2 = {{stepSys}, {ic}, out} /. randomEffects;
                                                                                                                                                                                                                                                                                          model1 = {{infSys}, {ic}, out} /. randomEffects;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               sStartValue = {{s1, 0.1}, {s2, 0.1}, {s3, 0.1}};
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   fullParameterList = Join[params, {s1, s2, s3}];
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        Define the S matrix for all models (measurment noise)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                data = Join[infData, stepData, oralData];
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            Define all non yet defined constants of the system
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      Construct a parameter list with all the parameters
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    \mathbf{L} = \big\{ \{\omega 11, \ 0, \ 0, \ 0, \ 0\}, \ \{0, \ \omega 22, \ 0, \ 0, \ 0\} \big\},
                                                                                                                                             Setting up models consisting of {sys}, {ic}, out
                randomParams = \{\eta1, \eta2, \eta3, \eta4, \eta5\};
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  models = {model1, model2, model3};
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      Define Omega (interindividual variation)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     {pExpValues, pValues, history} =
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  listOfInputs = {DOSE, RATE};
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  only consains a single model.
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                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                Estimation of parameters
                                                                                                                                                                                                                                                                                                                                                                                                                                                                         model3 = {{oralSys},
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           \Omega = L.Transpose[L];
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              S1 = \{\{s1\}\};
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         S2 = {{s2}};
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     S3 = {{s3}};
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   oralSys = oralSys /. Thread[bioInput \rightarrow bioInputFunctions[[3]]] /. fixedParamRules;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                Define random variables (i.e. multiplicative random noises to certain parameters, here ID50, kout,
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 ic = \{Ab[0], R[0], M1[0], M2[0], M3[0], M4[0], M5[0], M6[0], M7[0], M8[0], Y[0]\} = \{Ab[0], R[0], R[0
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               stepSys = sys /. Thread[bioInput \rightarrow bioInputFunctions[[2]]] /. fixedParamRules;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            [nfSys = sys /. Thread[bioInput \rightarrow bioInputFunctions[[1]]] /. fixedParamRules;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    oralic = {Aa[0], Ab[0], R[0], M1[0], M2[0], M3[0], M4[0], M5[0], M6[0], M7[0],
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          bioInputFunctions = {RATE * UnitStep[DOSE / RATE - t], RATE * UnitStep[30 - t] +
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             \texttt{Piecewise}\left[\left.\left\{\left\{\text{RATE}-\text{Ceiling}\left[\left(\text{t}-30\right)\middle/10\right]*\text{RATE}\middle/19,\text{ t}>30\,\text{&&t}<210\right\}\right\}\right]+\right.
Specify fixed parameter rules and random effects (transform Imax to keep it bounded)
                                                                                                                                                                                                                                                                                                                                            \mathtt{R0} \rightarrow \left(\mathtt{R0} \ast \mathtt{Exp}[\eta 3]\right), \ \mathtt{kout} \rightarrow \left(\mathtt{kout} \ast \mathtt{Exp}[\eta 4]\right), \ \mathtt{ktol} \rightarrow \left(\mathtt{ktol} \ast \mathtt{Exp}[\eta 5]\right)\right\};
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       Piecewise [{{RATE * UnitStep[210 + (DOSE - 20) / RATE - t], t > 210}}],
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        ktol (M3[t] - M4[t]), ktol (M4[t] - M5[t]), ktol (M5[t] - M6[t]),
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            ktol (R[t] - Ml[t]), ktol (Ml[t] - M2[t]), ktol (M2[t] - M3[t]),
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  (1 - \text{Imax} * \text{Ab[t]}^{\wedge} / (\text{ID50}^{\wedge} + \text{Ab[t]}^{\wedge})) * (\text{R0}/\text{M1[t]})^{\wedge} p
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             (1 - \text{Imax} * \text{Ab[t]}^{\wedge} / (\text{ID50}^{\wedge} + \text{Ab[t]}^{\wedge})) * (\text{R0}/\text{M1[t]})^{\wedge} p
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  M3'[t], M4'[t], M5'[t], M6'[t], M7'[t], M8'[t], y'[t]} =
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 M3'[t], M4'[t], M5'[t], M6'[t], M7'[t], M8'[t], Y'[t]} ==
                                                                                                                                             fixedParamRules = \{ kin \rightarrow R0 * kout, Imax \rightarrow 1 / (1 + Exp[-\theta1]) \};
                                                                                                                                                                                                                                                 randomEffects = \{kb \rightarrow (kb * Exp[\eta 1]), Ki \rightarrow (Ki * Exp[\eta 2]),
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      -aVmax * Aa[t] / (aKm + Aa[t]), bioInput - kb * Ab[t],
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      oralSys = {Aa'[t], Ab'[t], R'[t], M1'[t], M2'[t],
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              kout*R[t]*(M8[t]/R0), ktol(R[t]-M1[t])
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          Define system, initial conditions and measured variables
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         ktol (M1[t]-M2[t]), ktol (M2[t]-M3[t]),
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              ktol (M3[t]-M4[t]), ktol (M4[t]-M5[t]),
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            ktol (M6[t]-M7[t]), ktol (M7[t]-M8[t]),
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               {bioInput - kb * Ab[t], (1 + Ki * y[t]) * kin *
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         ktol (M5[t]-M6[t]), ktol (M6[t]-M7[t]),
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     {0, R0, R0, R0, R0, R0, R0, R0, R0, 0};
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     ktol (M7[t] - M8[t]), 1 - R[t] / R0};
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               sys = {Ab'[t], R'[t], M1'[t], M2'[t],
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         absInputFunctions = {RATE * DOSE};
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              Aa[t] * aVmax / (aKm + Aa[t]) };
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         kout * R[t] * (M8[t] / R0),
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 (1+Ki *y[t]) *kin *
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                1-R[t]/R0};
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              Specify systems
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            R0 and Ki)
```

out = <u>R</u>